

Space Science Mission DATA

How to design a Space Science Mission

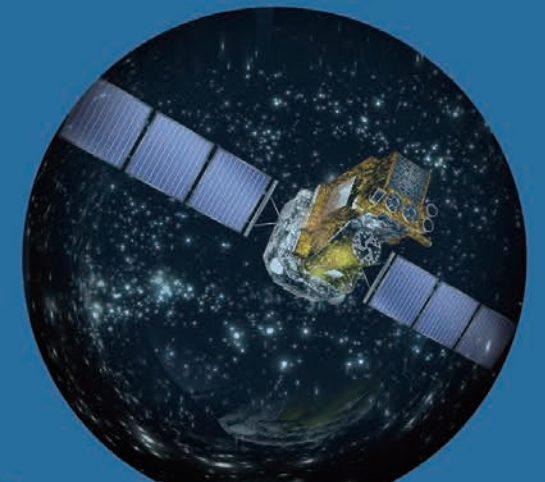
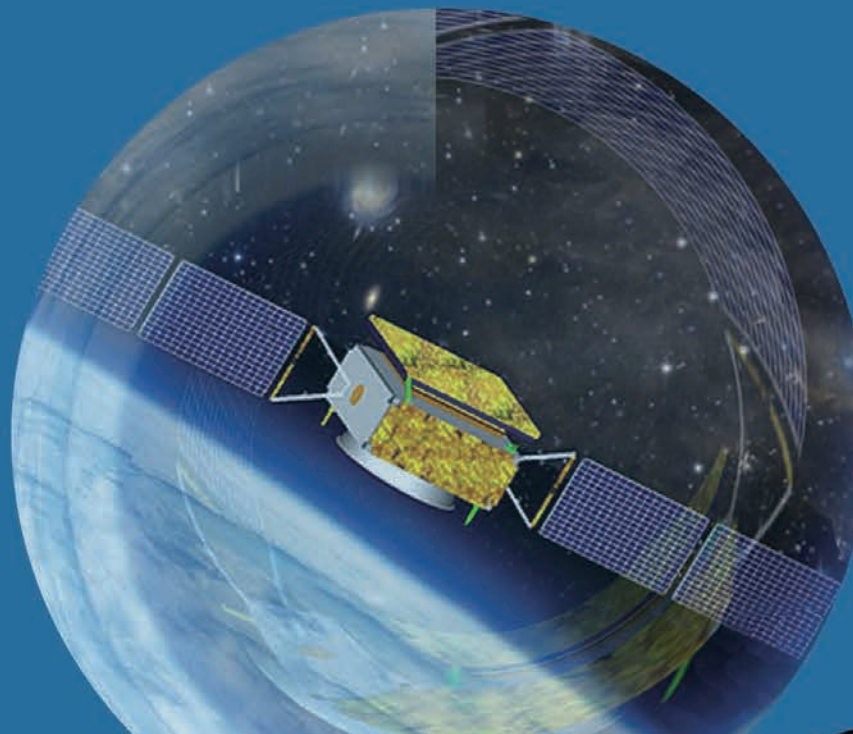
October 17 - 26, 2016

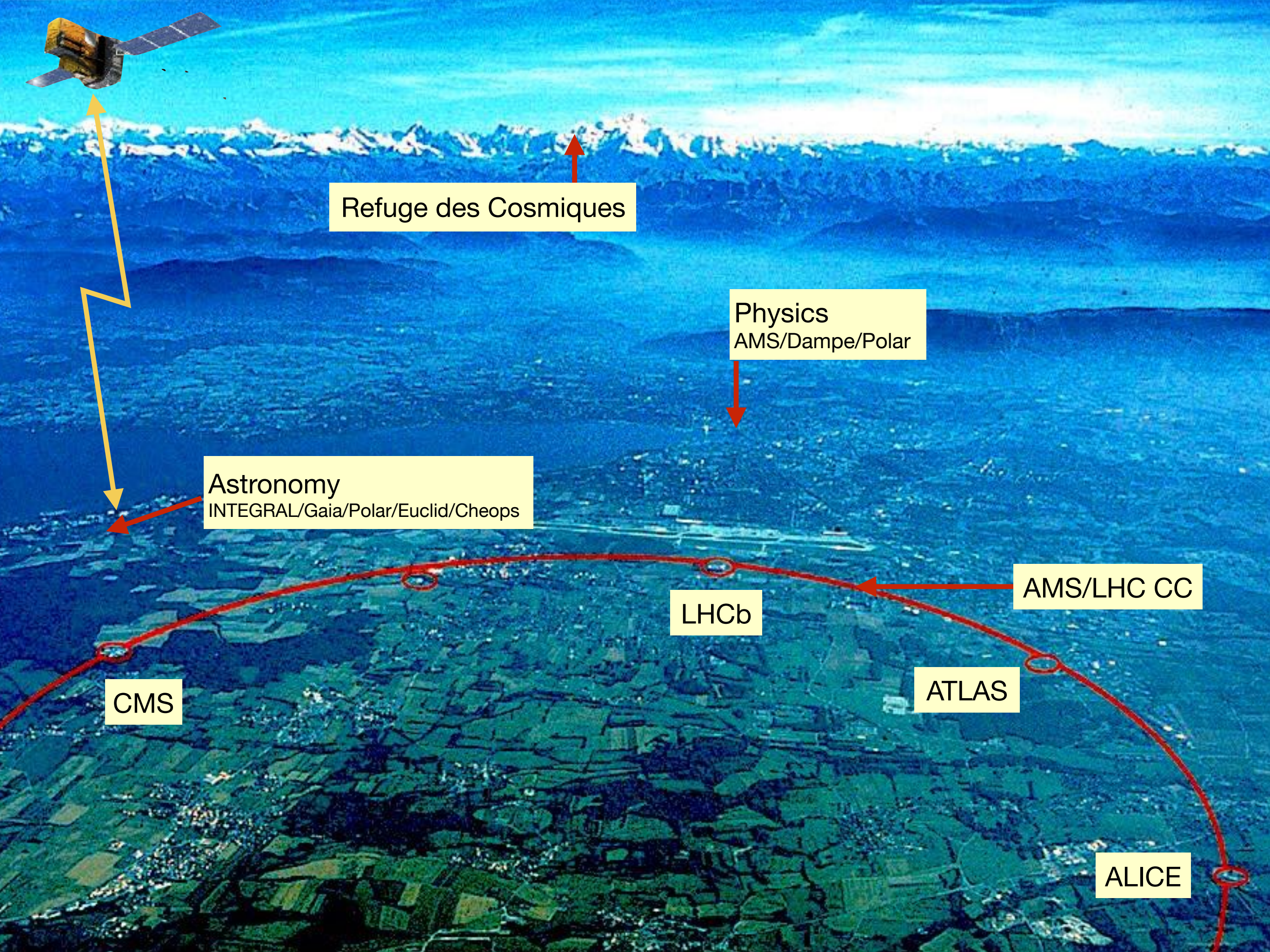
Si Racha, Chon Buri, Thailand

www.apsco.int/APSCO_ISSSI-BJ_SS/

TOPICS

- Scientific objectives
- Payload design
- Orbital constraints
- Spacecraft AOCS
- Spacecraft design and optimization
- Operations ground segment
- Scientific management
- Project management
- Micro-satellite launching and operation
- Cubesat mission design and integration
- Designing of space science experiment for Space Station





Refuge des Cosmiques

Physics
AMS/Dampe/Polar

Astronomy
INTEGRAL/Gaia/Polar/Euclid/Cheops

AMS/LHC CC

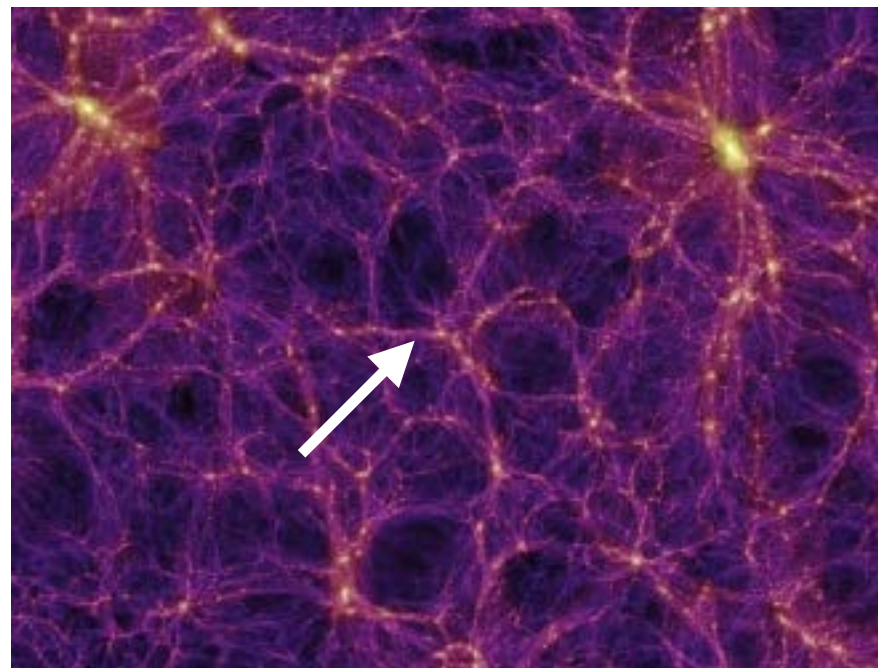
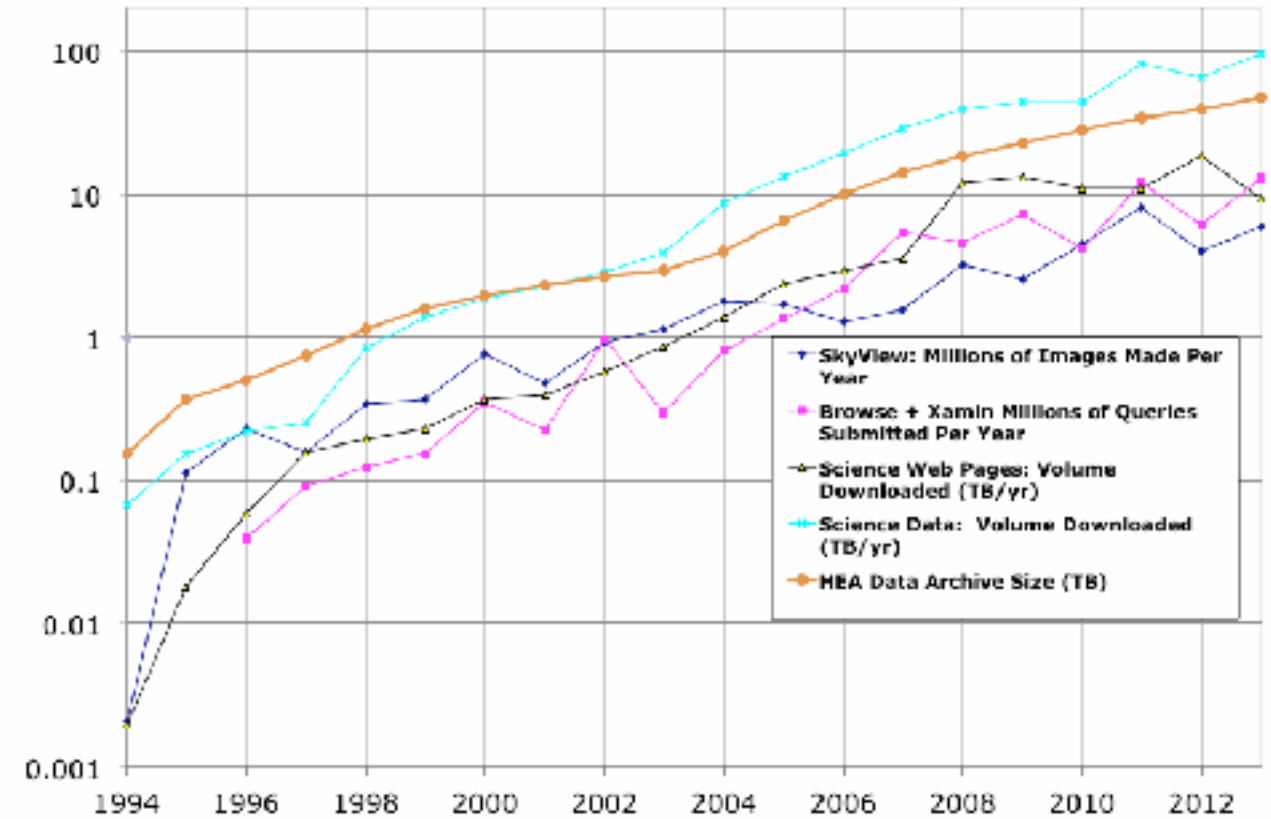
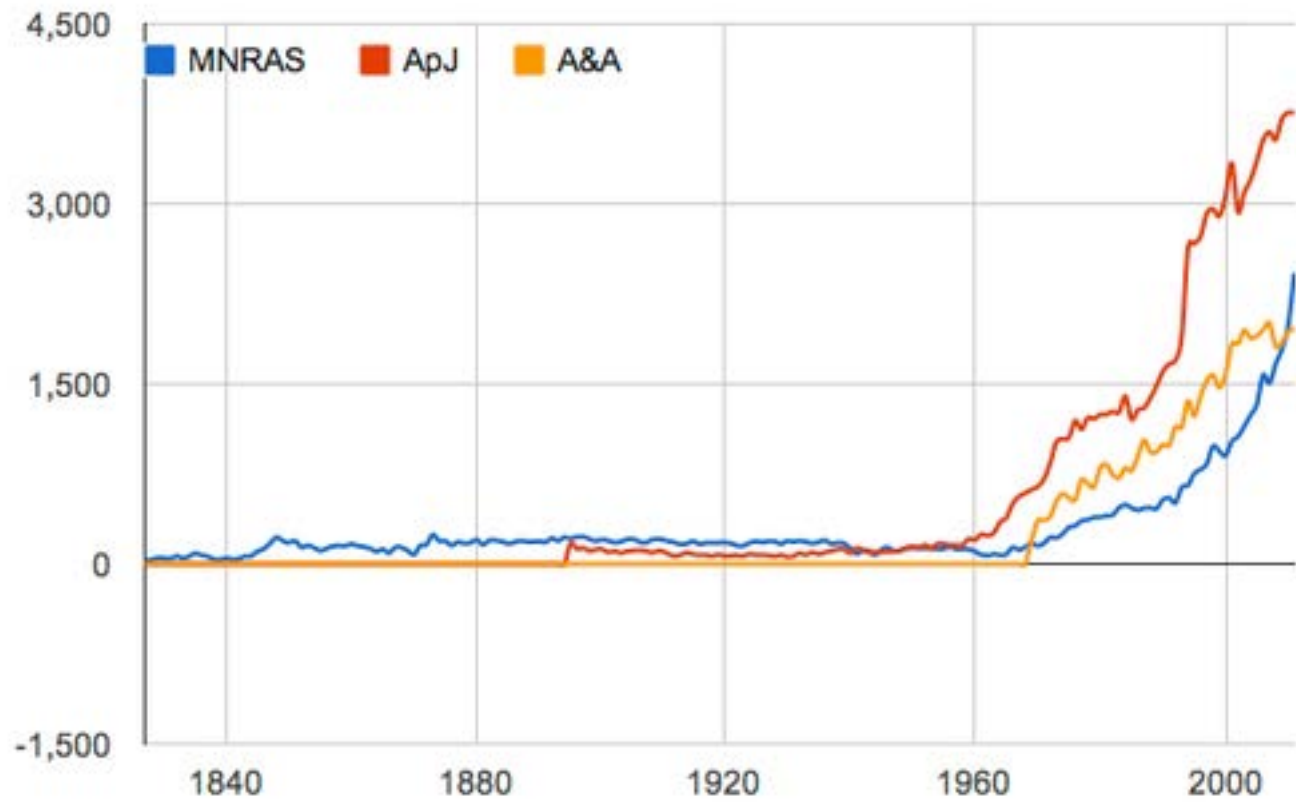
LHCb

CMS

ATLAS

ALICE

Astronomy vs Space Science vs Data



Space Science Mission DATA

Science and Drivers

Science Mission Elements

Data Handling

Development Management

Data is the Legacy

Light is Emitted by Particles

10^{25} protons @ 200 km/h $\sim 10^{12}$ GeV

Energy

10^{12} GeV

10^3 GeV

1 GeV



Cosmic rays

1 $(10\text{km})^{-2} \text{y}^{-1}$

1 $\text{m}^{-2} \text{min}^{-1}$

10'000 $\text{m}^{-2} \text{sec}^{-1}$

Photons

1 $\text{earth}^{-1} \text{y}^{-1}$

10 $\text{m}^{-2} \text{y}^{-1}$

1 $\text{m}^{-2} \text{sec}^{-1}$

ground

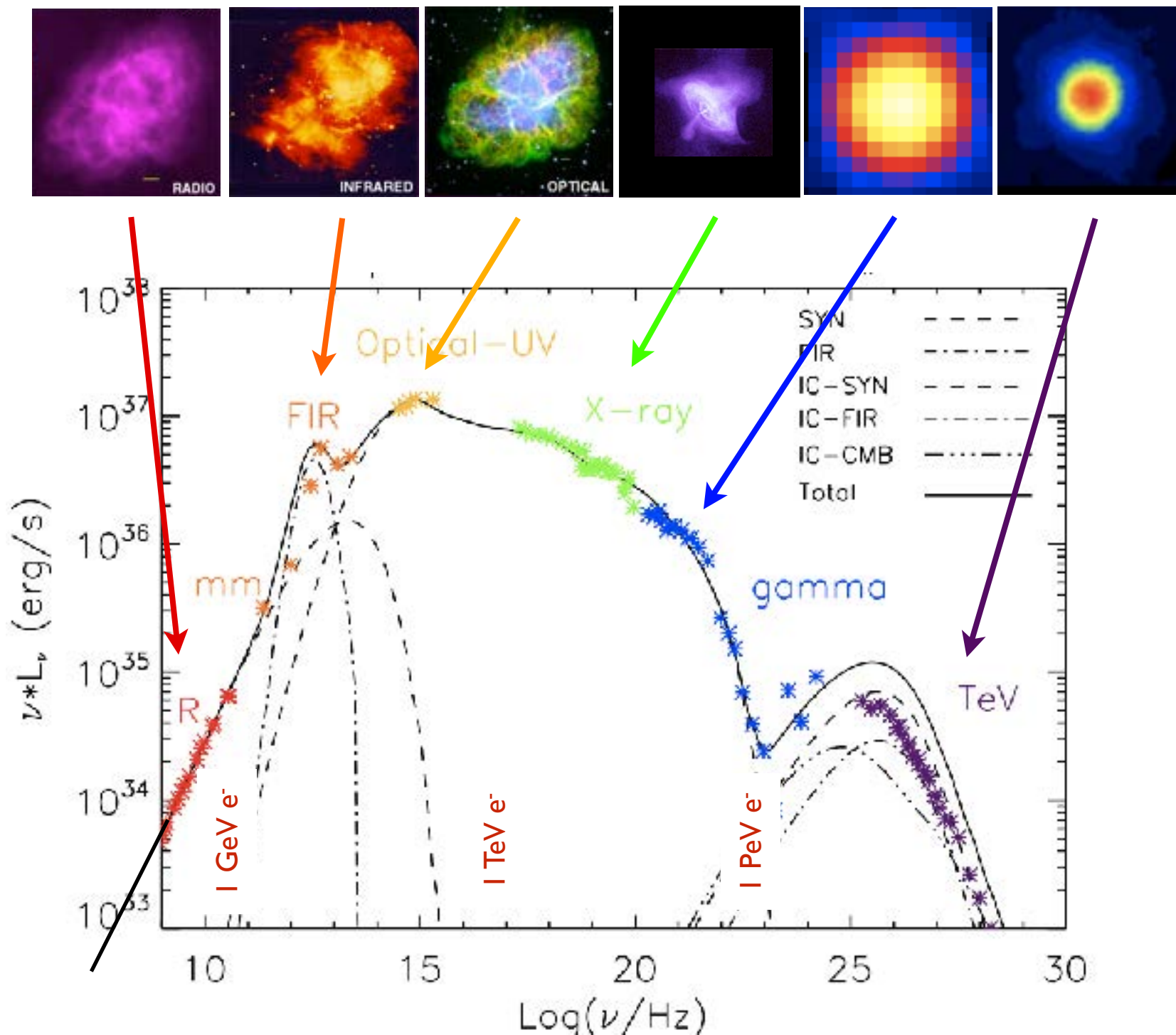
space

- Strong gravitational field
- Strong magnetic field
- Diffuse Shock Acceleration
- Radioactivity/Annihilation

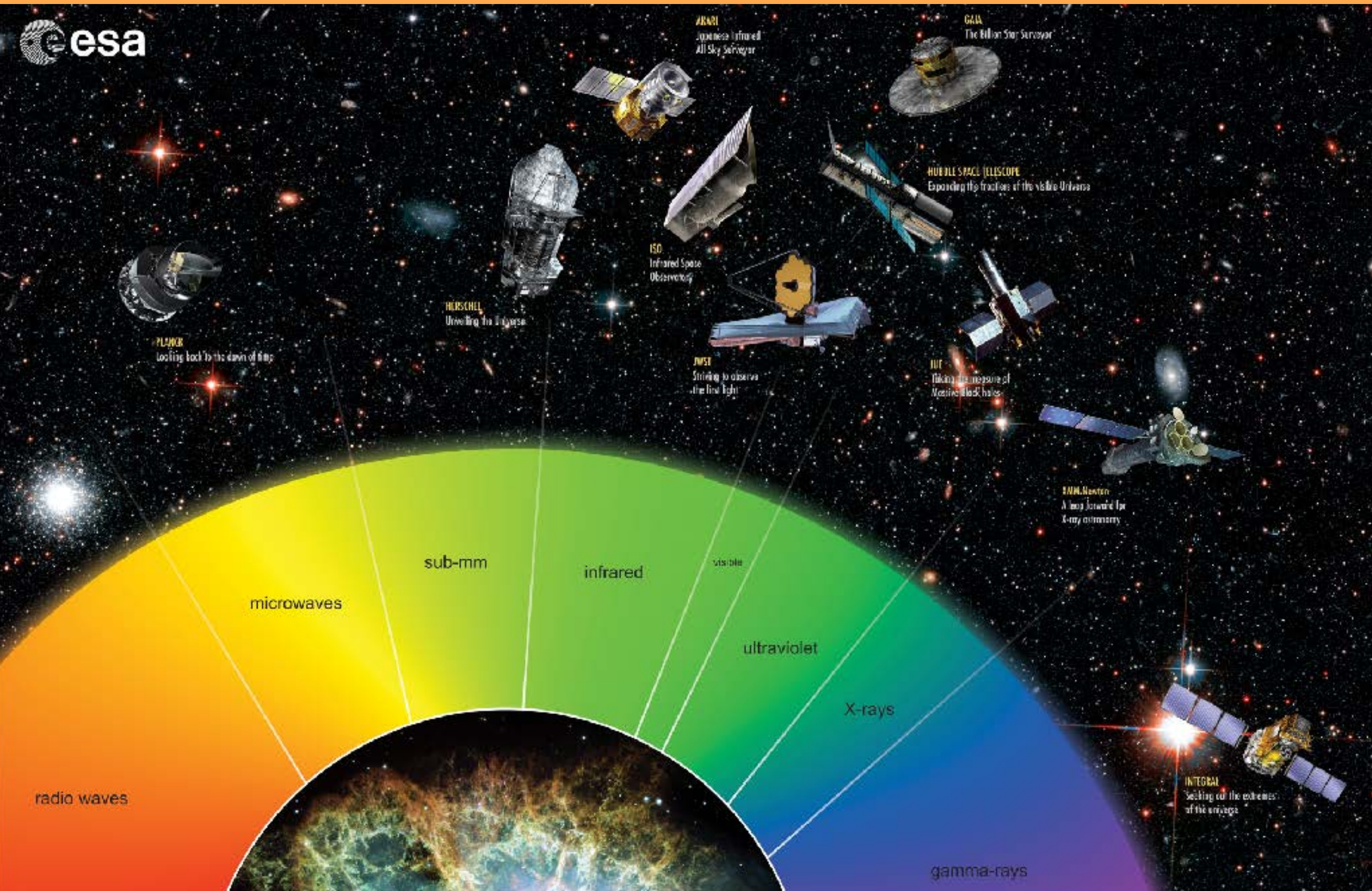
Multi-Wavelength Astronomy

Crab Nebula

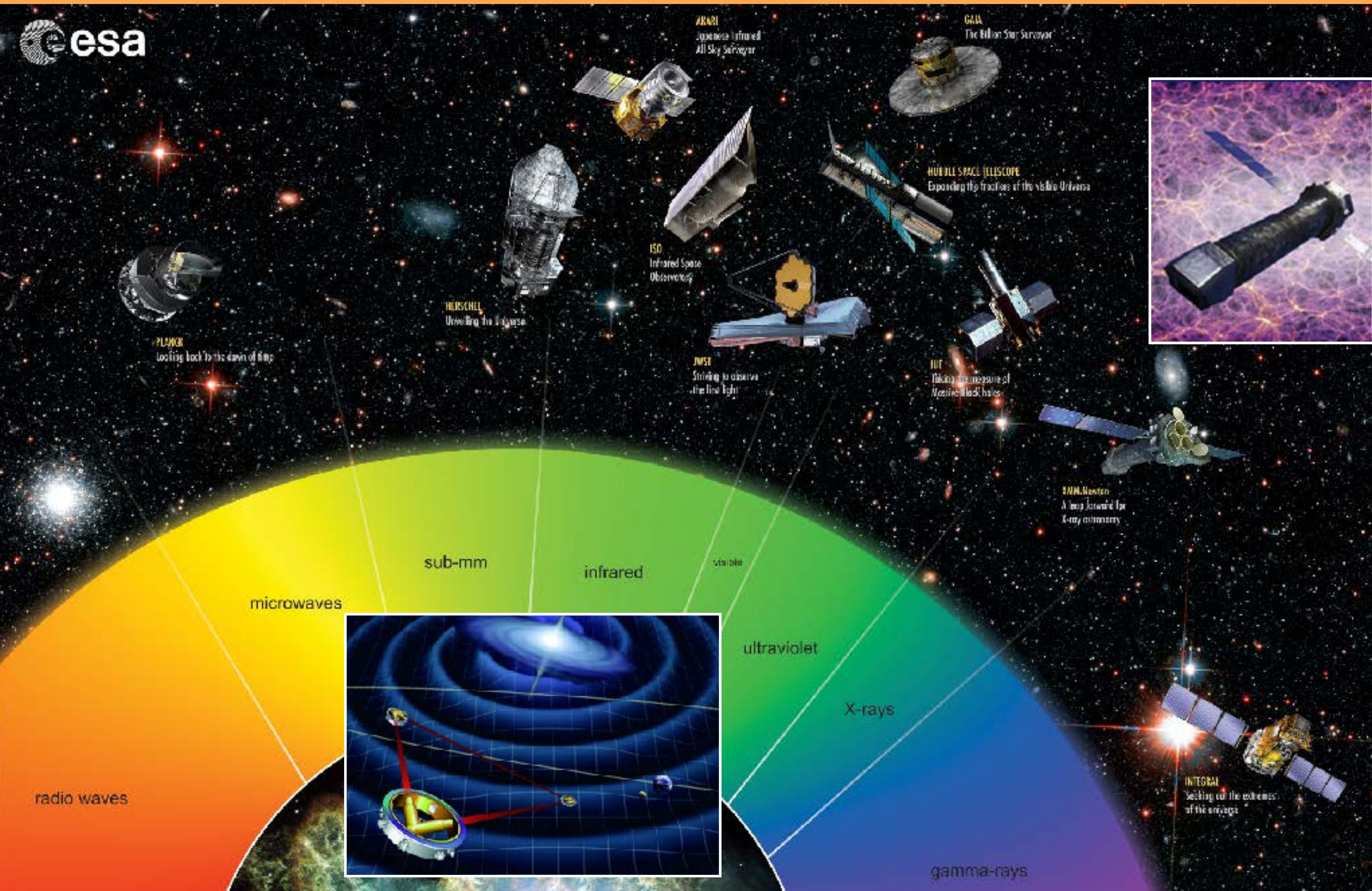
Most energetic (PeV= 10^{15} eV) electrons ever detected in the Universe



Space Science Missions Across the Electromagnetic Spectrum

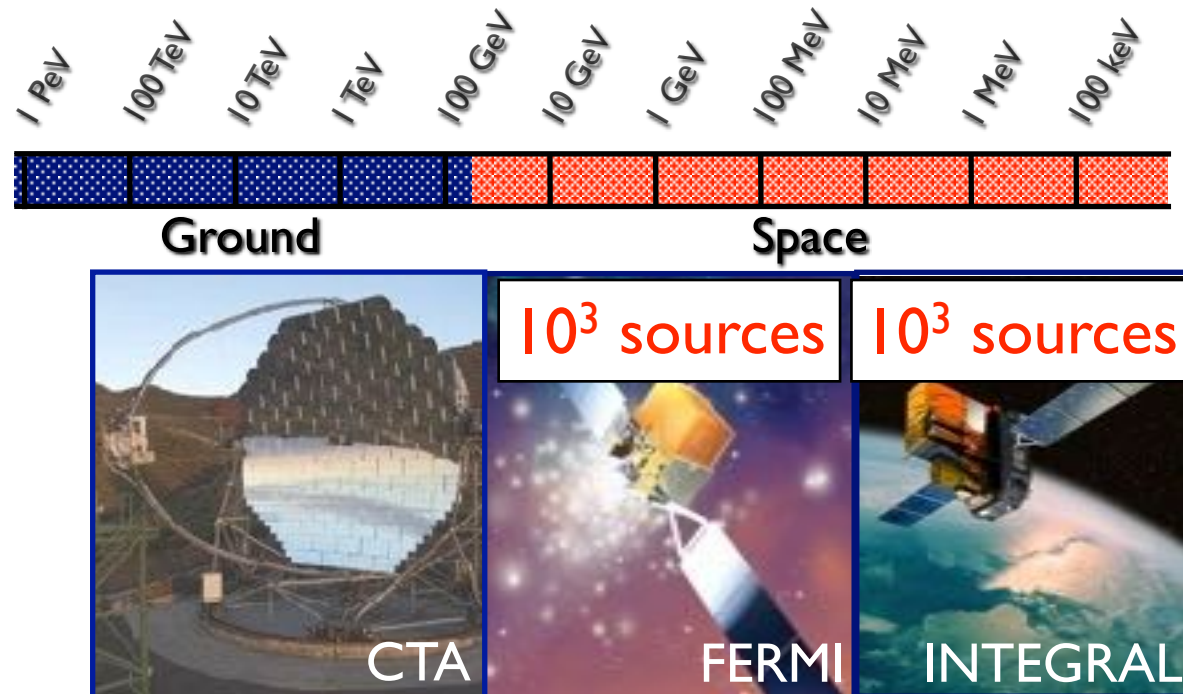


Space Science Missions Across the Electromagnetic Spectrum

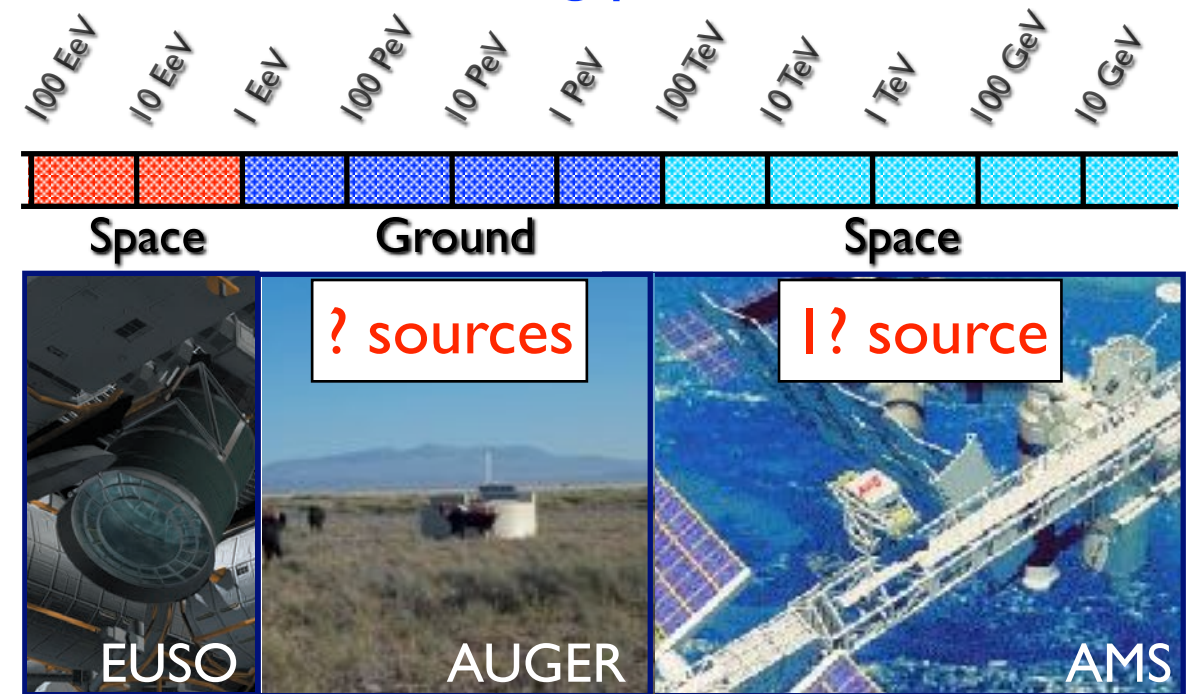


Astrophysics of the 21th Century

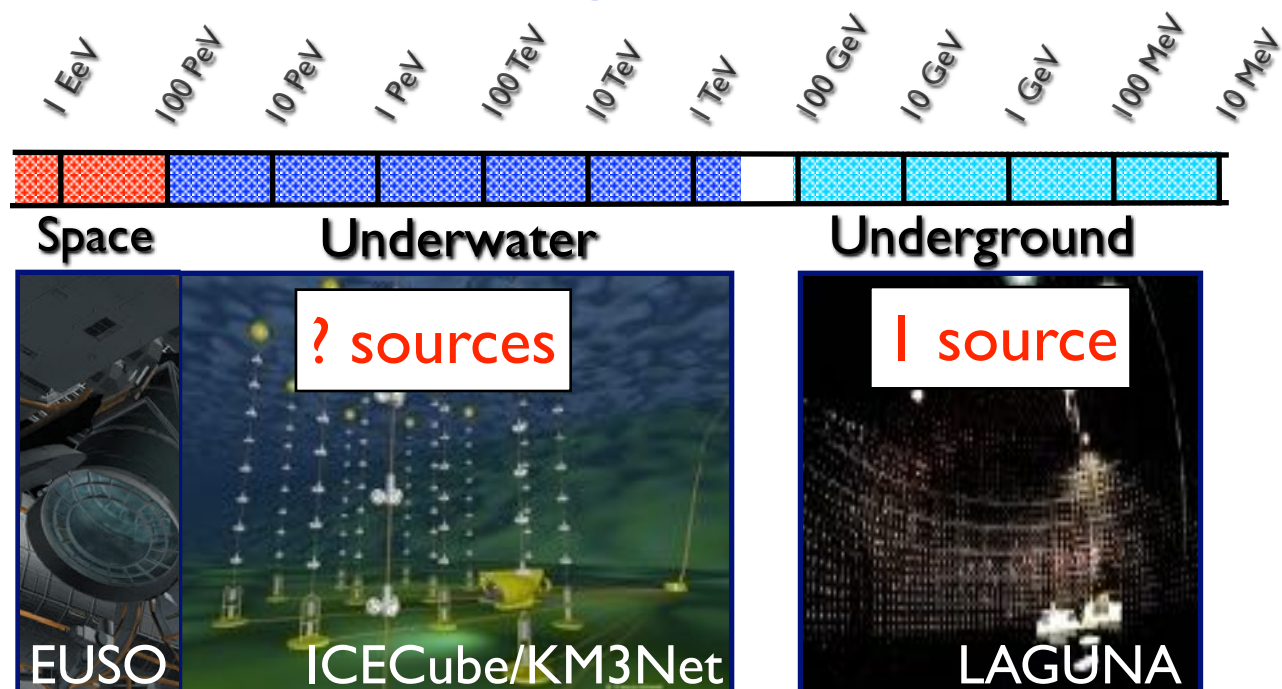
Detecting photons



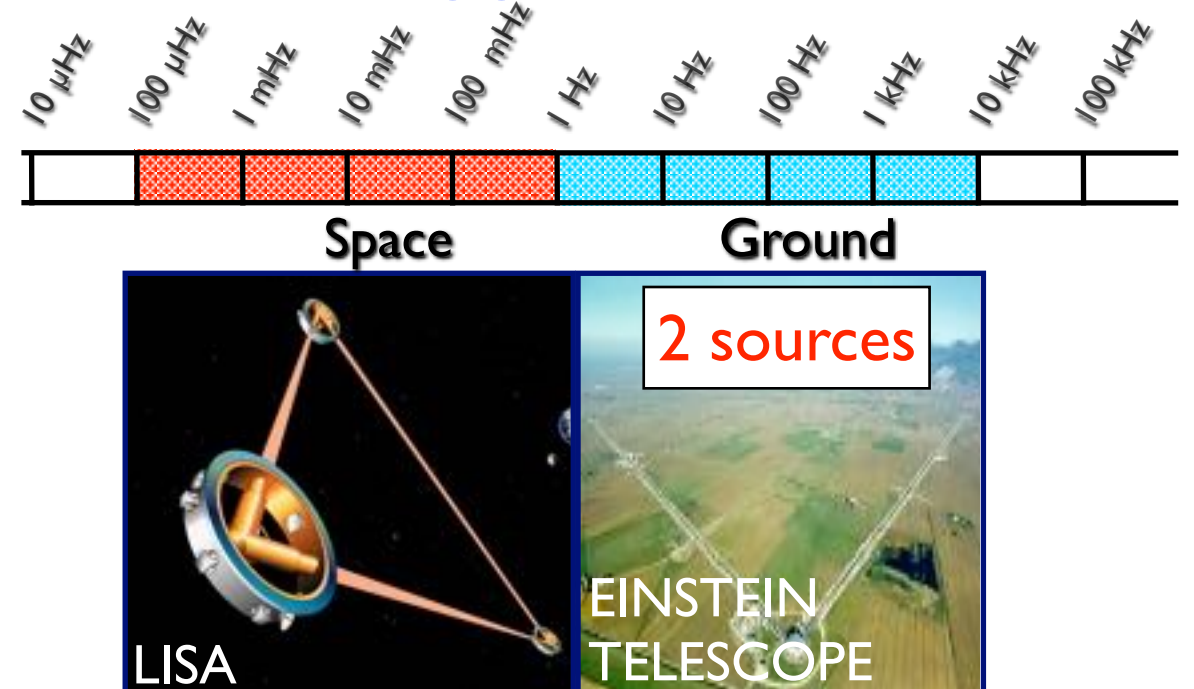
Detecting particles



Detecting neutrinos

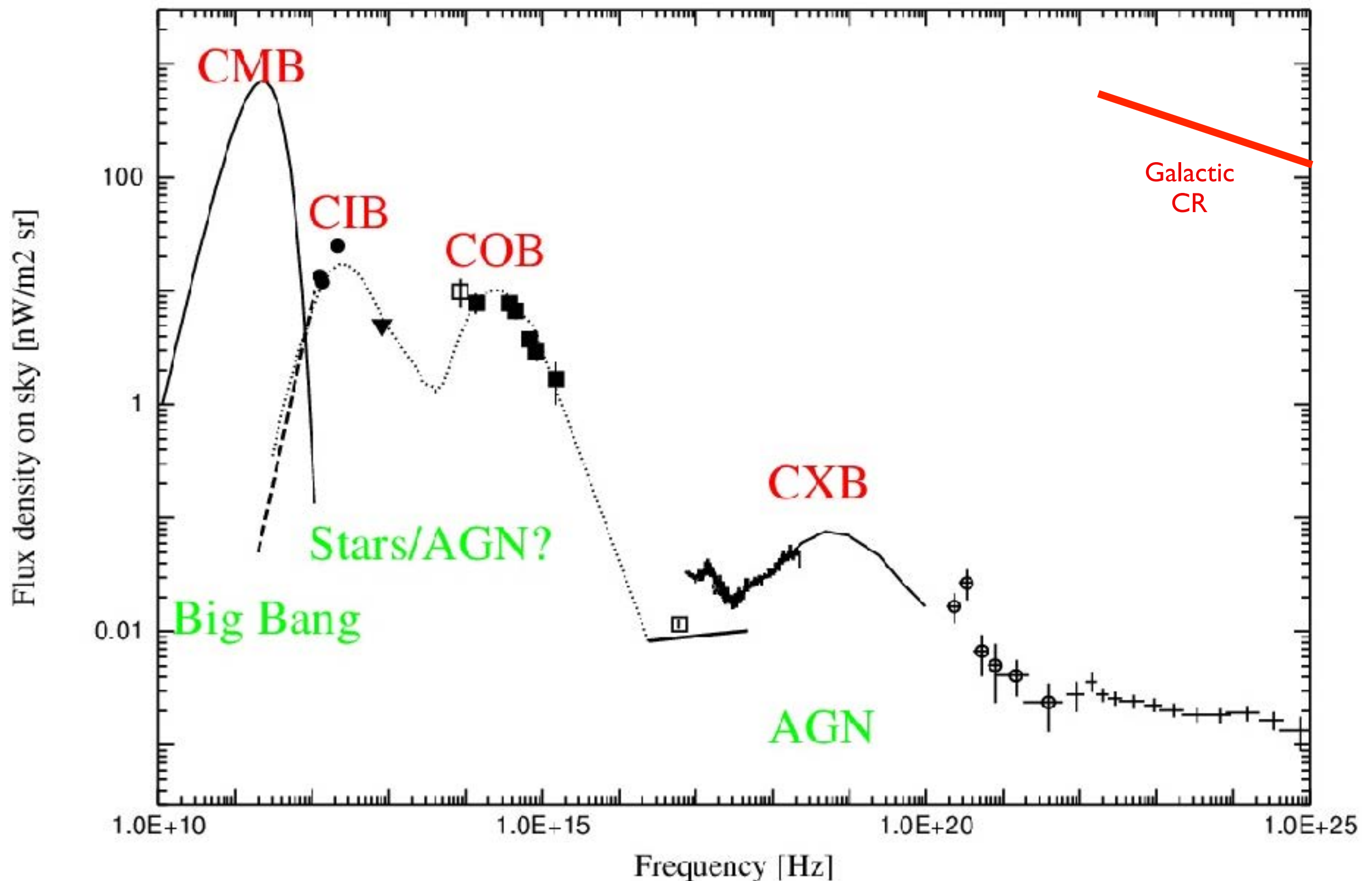


Detecting gravitational waves



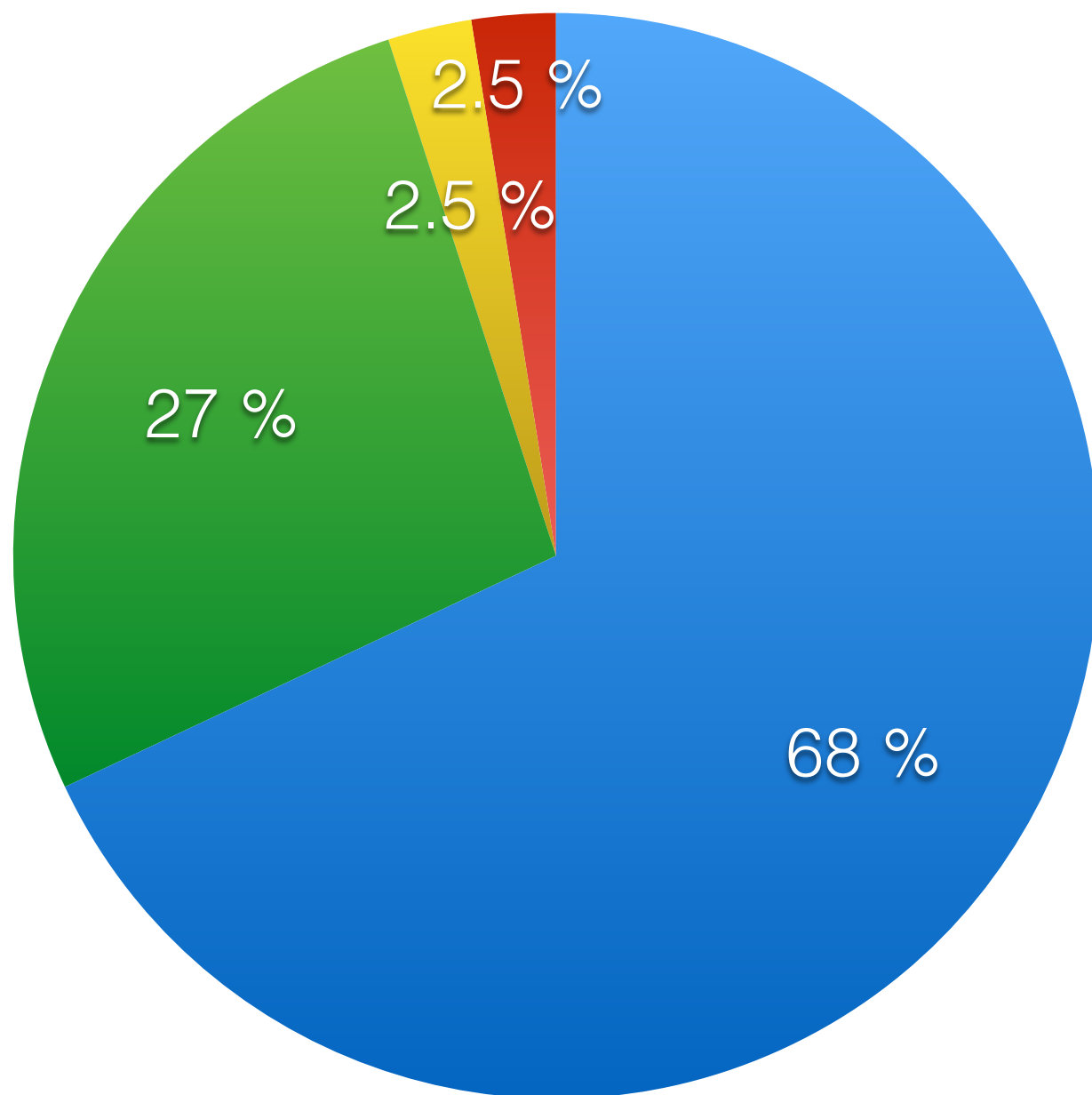
Radiation in the Universe

The Cosmic Energy Density Spectrum

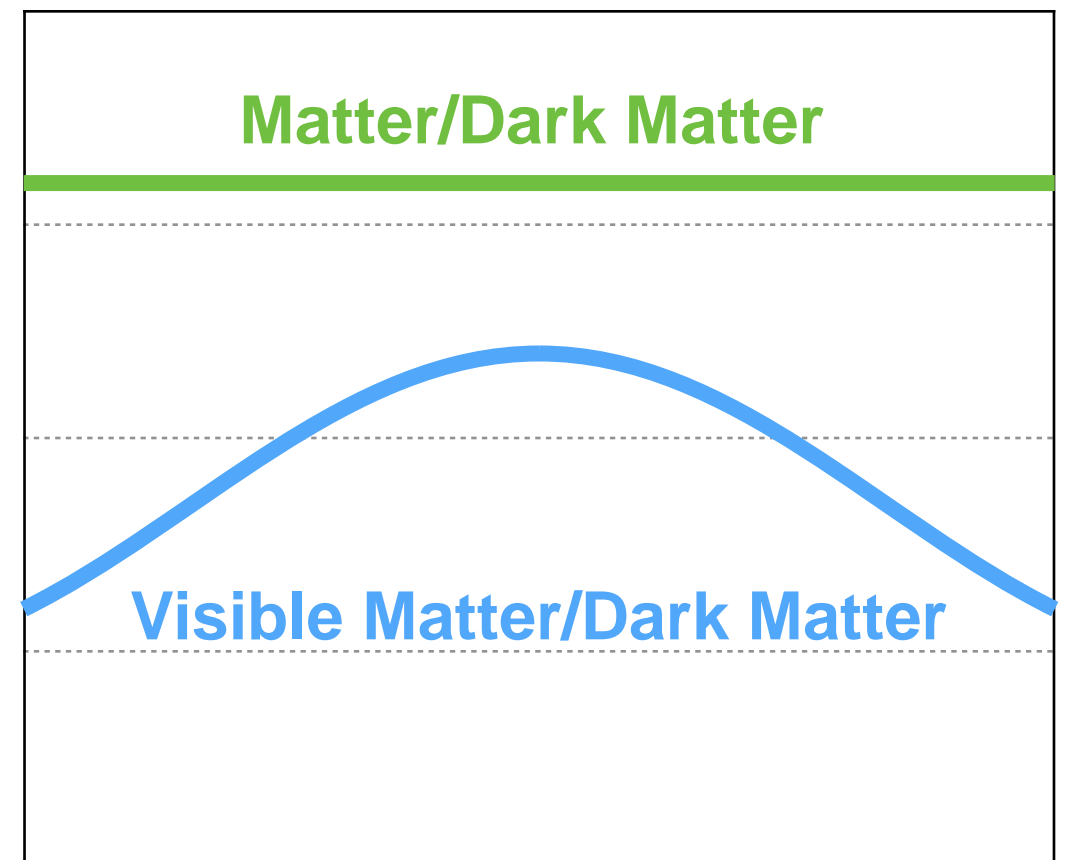


Matter in the Universe

- Dark Energy
- Dark Matter
- Visible Matter
- Invisible Matter



Baryons are missing at all scales

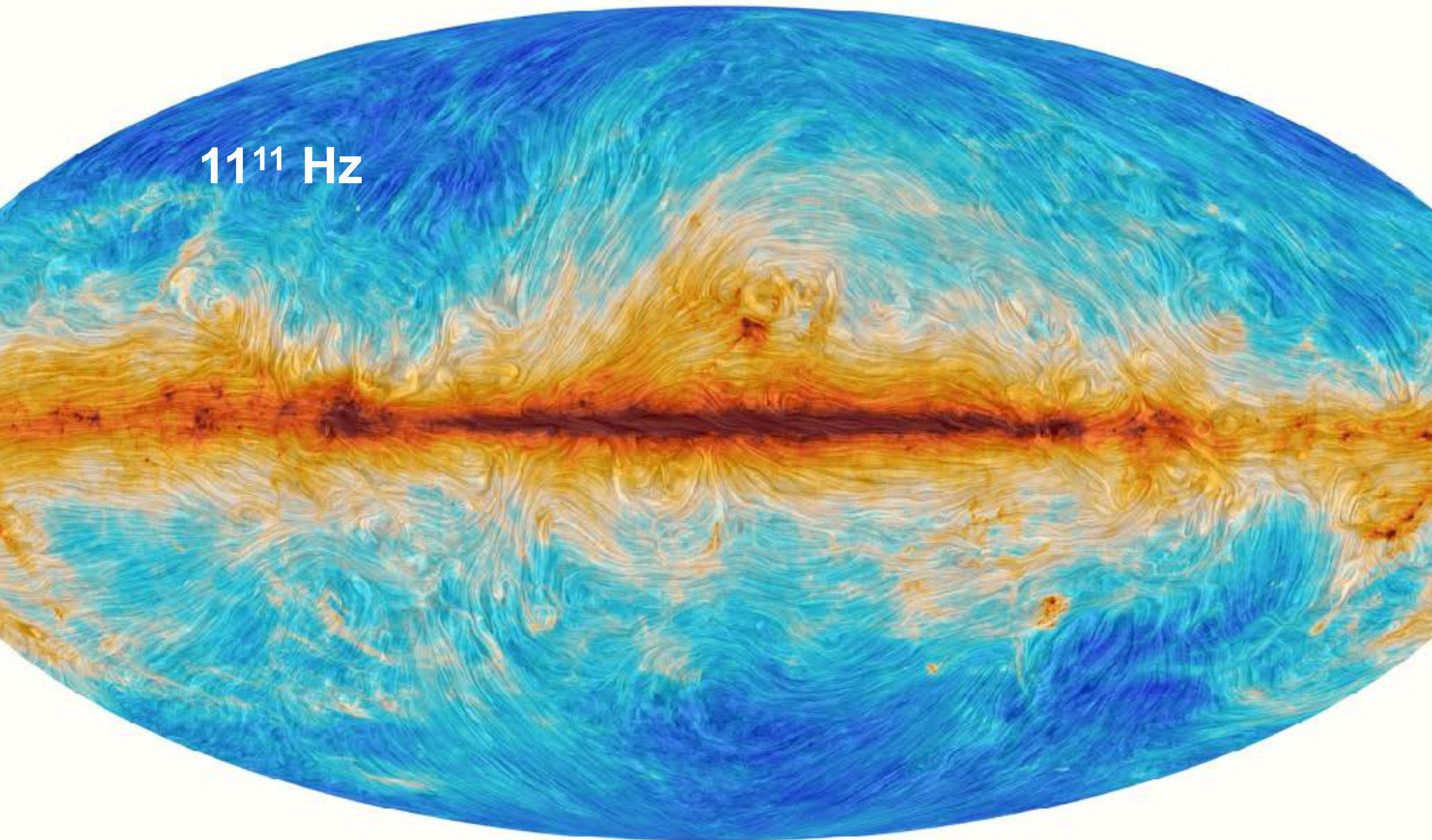


Milky Way

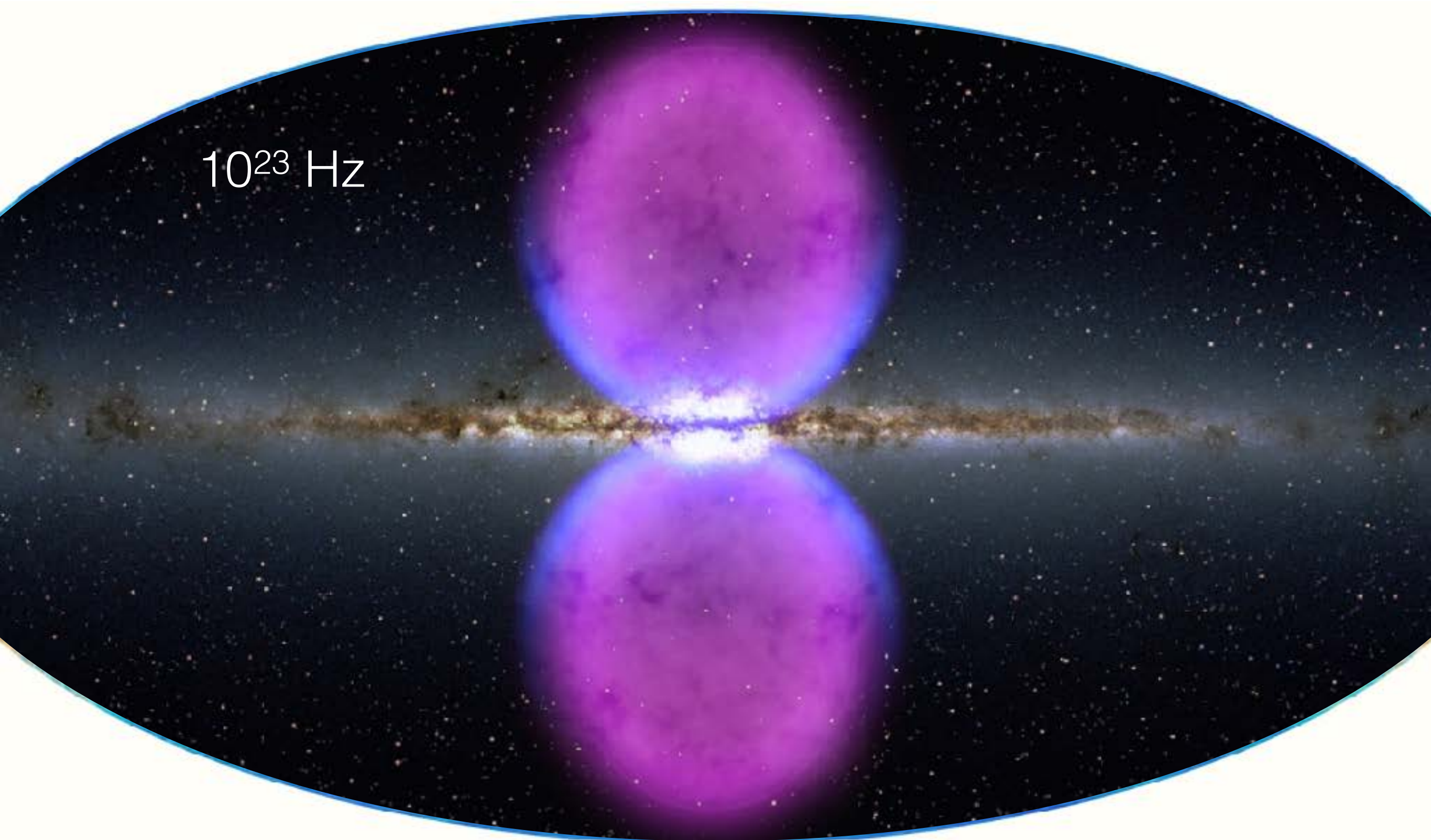
Clusters

Universe

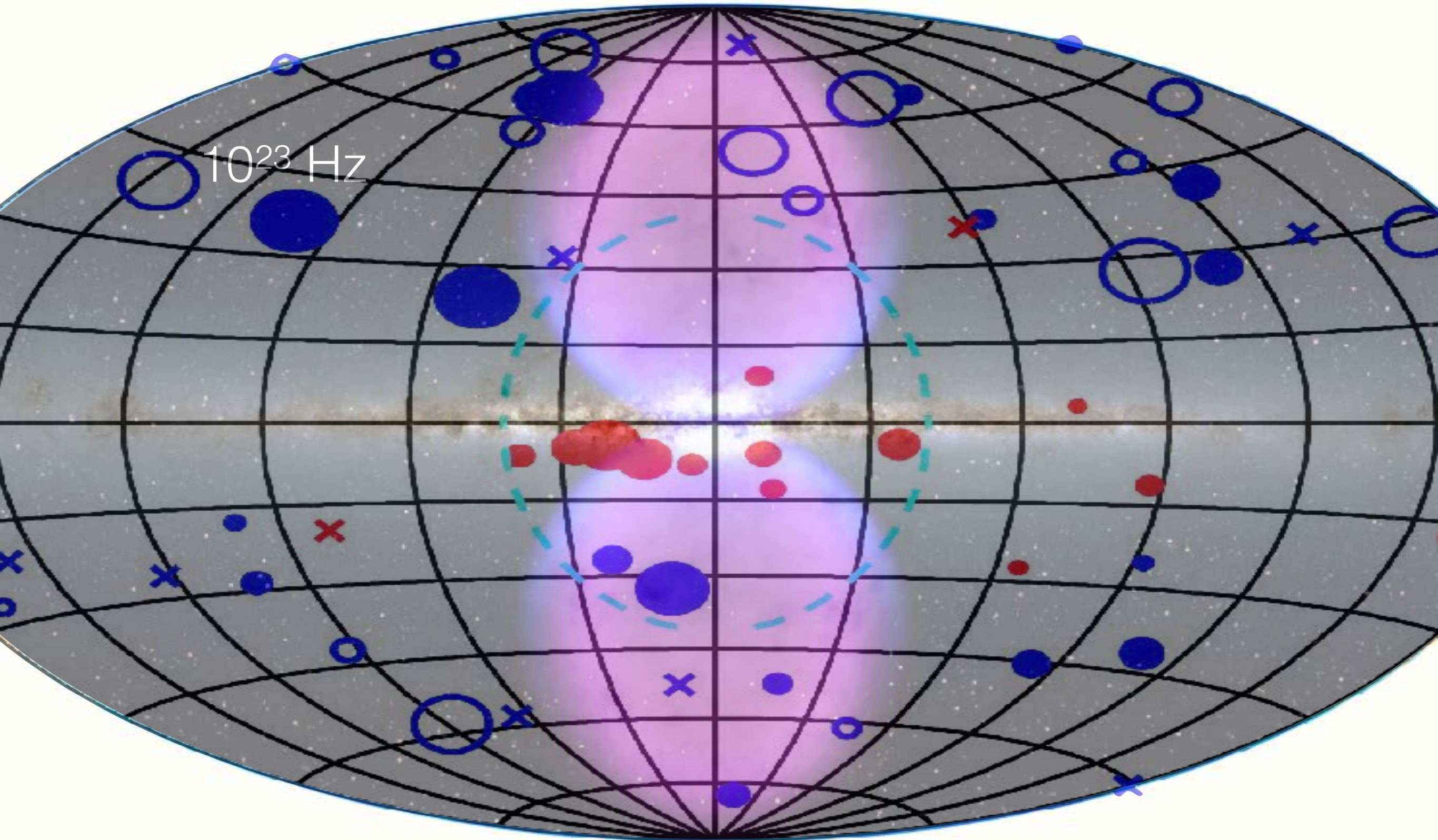
Particle Acceleration and Feedback



Particle Acceleration and Feedback



Particle Acceleration and Feedback



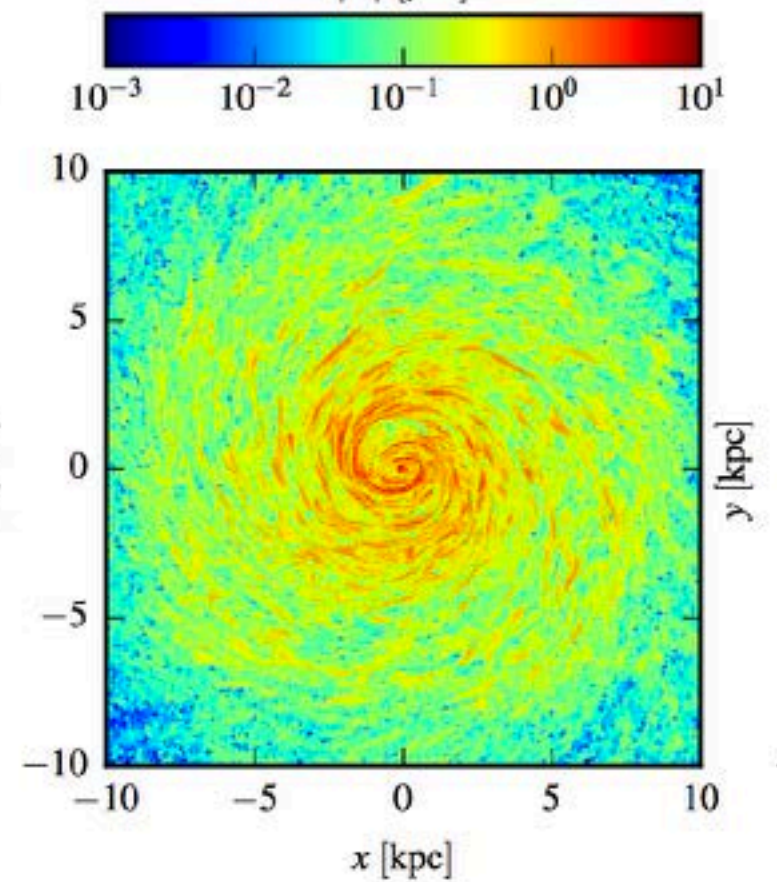
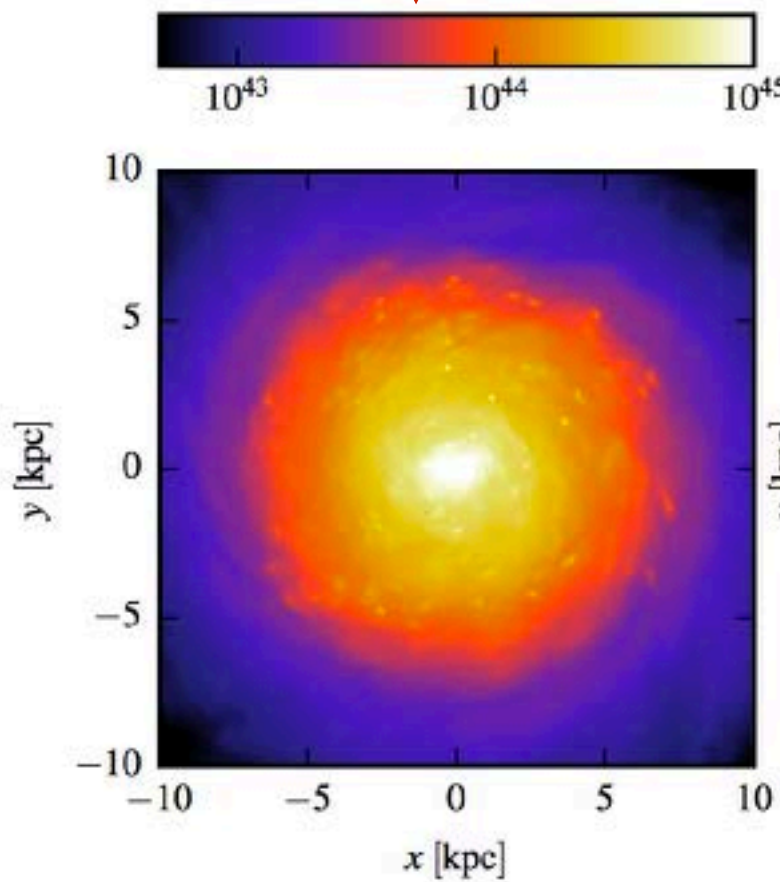
Anisotropic CR Diffusion

1 eV/cm³

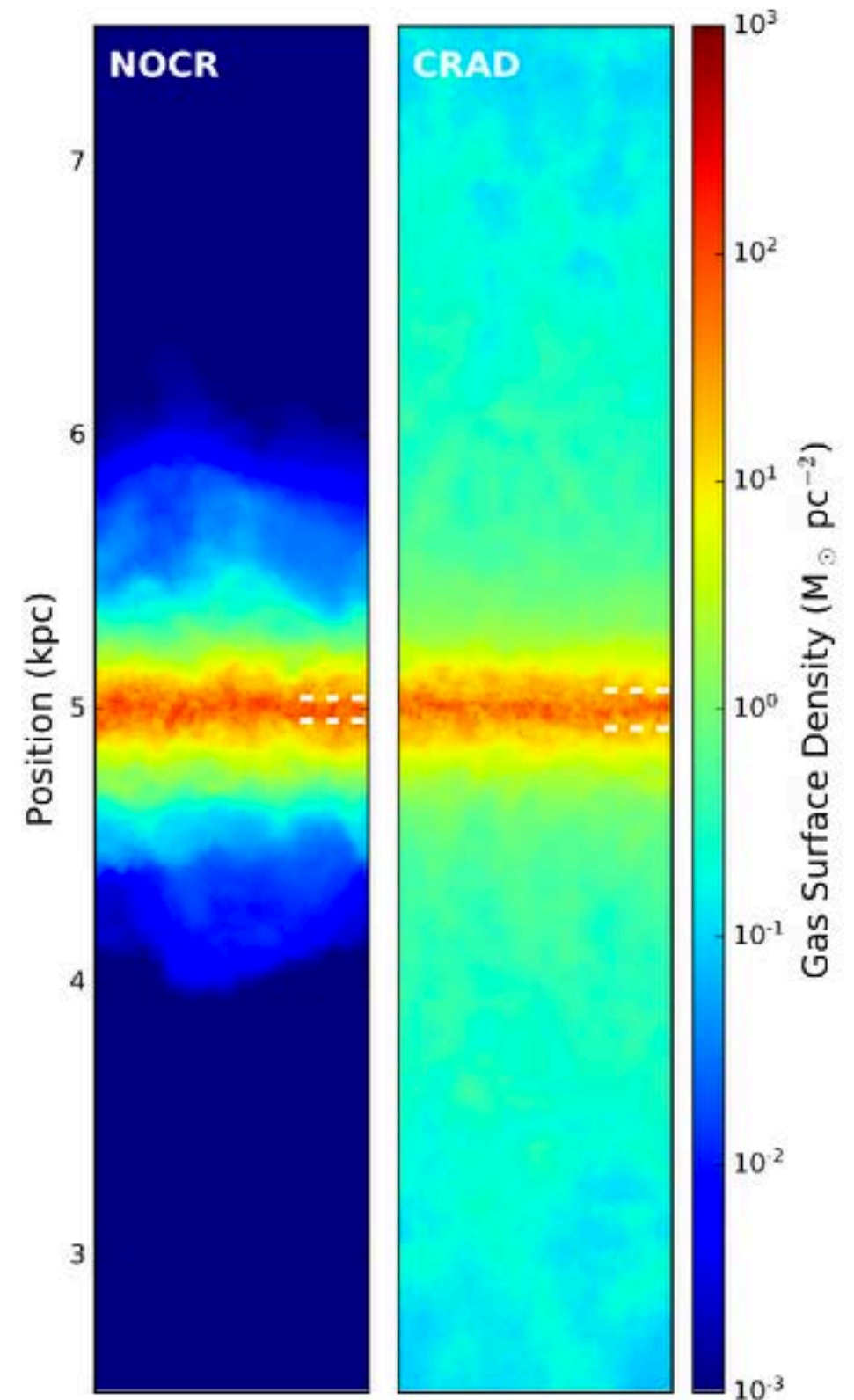
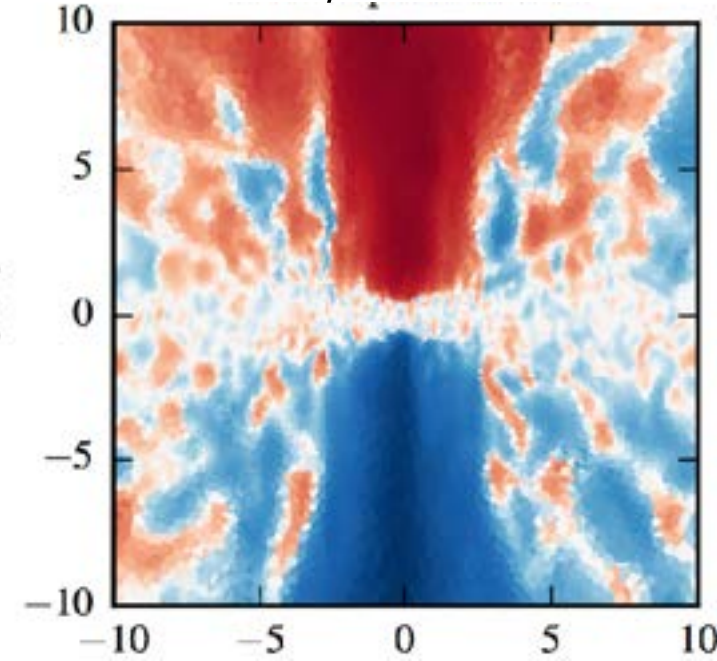
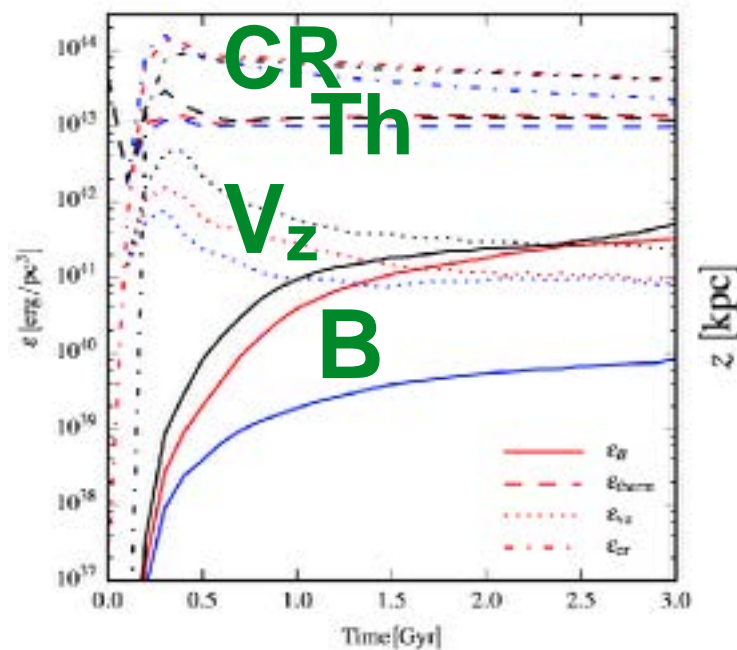
$\epsilon_{\text{CR}} [\text{erg pc}^{-3}]$

Field amplification

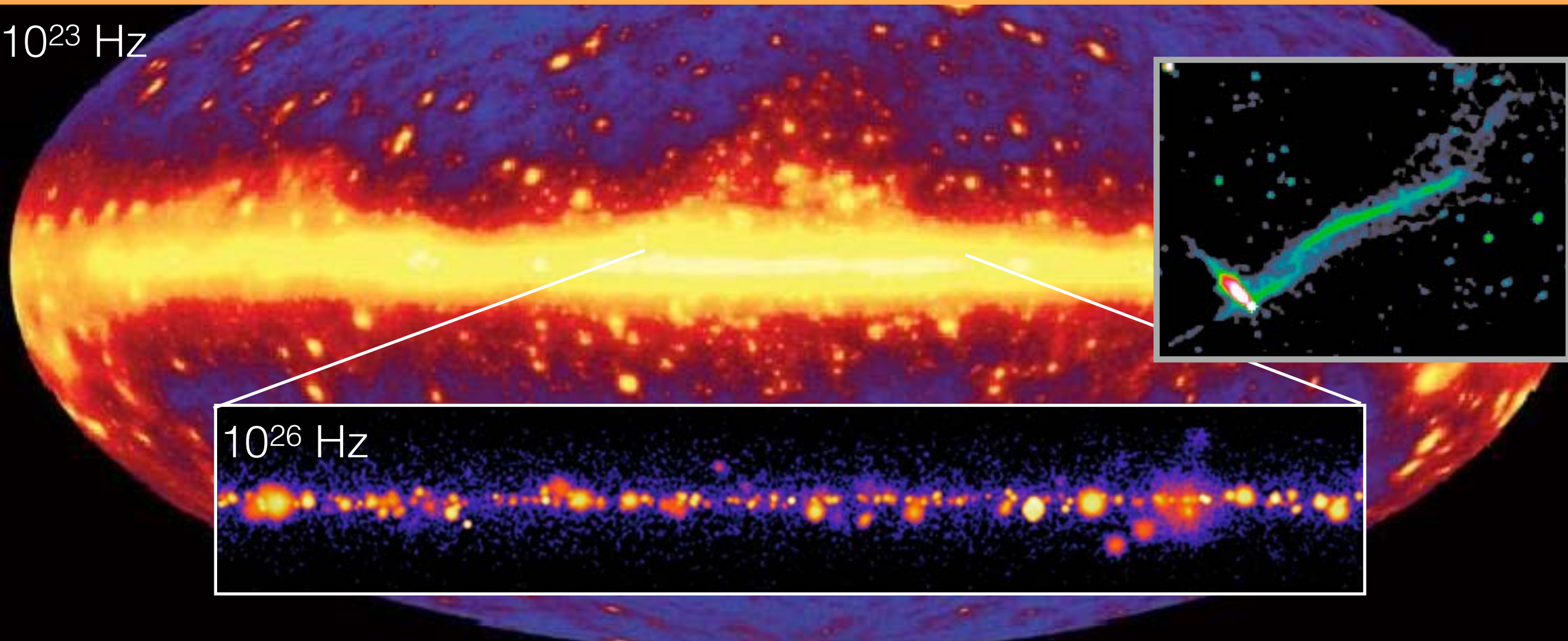
$|B| [\mu\text{G}]$



$dM/dt \sim \text{SFR}$



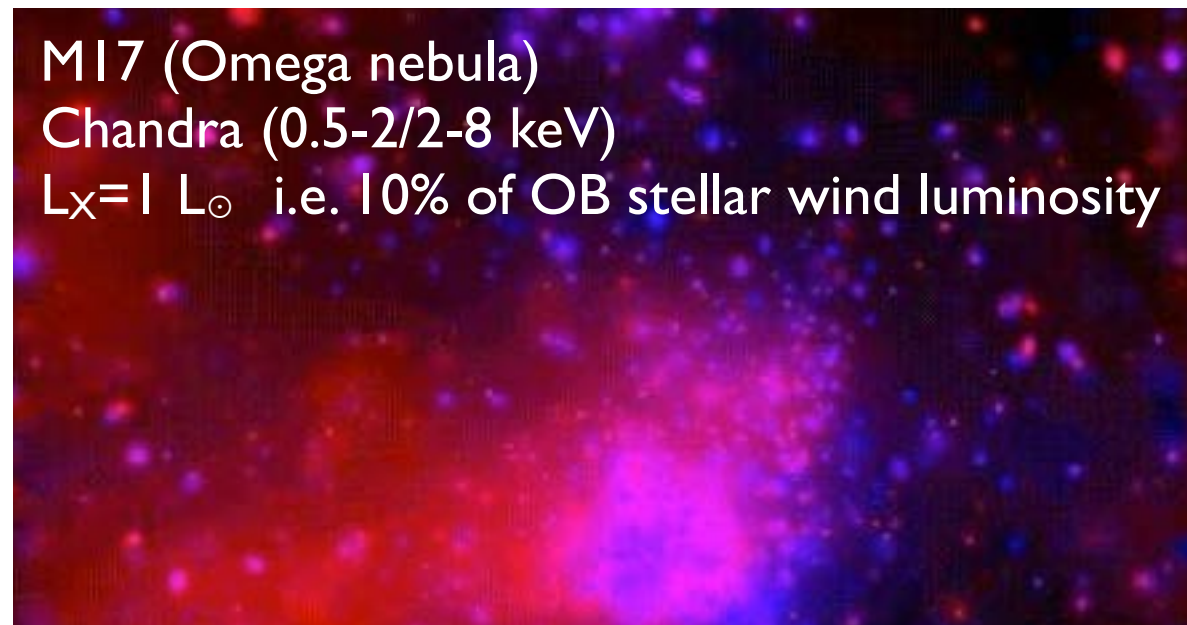
The Milky Way at Gamma-Rays



Accelerators:

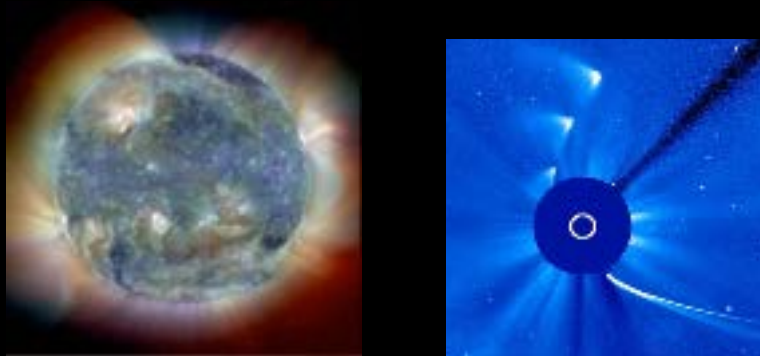
- 1 Supernova Remanents
- 2 Wind collisions in OB regions
- 3

M17 (Omega nebula)
Chandra (0.5-2/2-8 keV)
 $L_X = 1 L_\odot$ i.e. 10% of OB stellar wind luminosity

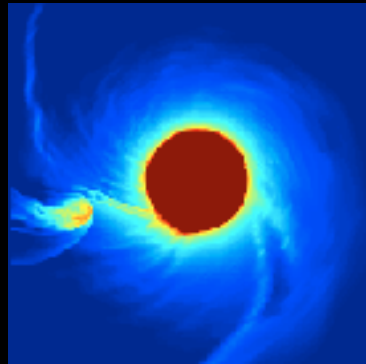


Cosmic Accelerators

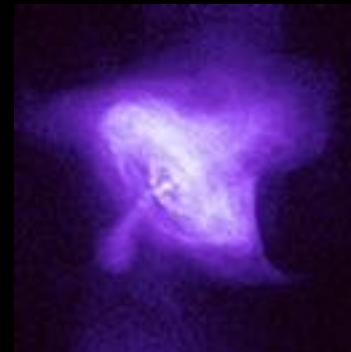
Stars



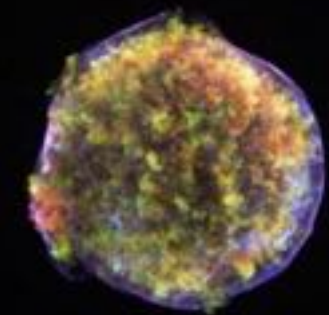
Compact Objects



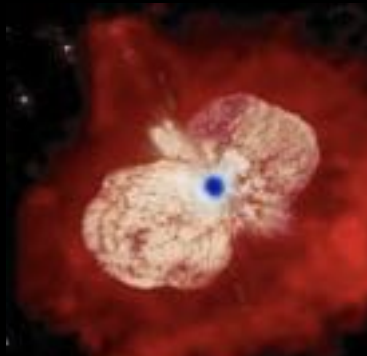
Pulsar Winds



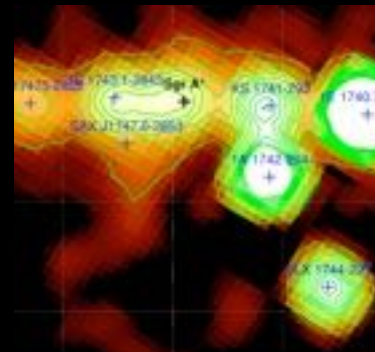
Supernova Remnants



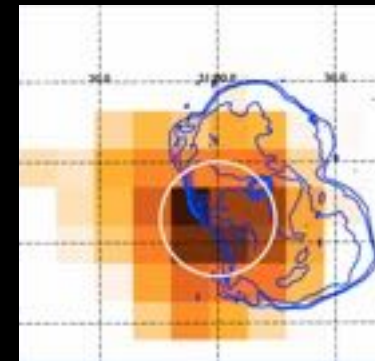
Wind Collisions



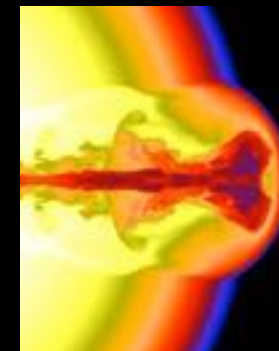
Super-massive Black-Holes



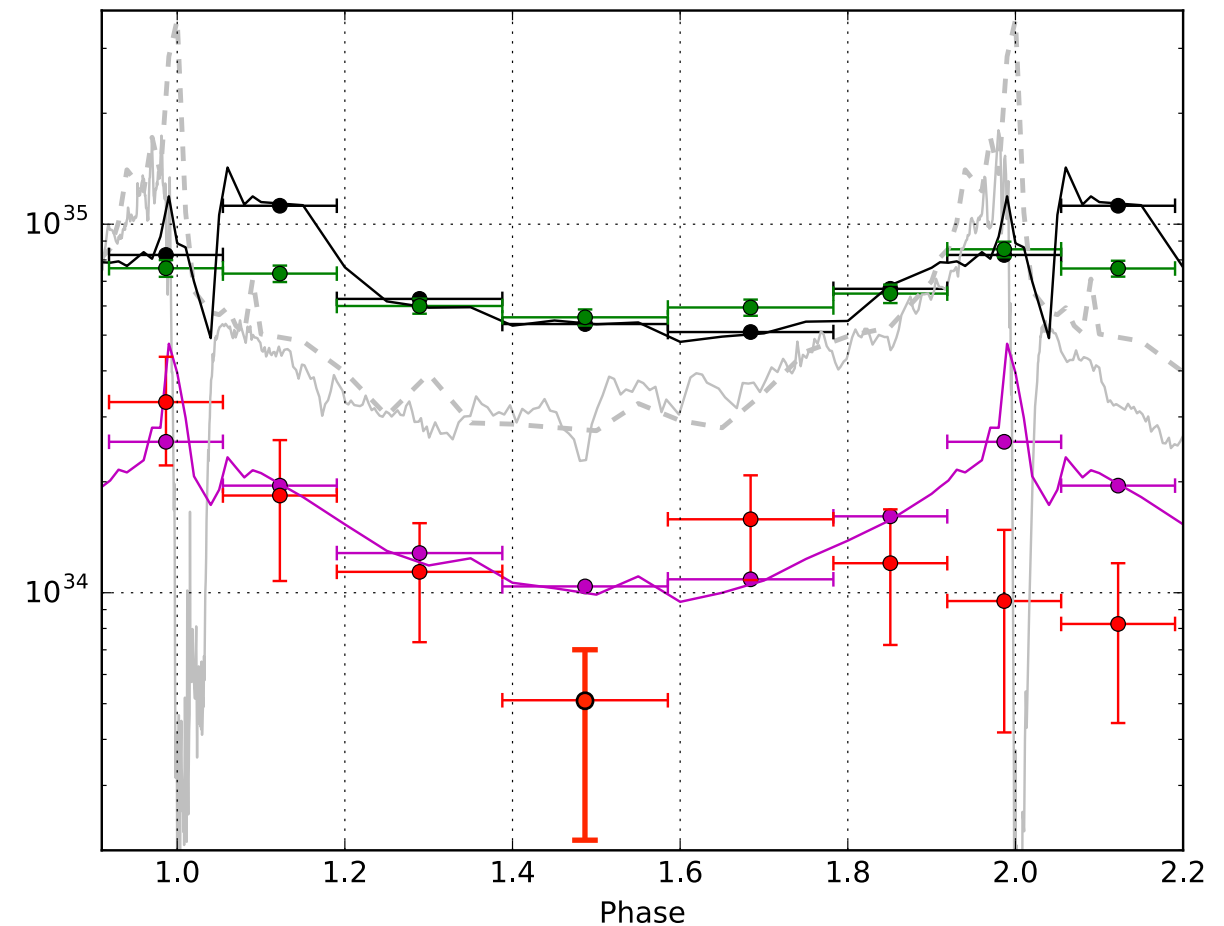
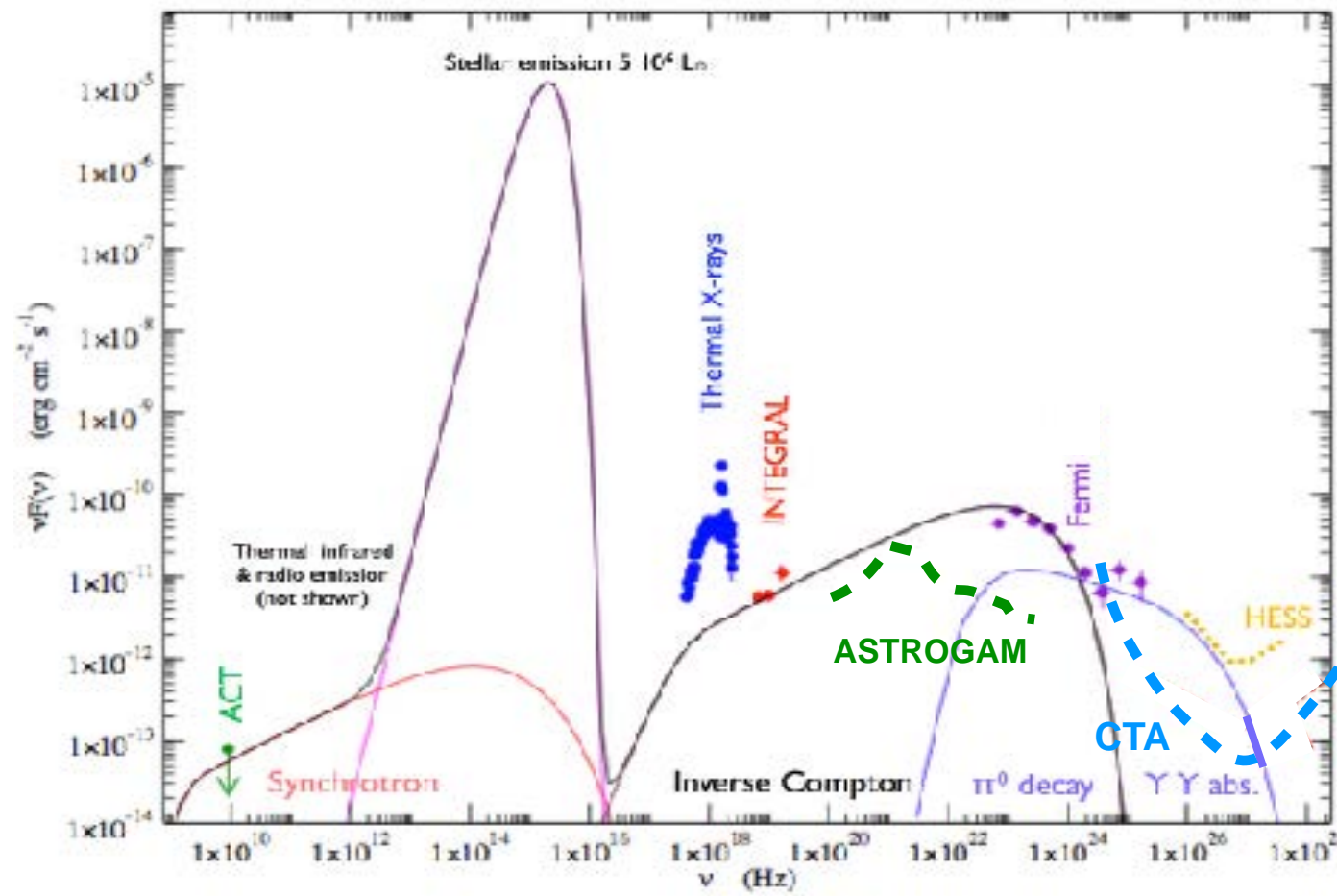
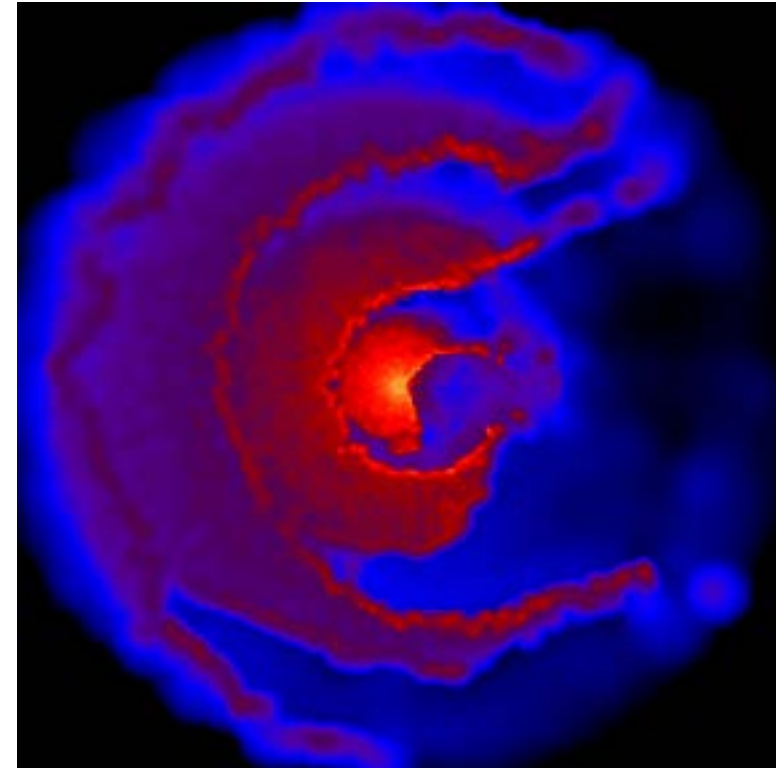
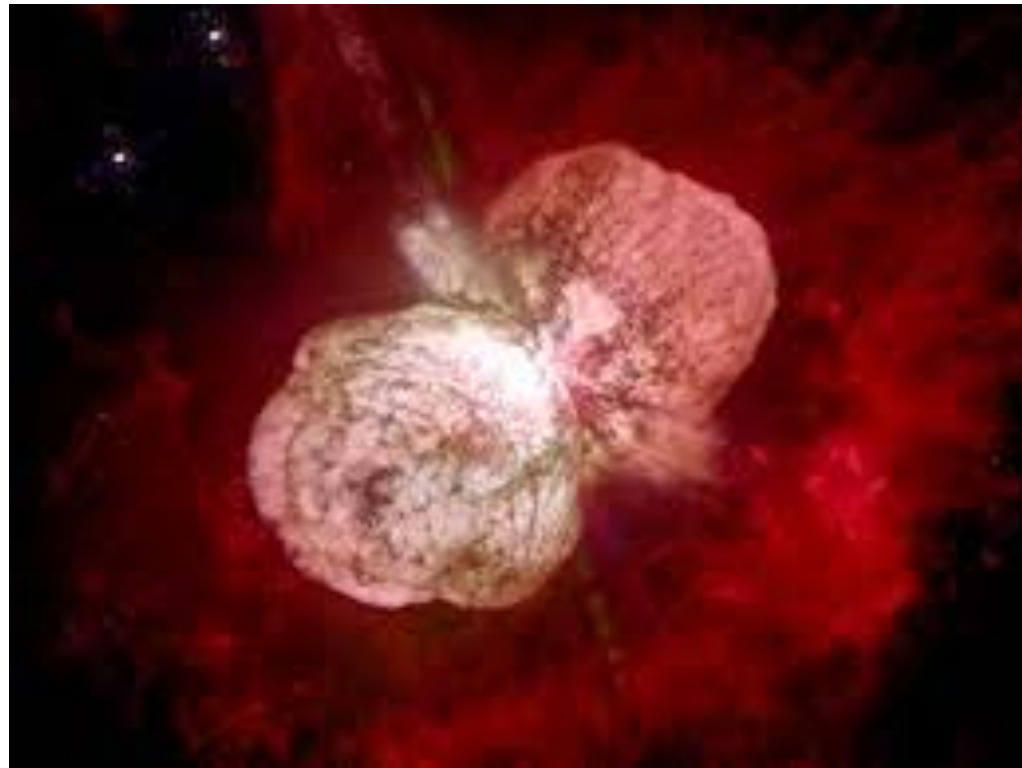
Clusters



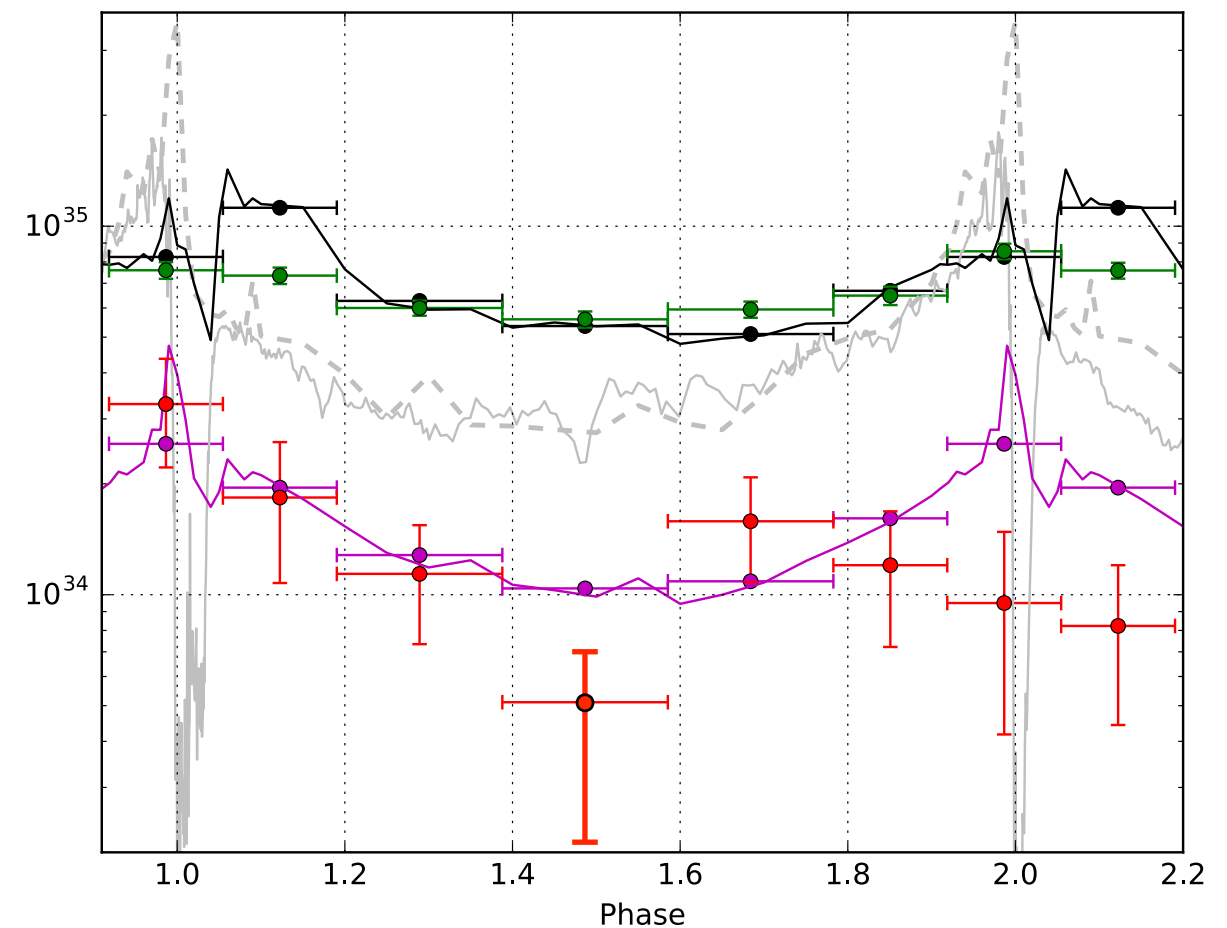
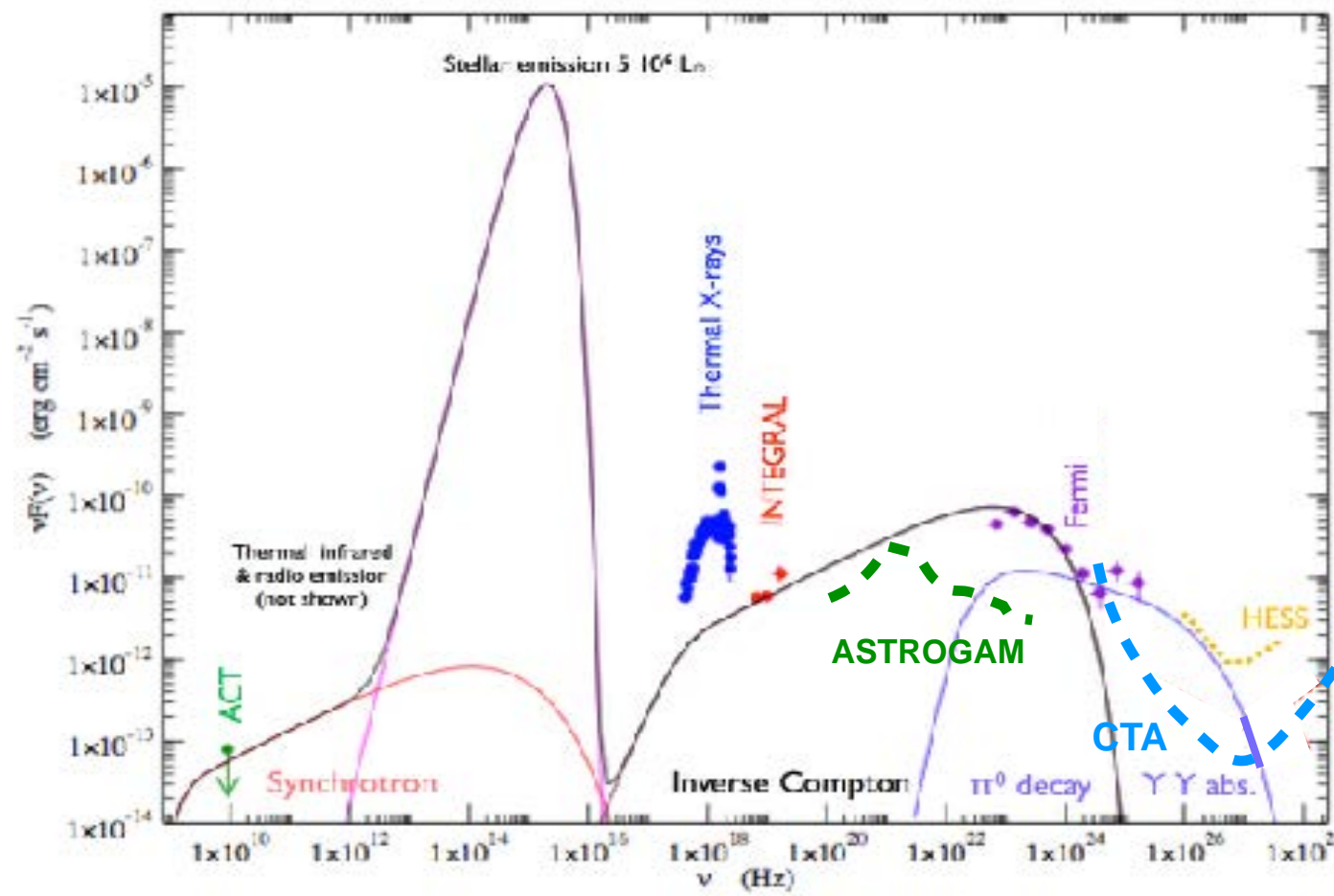
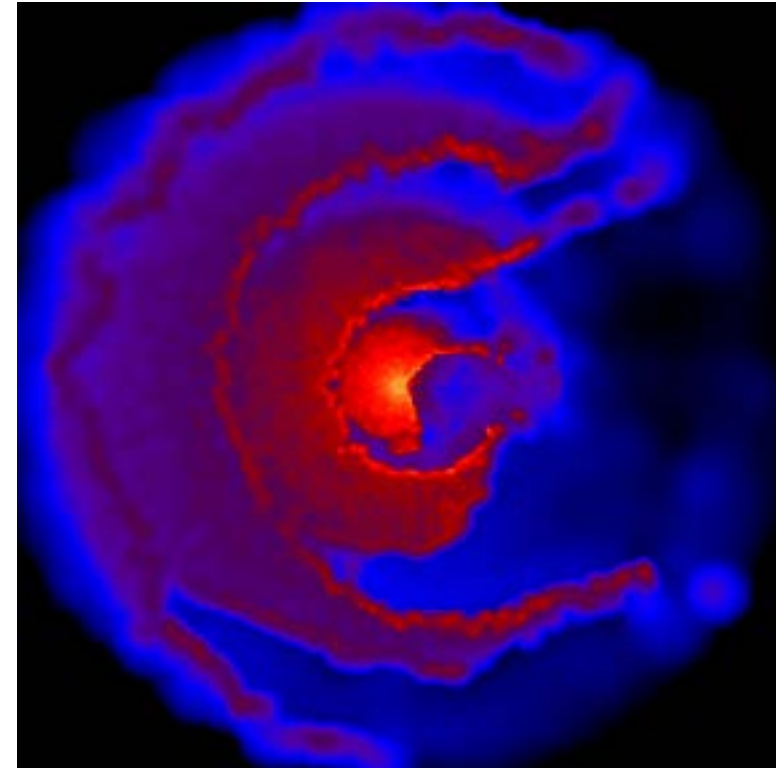
Gamma-Ray Burst



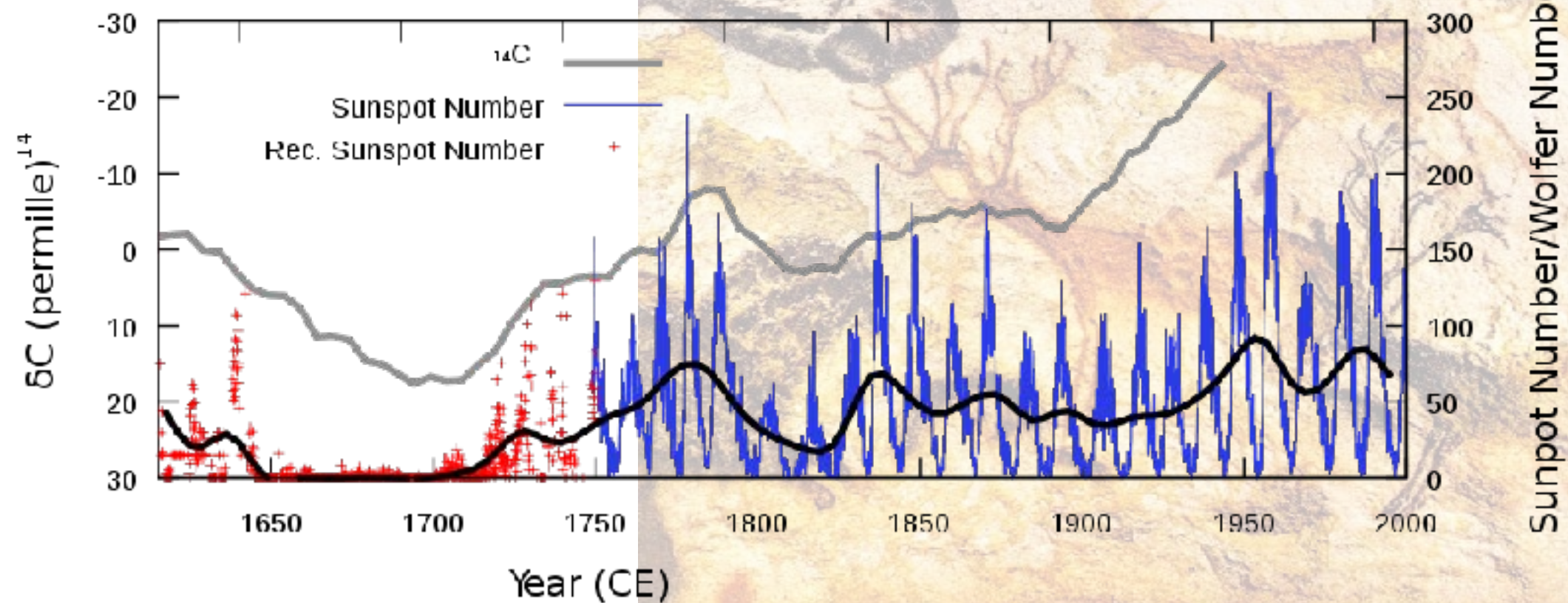
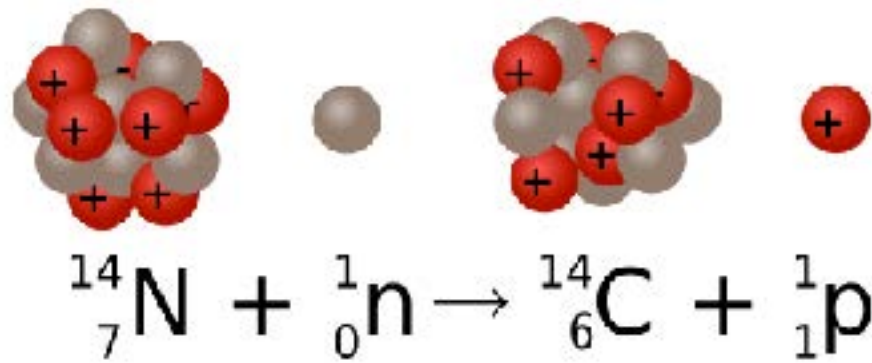
Eta Carinae



Eta Carinae



Feedback on Earth: Carbon 14



Feedback on Earth: Climate

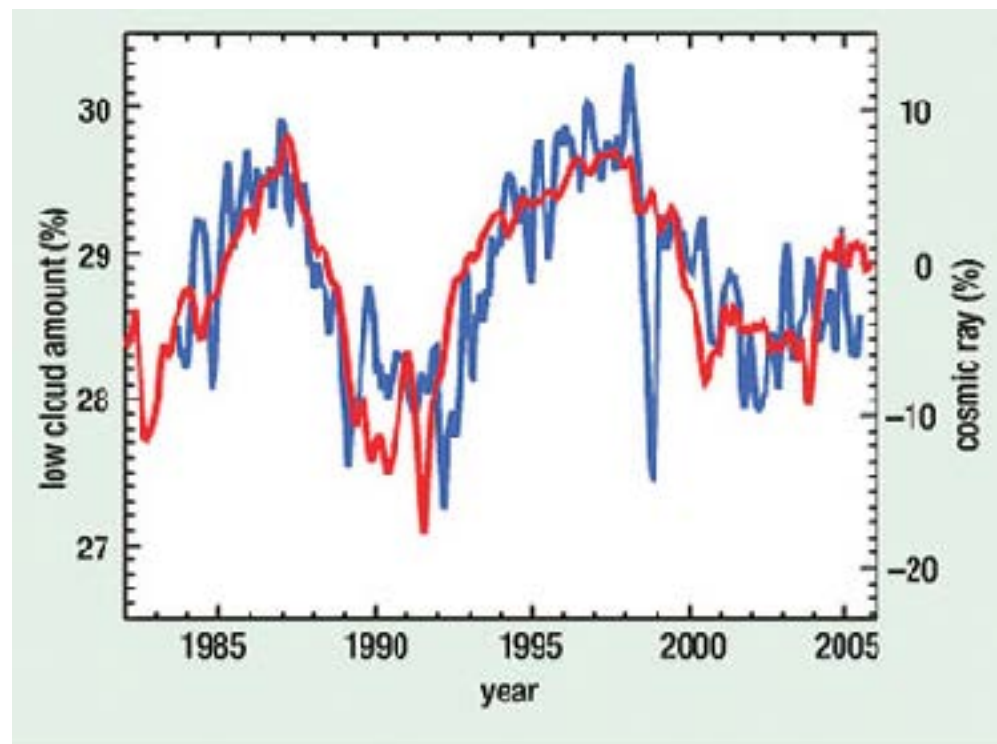
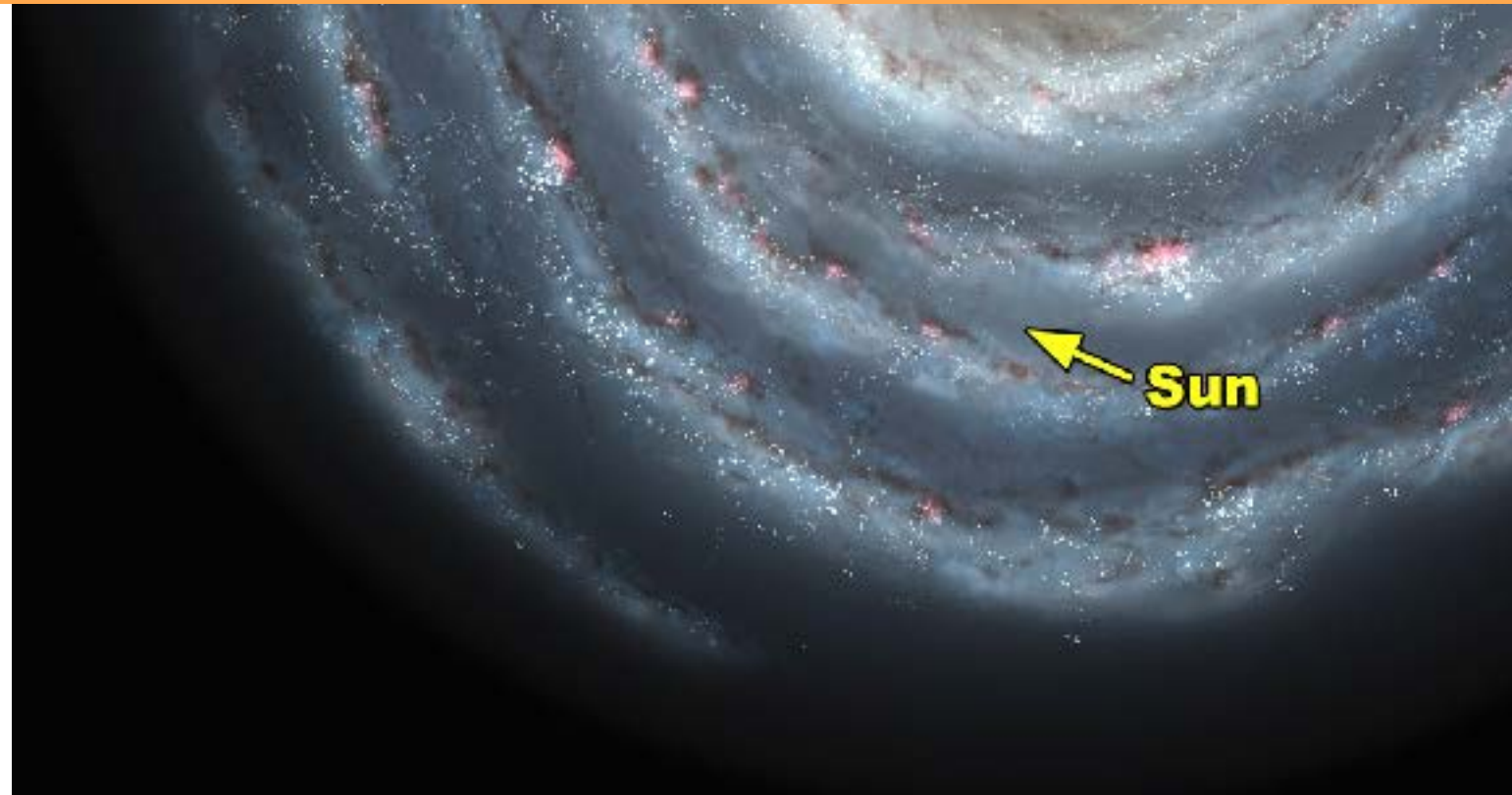
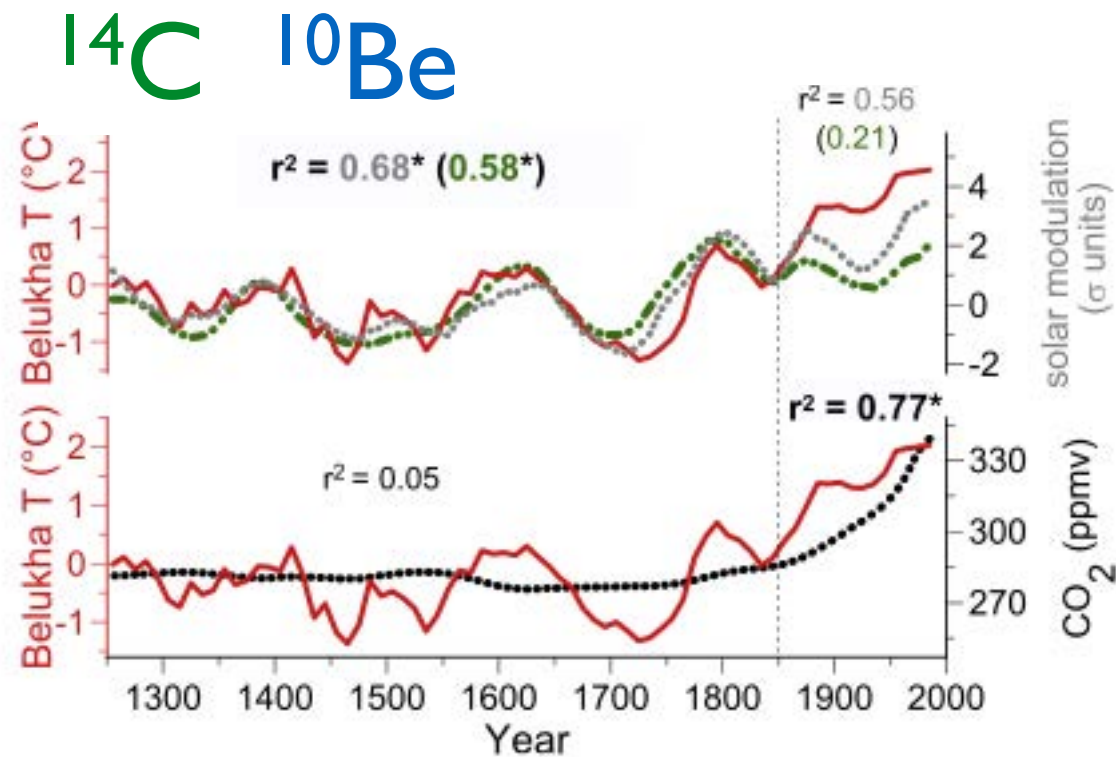


Figure 2. Global variation in cloud amount for clouds below 3.2 kilometers above sea level (blue line) compared to the anomaly in cosmic ray counts at Climax, Colorado (red line).⁶

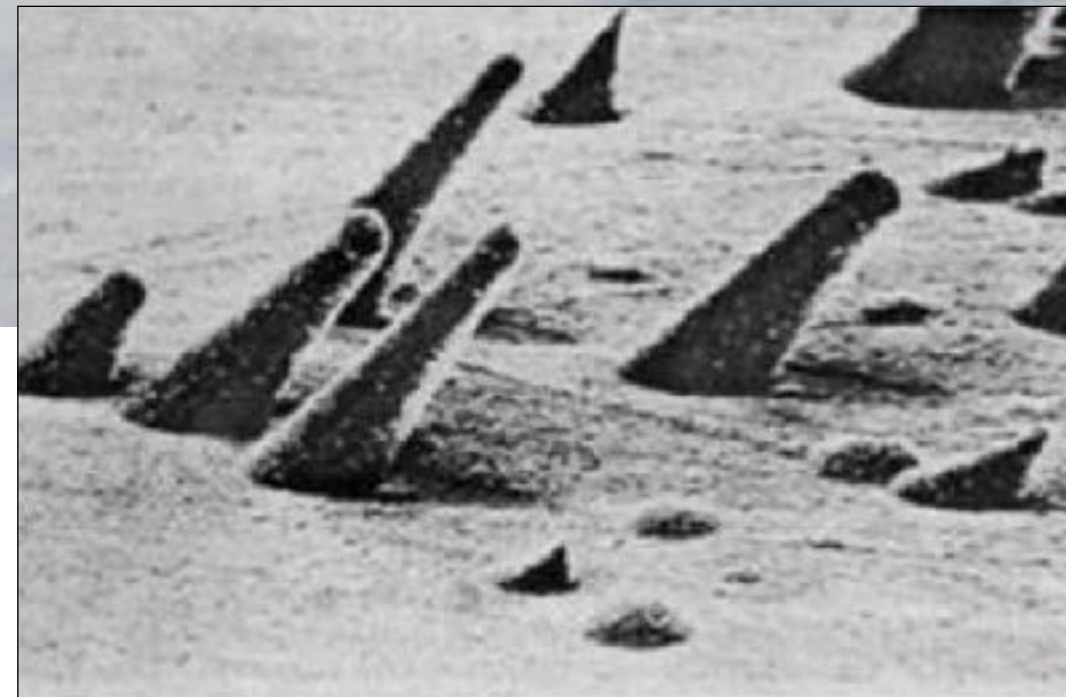
Atmosphere transparency
Cloud formation



Feedback on Humans: Irradiation



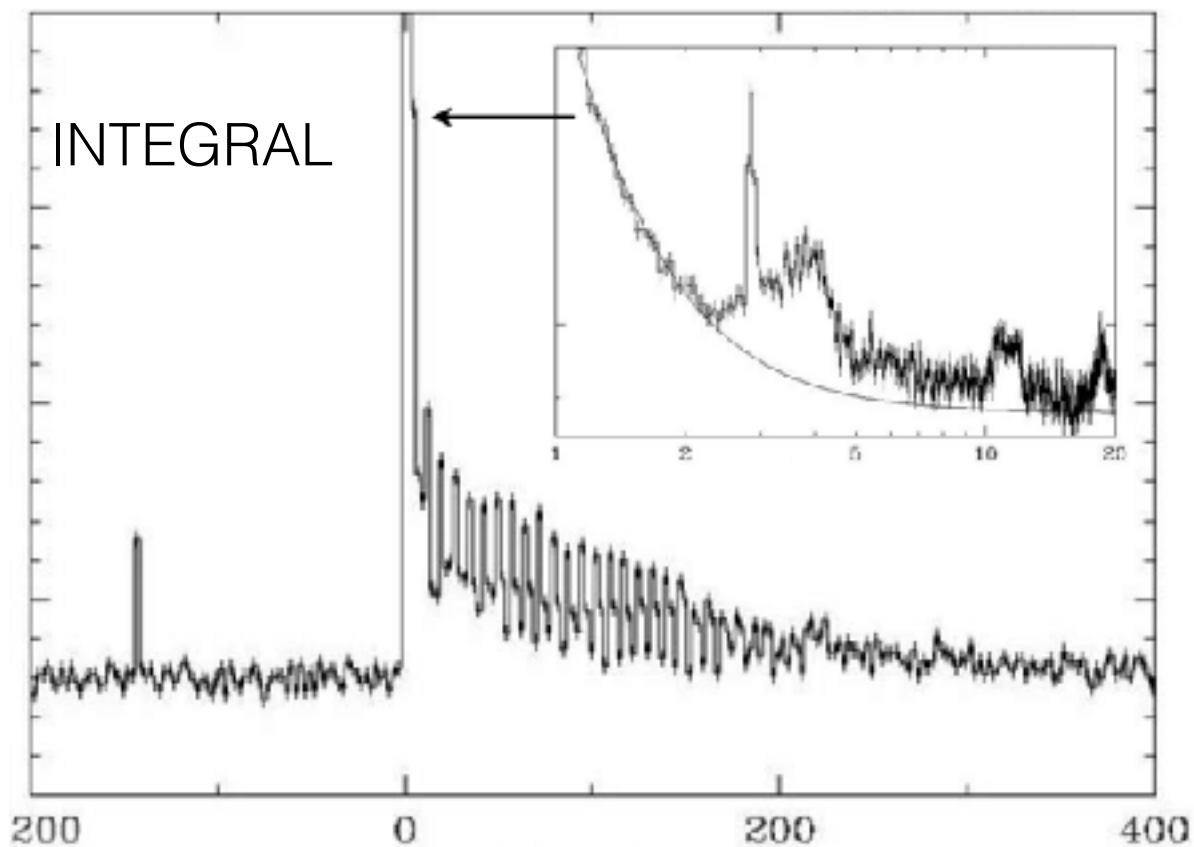
$\sim 1 \text{ Sv/y}$



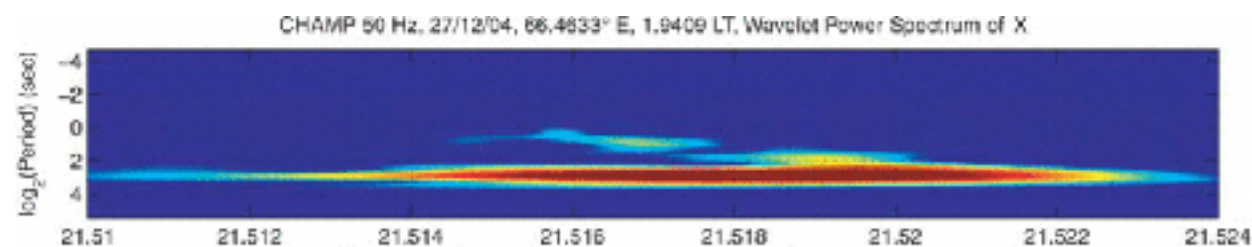
Gamma-Ray feedback on Earth

Giant flares from Magnetars

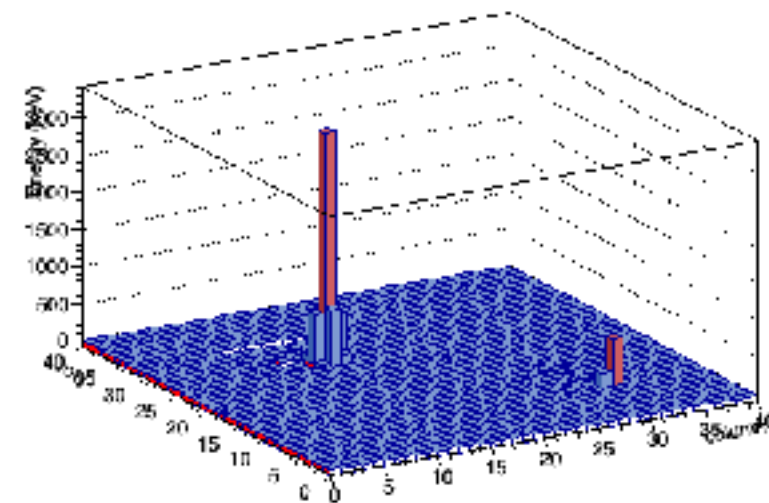
SGR 1806-20 - Dec 24, 2004



$P=7.56$ sec



Gamma-Ray Bursts



SCIENCE MISSION ELEMENTS

INTEGRAL

Medium mission of the ESA's Horizon 2000 program.
Launched on October 17, 2002.
Hard X-rays & soft gamma-rays.

- Best spatial resolution
- Best narrow-line sensitivity
- Large field of view i.e. long effective exposure
- Broad energy range

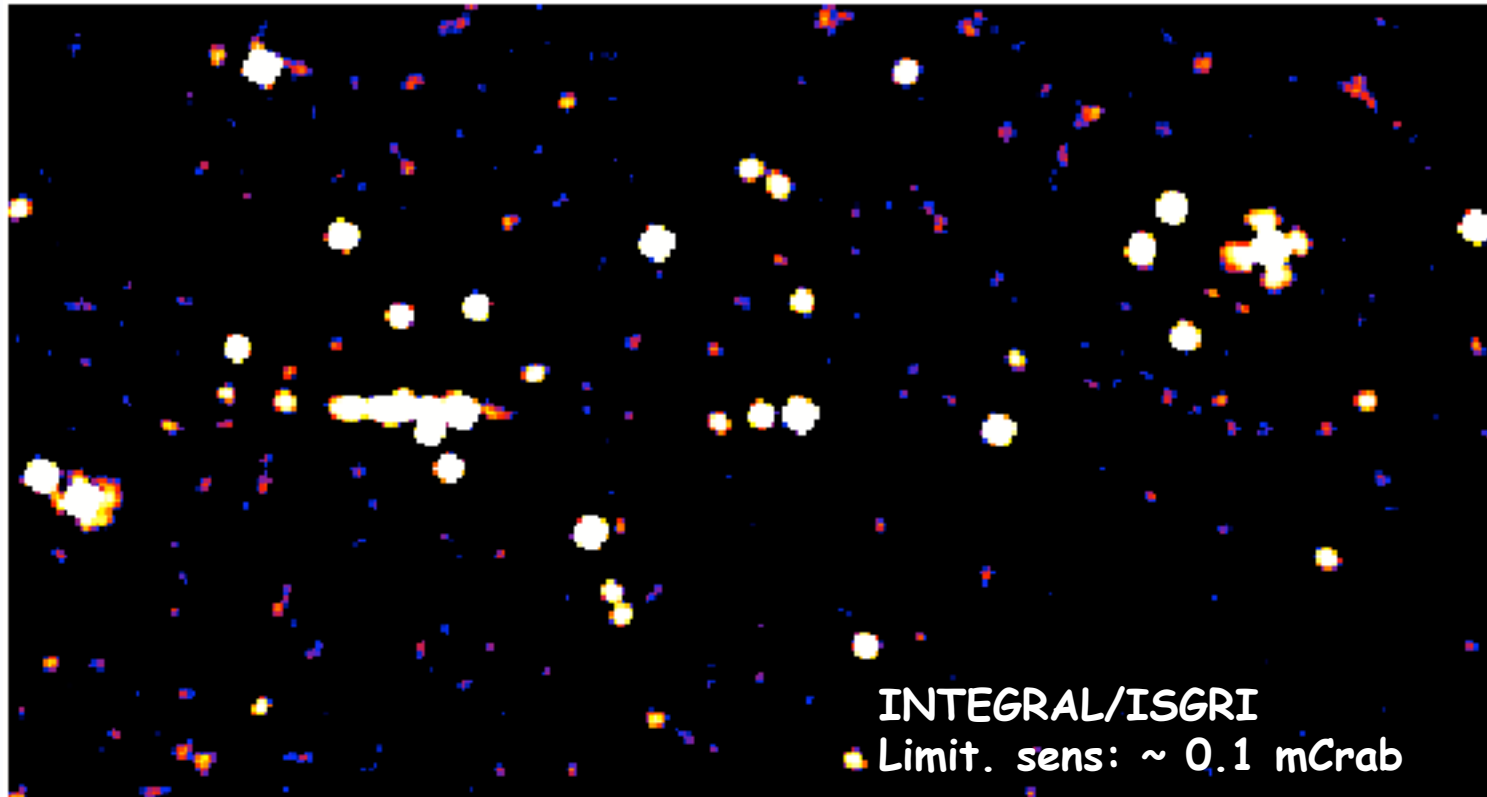
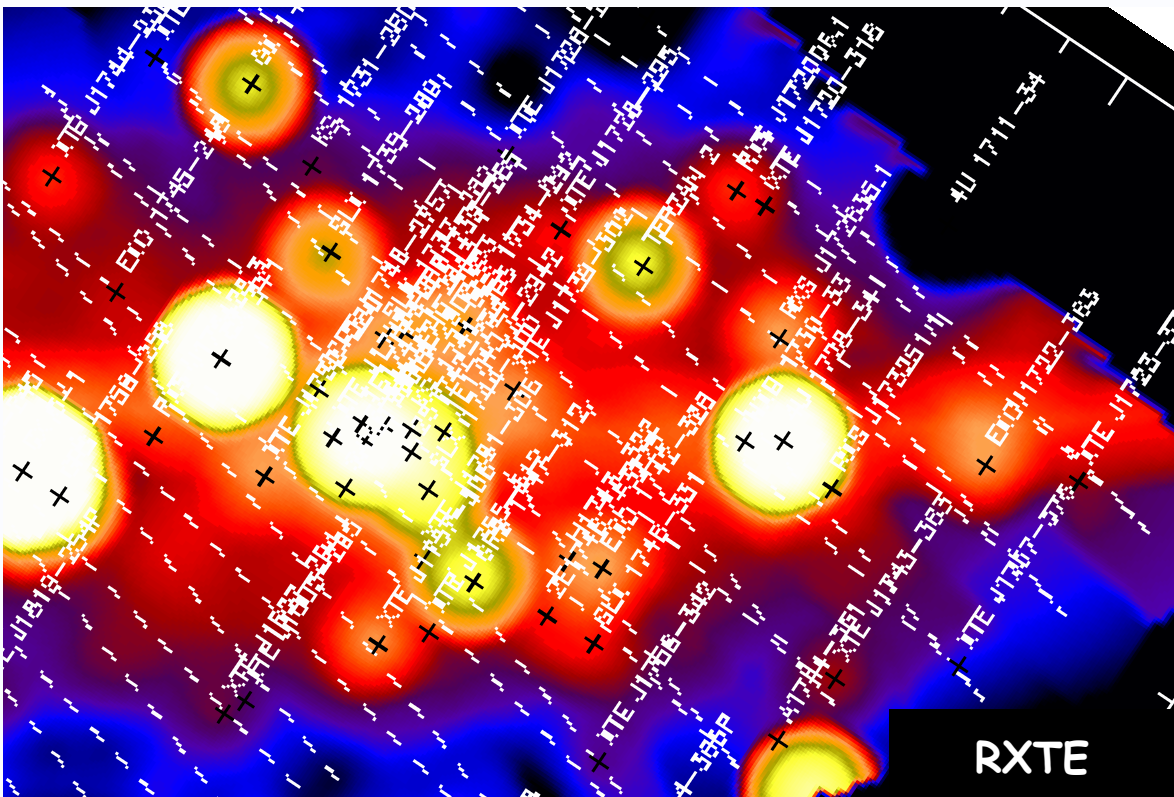
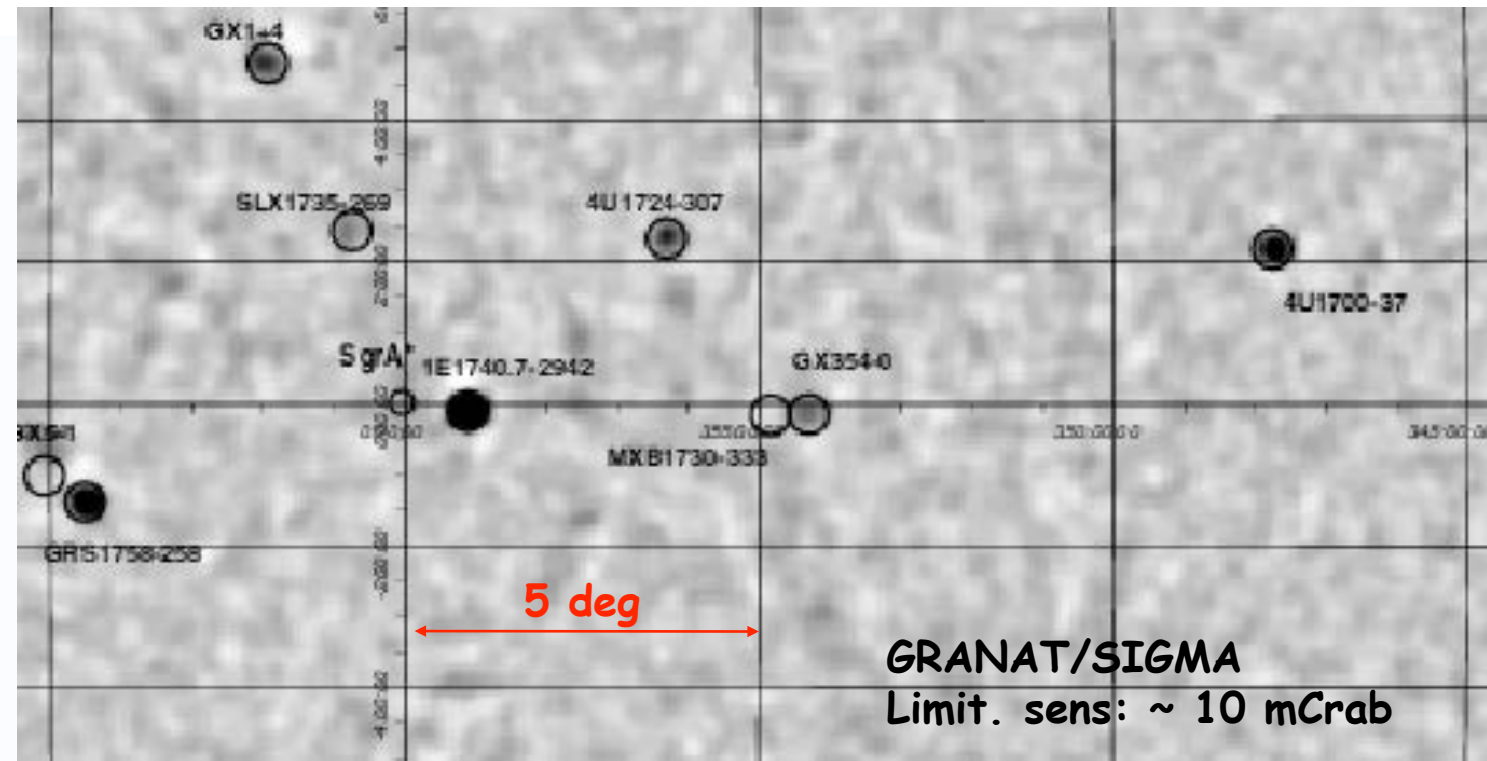
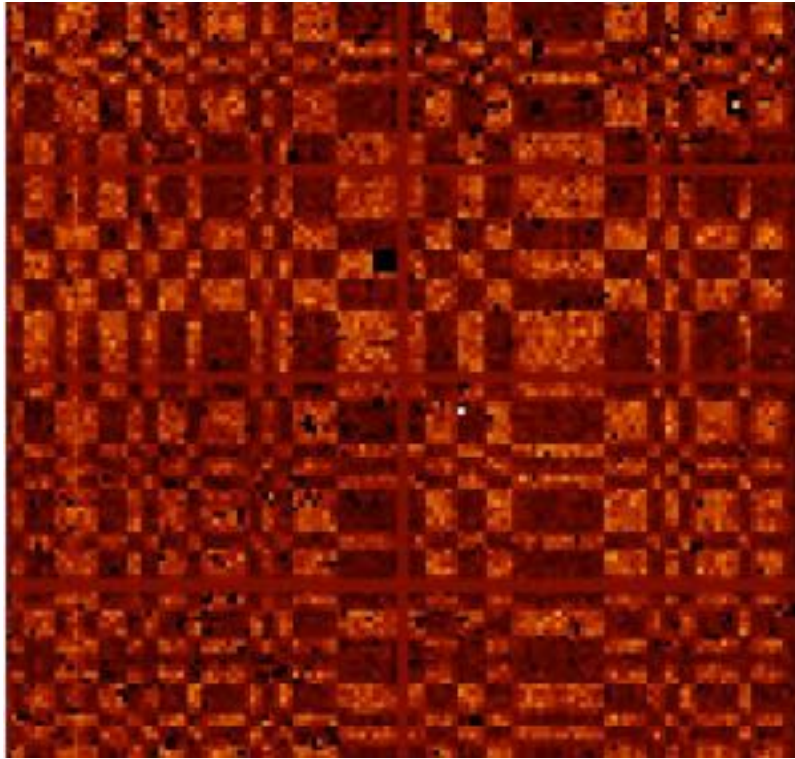
	SPI	IBIS
Energy range	18 keV - 8 MeV	15 keV - 10 MeV
Detector	19 Ge detectors (each 6 × 7 cm), cooled @ 85K	16384 CdTe dets (each 4×4×2 mm), 4096 CsI dets (each 8.55×8.55×30 mm)
Detector area (cm ²)	500	2600 (CdTe), 3000 (CsI)
Spectral resolution (FWHM)	3 keV @ 1.7 MeV	8 keV @ 100 keV
Field of view (fully coded)	16° (corner to corner)	8.3° × 8°
Angular resolution (FWHM)	2.5' (point source)	12'
Source location (radius)	< 1.3° (depending on source strength)	30" @ 100 keV (50 σ source) 3' @ 100 keV (5 σ source)
Absolute timing accuracy (3 σ)	< 200 μ s ^b	< 100 μ s ^b
Mass (kg)	1309	746
Power [max/average] (W)	385/110	240/208



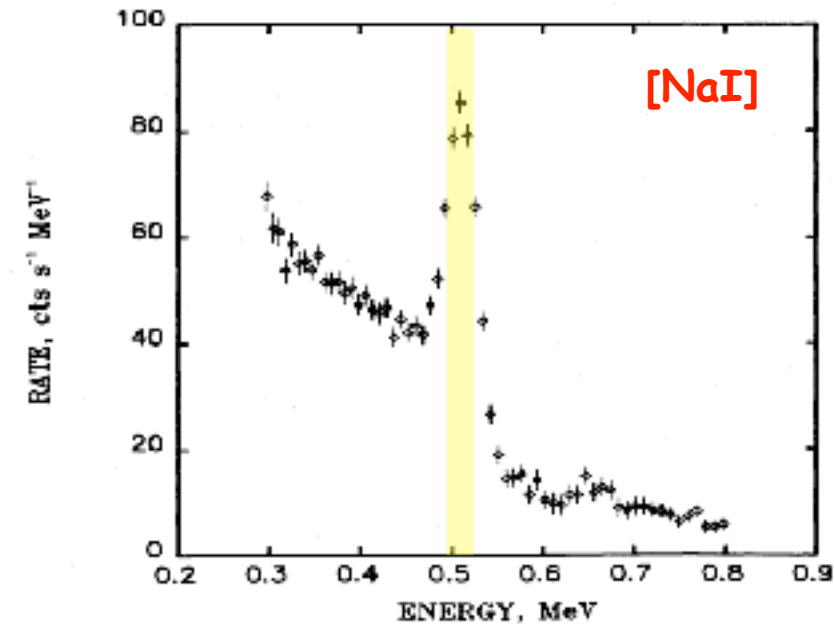
X-ray monitor (JEM-X) 3-35 keV
Optical monitor (OMC) V band



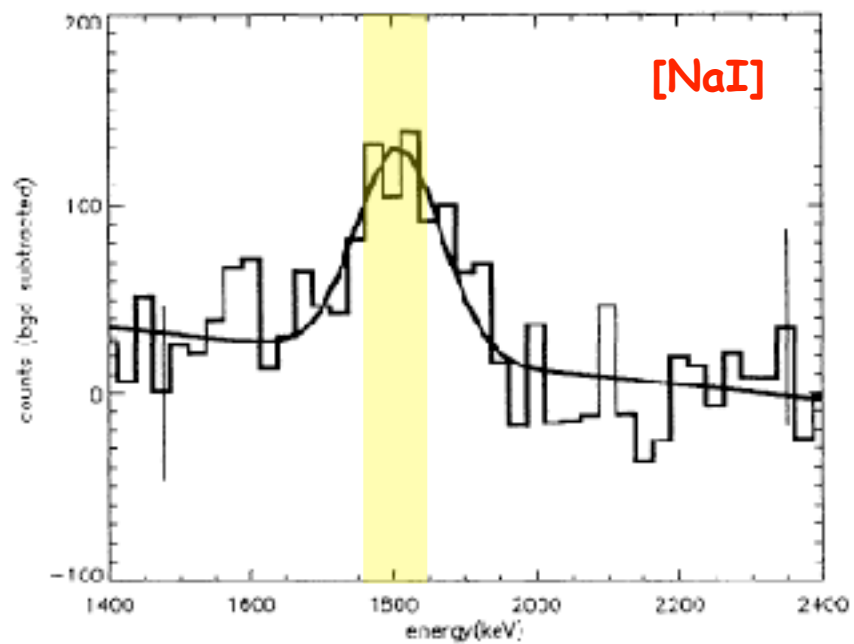
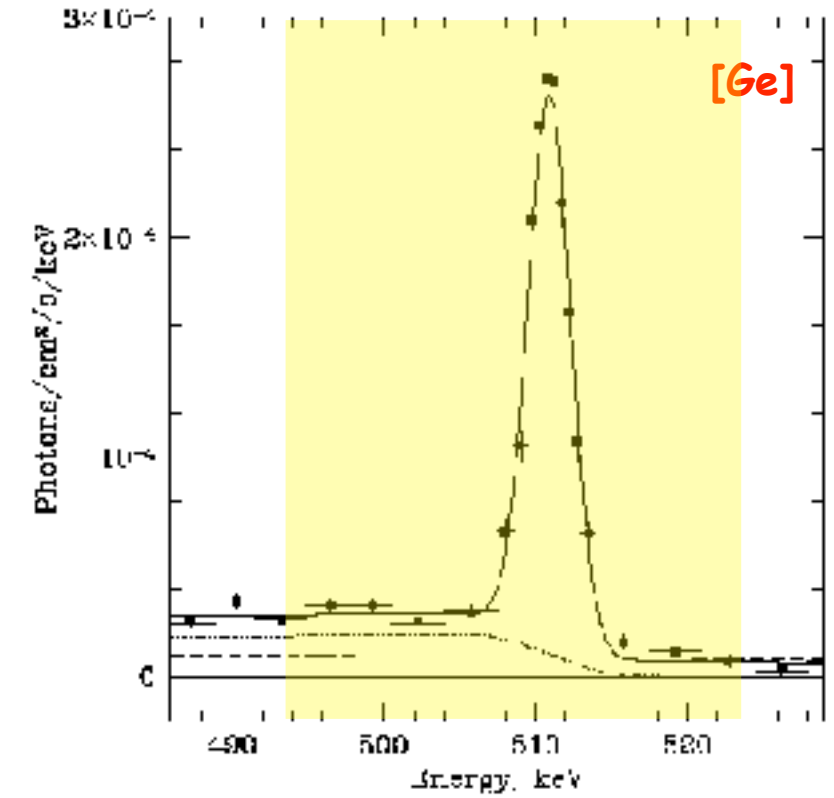
Advances in Imaging



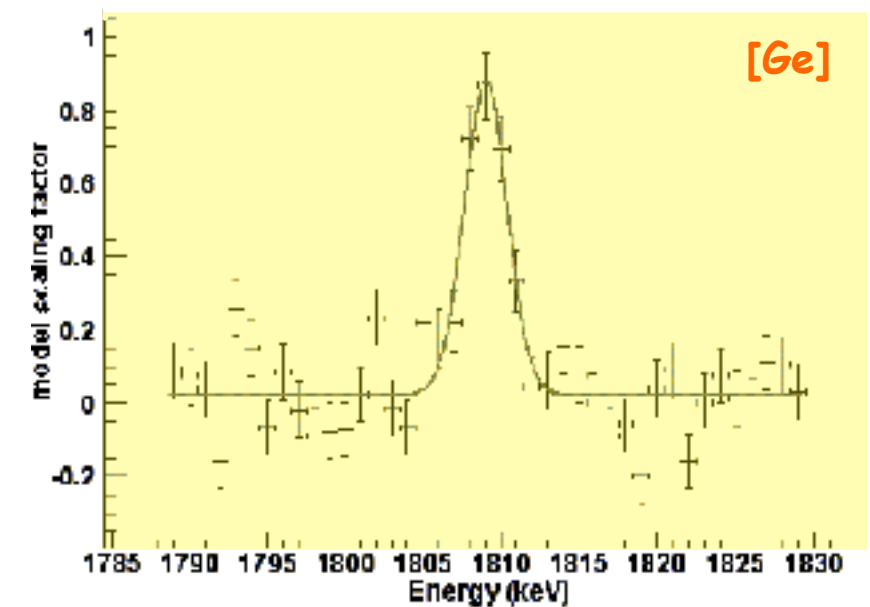
Advances in Spectroscopy



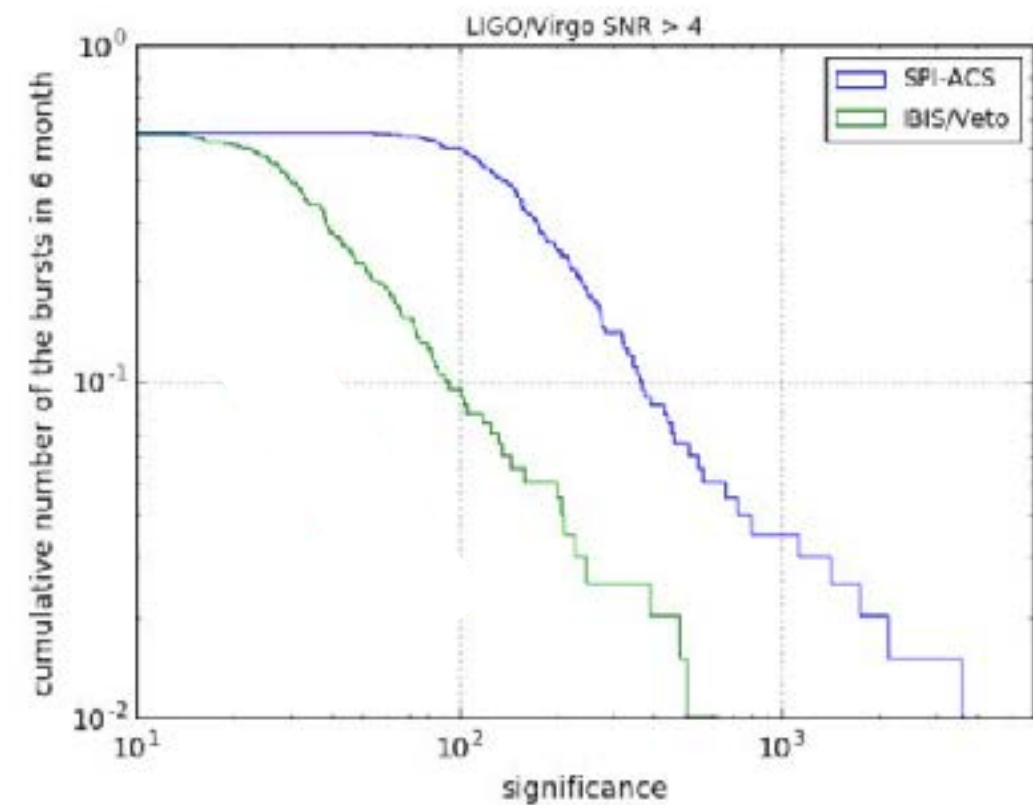
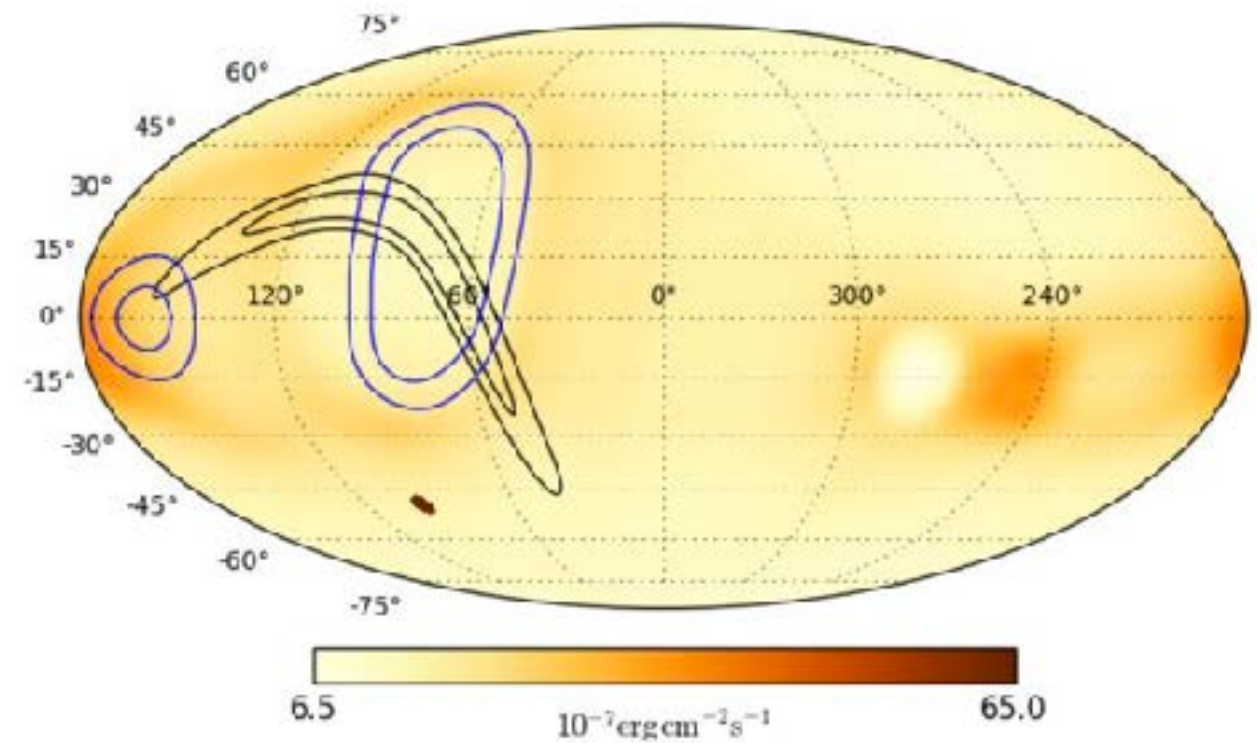
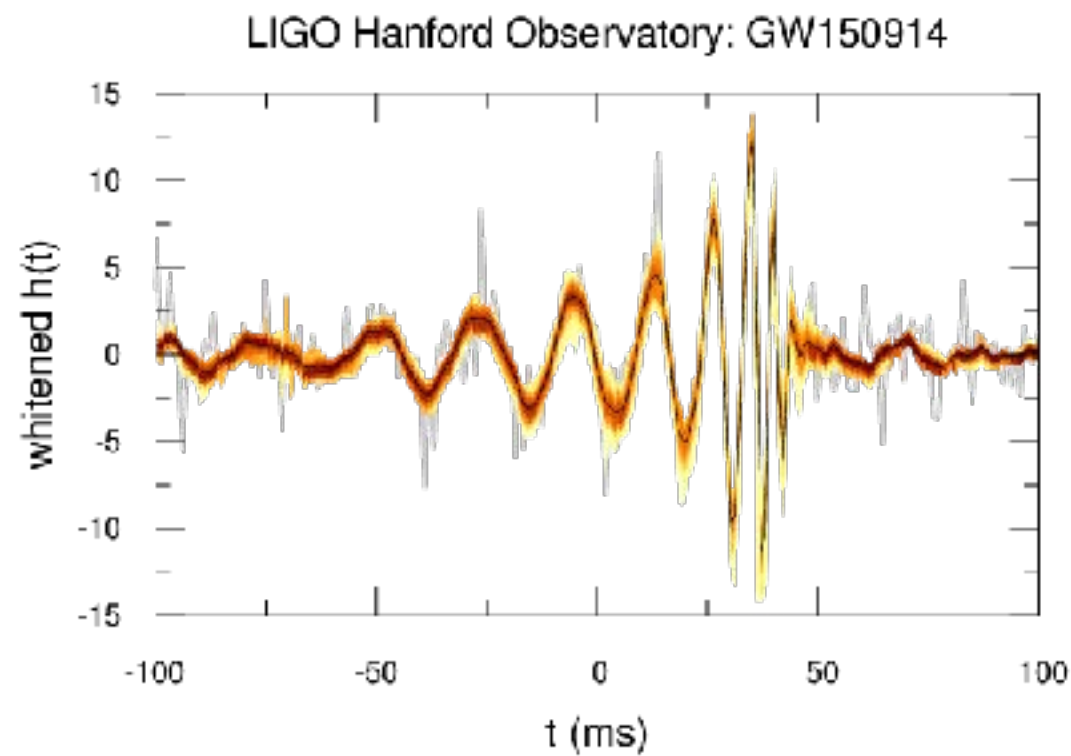
Galactic Bulge
511 keV



Galactic Plane
1809 keV



Gravitational Wave Counterpart

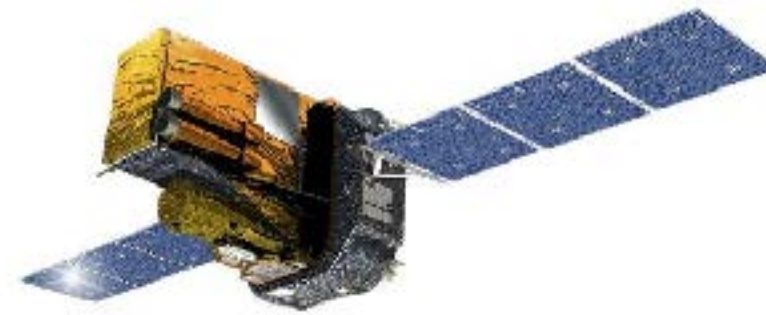


Mission Segments

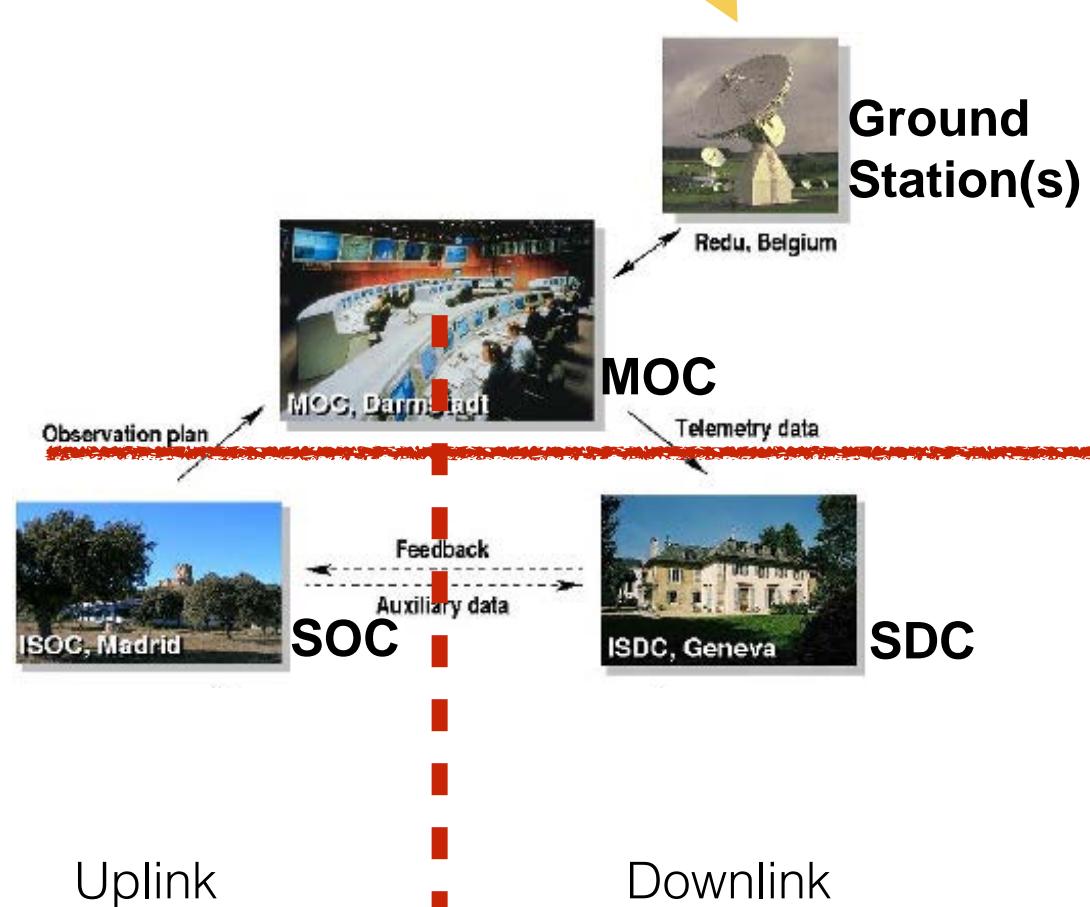
Launch segment



Flight segment



Ground segment



Operation Ground Segment

Science Ground Segment

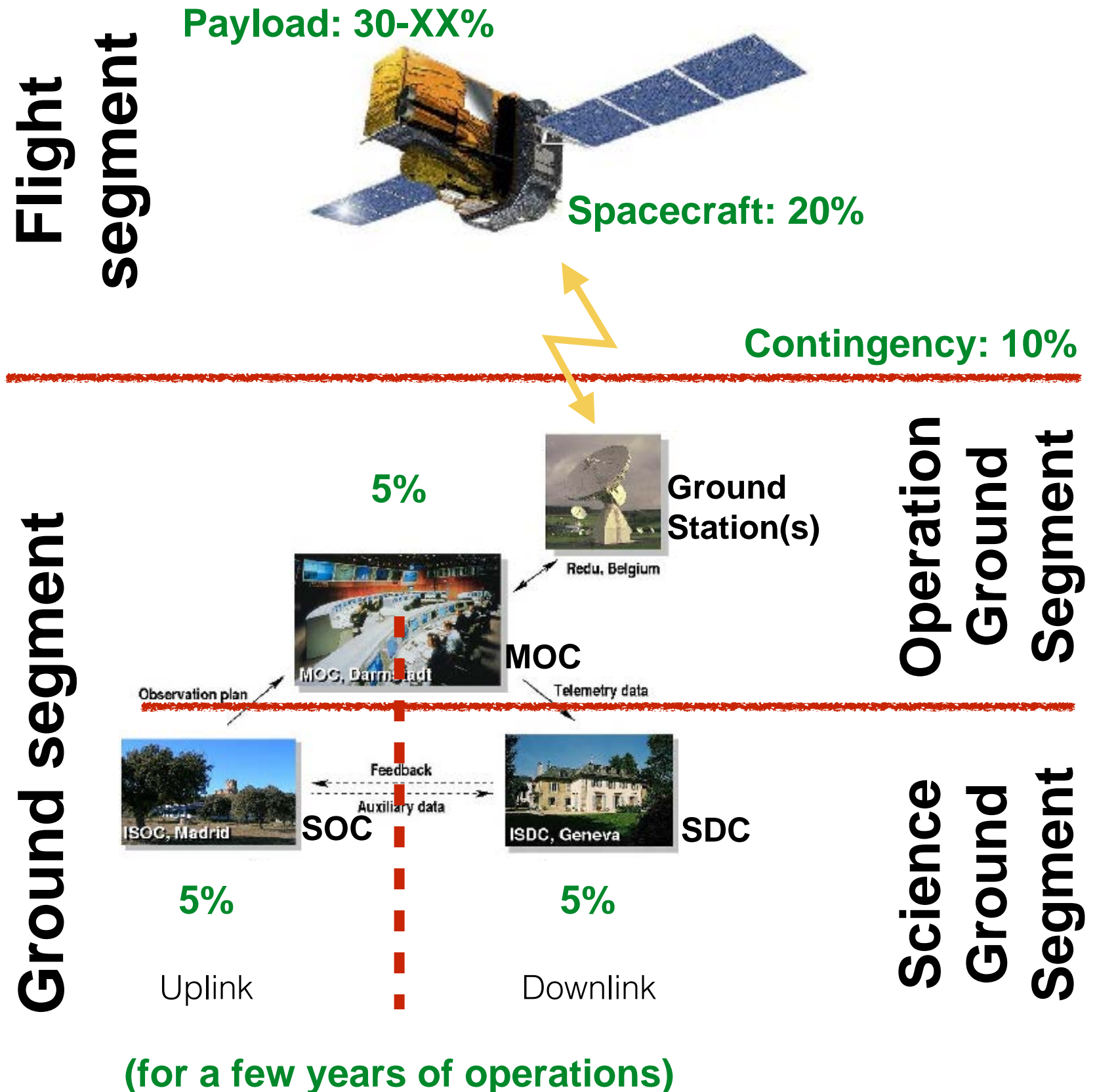
Program segment

Mission Segments

Launch segment 10-15%



Program segment 10%



Science Ground Segment

Main tasks:

- Science mission planning and scheduling

Observation Proposals

Planning Files

- Mission simulations

Simulators

Oper. Optimisation

- Science data processing

Data Products

Alerts

- Mission legacy

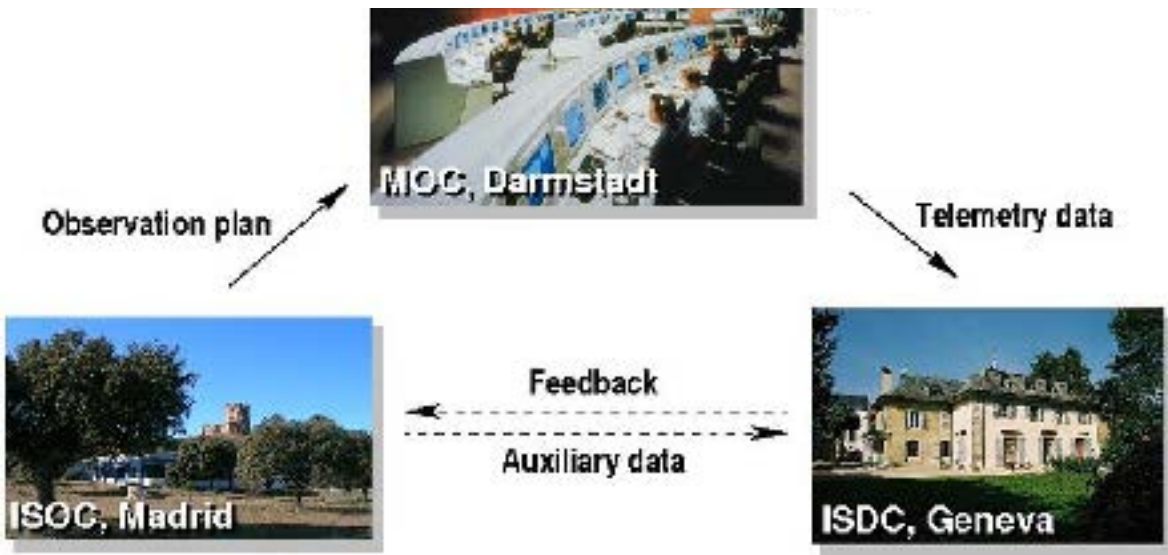
Archive

Data access

These functions can be located at one or many places

Science Ground Segment

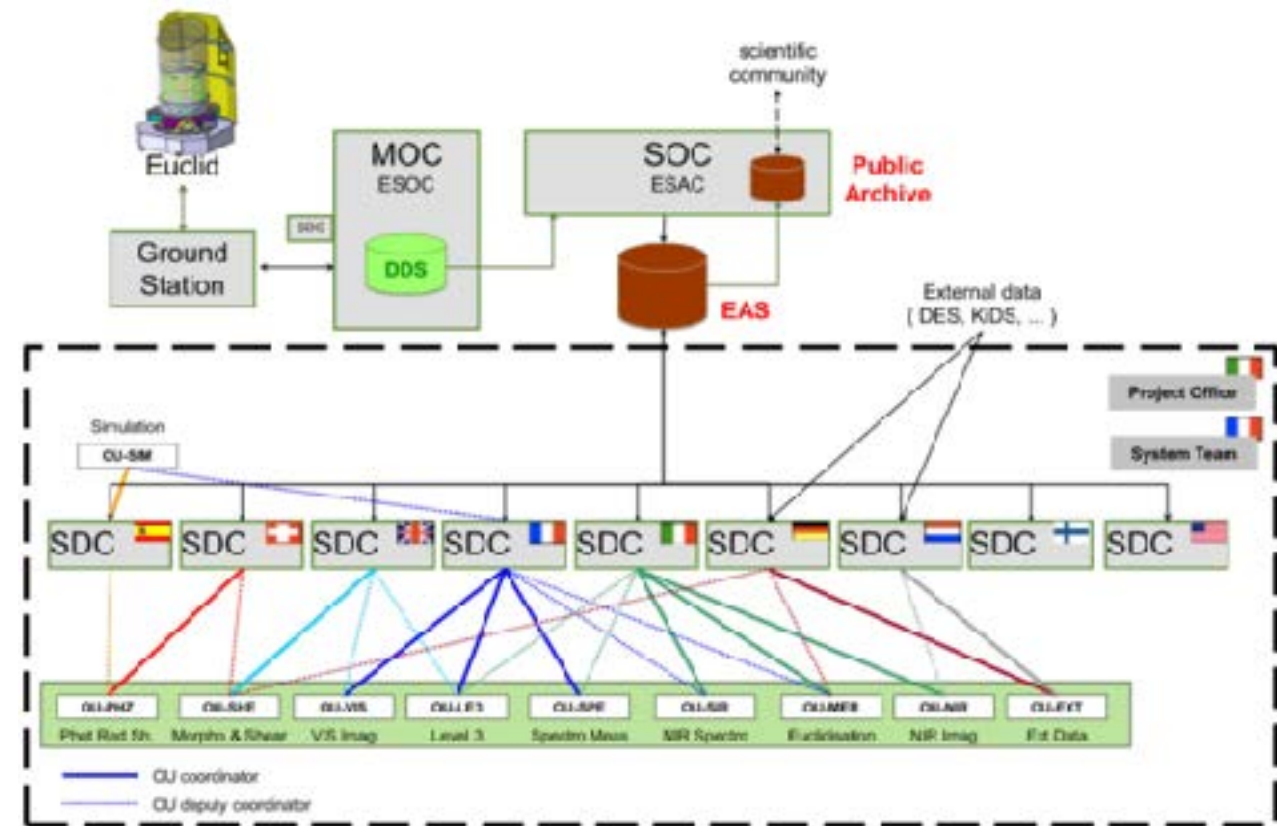
INTEGRAL



GAIA



Euclid



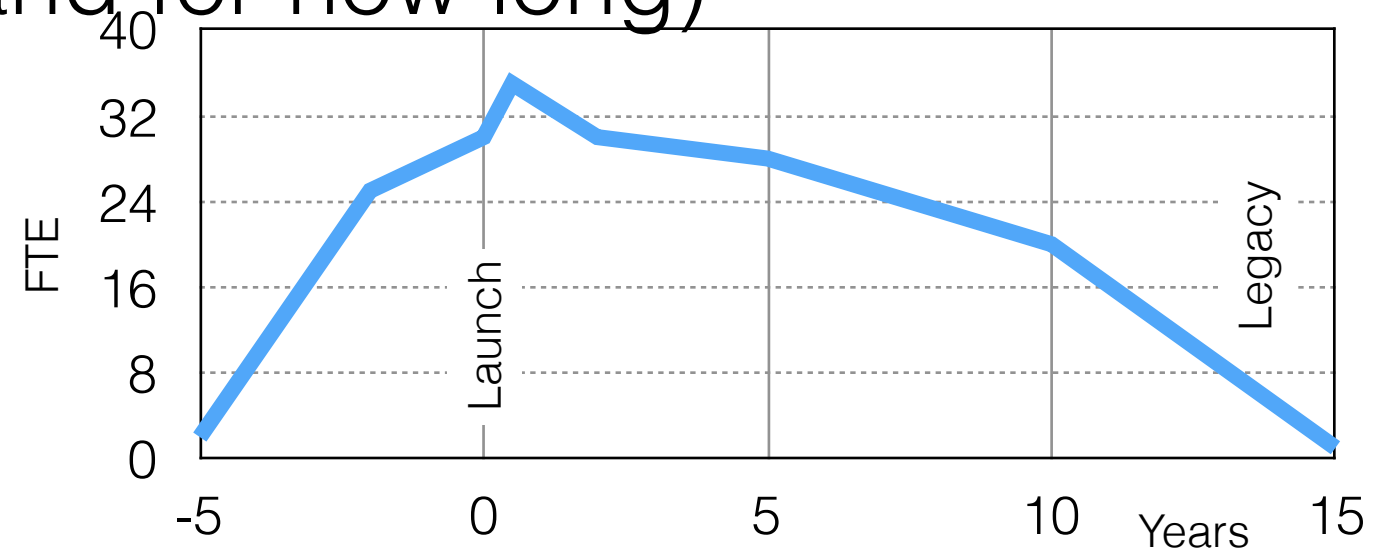
These functions can be located at one or many places
The location of the data will not matter in the future

Design Drivers

- Science
 - transient detection
 - number of detected sources/events
 - observatory/PI instrument
 - size/nature of user community
 - evolution of scientific questions
 - scientific parts in the hands of scientists
 - data rights
- Legacy
 - data and software maintenance
 - archive scientific value, at different levels
 - possibility to generate new results
 - maintaining/enhancing communities
 - value for education
 - archive fate (is there one ?)

Implementation Drivers

- Ressources (who can pay and for how long)

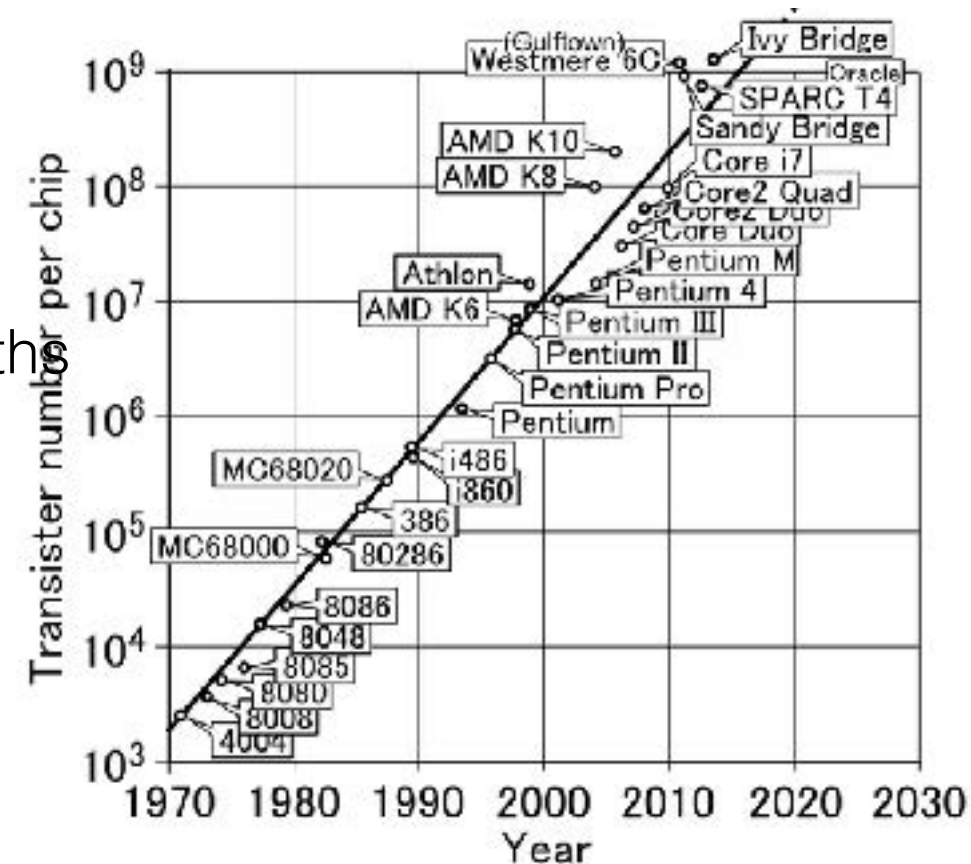


- Data size and processing power

- Moore's Law : CPU doubles every 24 months
- Kryder's Law : Disk size doubles every 12 months
- Nielsen's Law Network bandwidth doubles every 21 months
- Disk bandwidth increases by 10% every 12 months

- Unique/multi-sites

Data could be centralised



Operational Drivers

- Commanding loops
- Handling of critical situations
- Survey, pointing, repointing, orbital period
- Instrument commissioning
- Instrument stability/complex calibration
- Mission duration

Design Principles

- Architecture driven by
1. science, 2. legacy, 3. implementation, 4. operations
- Asynchronous processes, event driven
- Agreed interfaces rather than complex APIs
- KISS: Keep It Simple, Stupid
- Minimize dependencies between subsystems and components
- Do not reinvent wheels
- Distributing processing is costly
- IT development is not the goal

DATA HANDLING

Science and Drivers

Science Mission Elements

Data Handling

Development Management

Data is the Legacy

Components

- Data formats
- Data acquisition
- Data checks
- Calibration
- Scientific analysis
- Data mining
- Archiving

Data Formats

- Most astronomy mission use FITS
- FITS initially developed for optical astronomy, FITS has conventions for many domains
- FITS is the archival format recognised by the IAU
- Files can include many FITS extensions including headers, tables, N dim images
- Data processing based on files (most observatories) or partially on databases (e.g. survey missions).
- FITS files are good for **long term maintenance** of data and software
- cfitsio (FITS access library) uses template files, which are good for **interface control** and ease data model evolution
- Virtual Observatory files (e.g. XML tables) are also used for high level data
- INTEGRAL:
 - 1382 FITS data structures
 - 263 Raw data
 - 114 Corrected data
 - 202 Analysis products
 - others for calibration and responses


```
#####
#
#DATANAME GENERAL - PACKETS - TELEMETRY DATA
#
#DESCRIPTION
# Contains the FITS wrapped telemetry.
#
#TEMPLATE GNRL-PACK-TLM
#
#CONTENT BINARY TABLE
#
#REMARKS
# The PACK_NUM column can have the values 0, 1, 2 and 3.
# 0 and 2 : normal packets; 1 and 3 : time packets
# 0 and 1 : first position in frame; 2 and 3 : second position in frame
#
#RP tm
#DB No
#V1
#
#CHANGES
# 1.4 : Template creation
# 1.5 : Renamed keyword TSTART (previously MJDSTART)
#      : Renamed keyword TSTOP (previously MJDEND)
#      : Added REVOL keyword
#      : Added time system keywords
# 1.5.1 : Changed format of FRAME_HDR column to 41B
# 1.6 : Time system is now Terrestrial Time (TT)
# 2.1 : Template put under Configuration Control
# 2.3 : Added the following keywords for frame and packet statistics:
#      : FRMTM, FRMIDLE, FRMINVLD, FRMTOTAL, PKTTM, PKTTLCMD, PKTTIME, PKTIDLE,
#      : PKTINVLD and PKTTOTAL (SCREW-00217 and SCREW-00252)
# 7.1 : Added TIMEPIXR keyword (SCREW-01431)
# 9.8.3 : Changed FRAME_SEQ column format from 1V to 1K (SPR-04868)
#
#####
XTENSION  BINTABLE / Binary table extension
EXTNAME    GNRL-PACK-TLM / Extension name
EXTREL      '9.8.3' / ISDC release number
BASETYPE   DAL_TABLE / DAL base type of the data structure
TELESCOP   INTEGRAL / Telescope or mission name
ORIGIN      ISDC / Origin of FITS file
CREATOR     String / Program that created this FITS file
CONFIGUR   String / Software configuration
DATE        UTC_format / FITS file creation date
MJDREF      51544.0 / Modified Julian Date of origin
TIMESYS     TT / Time frame system
TIMEUNIT    d / Time unit
TIMEREf     LOCAL / Time reference frame
ERTFIRST    UTC_format / Earth received time of the first packet
ERTLAST     UTC_format / Earth received time of the last packet
REVOL       Integer / Revolution number
TSTART      Real / Earth received time of first packet (ISDC-JD)
TSTOP       Real / Earth received time of last packet (ISDC-JD)
FRMTM        Integer / Number of good telemetry frames
FRMIDLE      Integer / Number of idle frames, not stored
FRMINVLD     Integer / Number of invalid frames, not stored
FRMTOTAL     Integer / Total number of frames
PKTTM        Integer / Number of telemetry packets
PKTTLCMD     Integer / Number of telecommand packets
PKTTIME      Integer / Number of time (STSP) packets
PKTIDLE      Integer / Number of idle packets
PKTINVLD     Integer / Number of invalid packets
PKTTOTAL     Integer / Total number of packets
TIMEPIXR     0.5 / Relative position [0,1] of time stamp in bins
      TTYPE#  TIME / ISDC-JD time
      TFORM#  1D / Format of column TIME
      TUNIT#  d / Unit of column TIME
      TTYPE#  FRAME_SEQ / Frame sequence number
      TFORM#  1K / Format of column FRAME_SEQ
      TTYPE#  FRAME_HDR / Frame header
      TFORM#  41B / Format of column FRAME_HDR
      TTYPE#  PACK_NUM / Packet number
      TFORM#  1B / Format of column PACK_NUM
      TTYPE#  CONTENT / Packet content
      TFORM#  440B / Format of column CONTENT
```

```
#####
#
#DATANAME IBIS-ISGRI - EVENTS - RAW DATA
#
#DESCRIPTION
# Contains the raw photon-by-photon events from the IBIS-ISGRI detector.
#
#TEMPLATE ISGR-EVTS-RAW
#
#CONTENT BINARY TABLE
#
#RP scw
#DB No
#V1
#
#CHANGES
# 1.4 : Template creation
# 2.0 : Added ISDCLEVEL keyword
# 2.1.3 : Added SWBOUND keyword
# 2.3 : Changed APID value to 1348_or_1476 (previously 1348)
#      : Template put under Configuration Control
# 3.1 : Removed PLOBTSTR and PLOBTEND keywords (SPR-00570)
# 3.4 : Changed APID value to Integer (SCREW-00412)
#
#####
XTENSION      BINTABLE / Binary table extension
EXTNAME        ISGR-EVTS-RAW / Extension name
EXTREL         '3.4' / ISDC release number
BASETYPE       DAL_TABLE / Data Access Layer base type
TELESCOP       INTEGRAL / Telescope or mission name
ORIGIN         ISDC / Origin of FITS file
INSTRUME       IBIS / Instrument name
DETNAM         ISGRI / Name of the detector layer
ISDCLEVEL      RAW / ISDC level of data processing
CREATOR        String / Program that created this FITS file
CONFIGUR       String / Software configuration
DATE           UTC_format / FITS file creation date
ERTFIRSTUTC    UTC_format / Earth received time of the first packet
ERTLAST        UTC_format / Earth received time of the last packet
REVOL          Integer / Revolution number
SWID           String / Science Window identifier
SW_TYPE        String / Type of the Science Window
SWBOUND        String / Reason for Science Window ending
BCPPID         String / Broadcast packet pointing ID at ScW start
PREVSWID       String / Identification of the previous Science Window
PCKSTART       Integer / Packet time of the start of the Science Window
PCKEND         Integer / Packet time of the end of the Science Window
APID           Integer / Application process identifier (1348 or 1476)
SSC_BEG        Integer / Source sequence count start
SSC_END        Integer / Source sequence count end
SSC_GAP        Integer / Number of missing packets
      TTYPE#  DELTA_TIME / Delta time to previous event
      TFORM#  1B / Format of column DELTA_TIME
      TTYPE#  RISE_TIME / Event rise time
      TFORM#  1B / Format of column RISE_TIME
      TTYPE#  ISGRI_PHA / Pulse height in the ISGRI layer
      TFORM#  1U / Format of column ISGRI_PHA
      TTYPE#  ISGRI_Y / Y location in the ISGRI layer
      TFORM#  1B / Format of column ISGRI_Y
      TTYPE#  ISGRI_Z / Z location in the ISGRI layer
      TFORM#  1B / Format of column ISGRI_Z
```

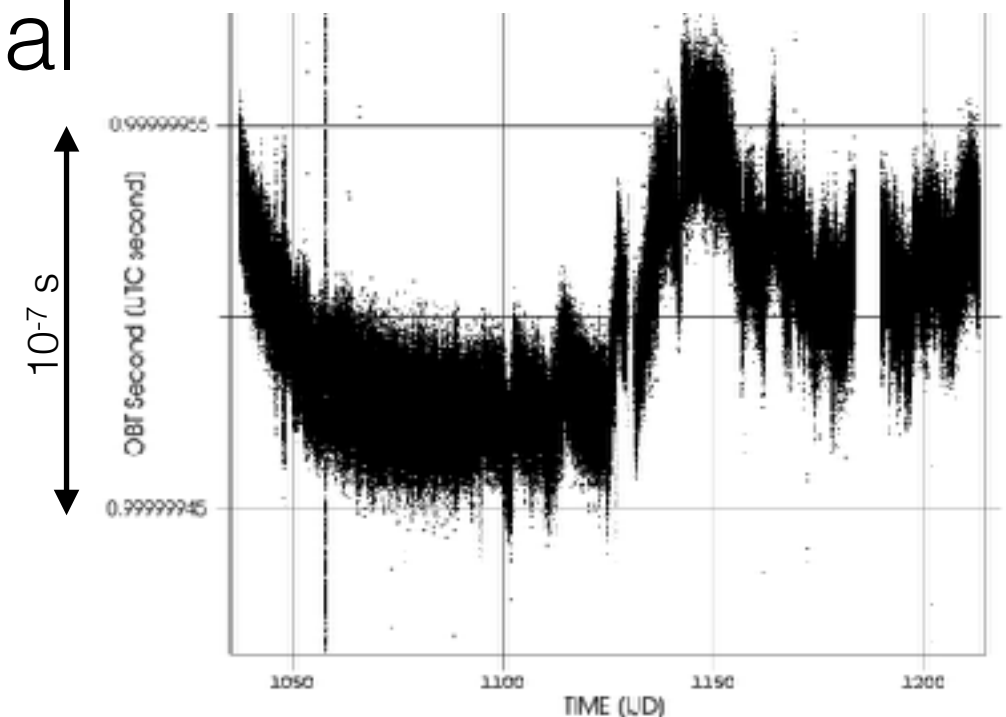
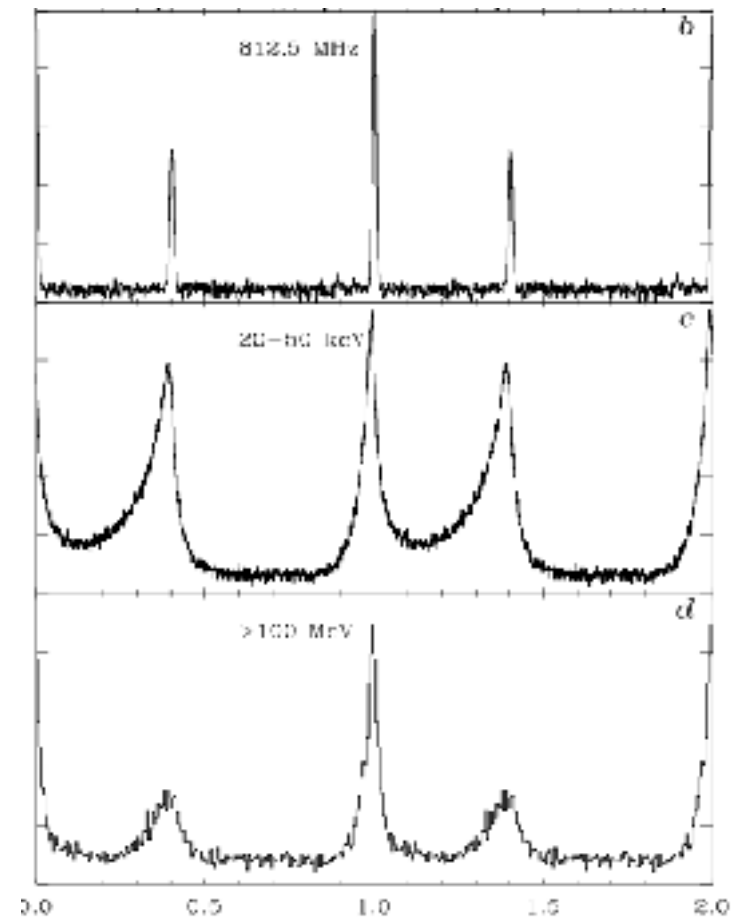


```
#####
#
#DATANAME IBIS-ISGRI - SKY - IMAGE
#
#DESCRIPTION
# Contains the IBIS-ISGRI sky image obtained for a single Science Window,
# for a given energy band and a given time span.
#
#TEMPLATE ISGR-SKY.-IMA
#
#CONTENT IMAGE
#DATADEF : Image pixel value
#AXDEF 1 : Phi angle (CAR) or X coordinate (TAN)
#AXDEF 2 : Theta angle (CAR) or Y coordinate (TAN)
#
#REMARKS
# This data structure can store either a cartesian (CAR) or a tangential (TAN)
# projection of the celestial sphere. The coordinate system is specific to this
# data structure. The standard keywords defined in this data structure provide
# all information require to compute RA and DEC (or GLON GLAT, or ELON ELAT)
# of any pixel.
#.
# This data structure has been defined according to the standard representations
# of celestial coordinates in FITS proposed by Greisen and Calabretta (AA,
# preprint)
#.
# The IMATYPE keyword can have the following values:
# INTENSITY, VARIANCE, RESIDUAL or SIGNIFICANCE
#.
# The UTC format is YYYY-MM-DDTHH:MM:SS
#
#RP obs/scw
#DB No
#V2
#
#CHANGES
# 2.0.1 : Template creation
# 2.0.2 : Removed the four PC00i00i (i=1,2) keywords
# 2.0.3 : Removed the LONGPOLE and LATPOLE keywords
# 2.1   : Set BUNIT value to count/s/cm**2
# 2.1.1 : Replaced CDEL1,CDEL2 and CROTA2 keywords
#       : by the CD1_1, CD1_2, CD2_1 and CD2_2 keywords
#       : Renamed DATE-END keyword (previously DATE_END)
#       : Temporarily changed BUNIT value from count/s/cm**2 to count/s
#       : Changed possible IMATYPE value from ERROR to VARIANCE
# 2.1.3 : Set the 4 CDi_i (i=1,2) to their default value
# 2.2   : Removed EXPID keyword
#       : Added ONTIME, DEADC and EXPOSURE keywords
#       : Changed HDUVERS value from 1.0 to 3.0
#       : Put back the LONGPOLE and LATPOLE keywords
# 2.3   : Added SWBOUND keyword
# 3.4.2 : Added TFIRST and TLAST keywords
#       : Removed DATE-OBS and DATE-END keywords
# 4.8   : Changed BUNIT value from count/s to String
#       : Changed CD1_1, CD1_2, CD2_1, CD2_2 values to Real (SCREW-00642)
# 4.9   : Template put under Configuration Control
# 6.5   : Changed HDUVERS keyword value to '1.1.0' (SPR-02602)
#
#####
XTENSION IMAGE          / Image extension
BITPIX                 -32          / IEEE 32-bit floating point values
NAXIS                   2          / Number of data axes
NAXIS1                  Integer     / Length of data axis 1
NAXIS2                  Integer     / Length of data axis 2
```

EXTNAME	ISGR-SKY.-IMA	/ Extension name
EXTREL	'6.5'	/ ISDC release number
BASETYPE DAL_ARRAY		/ Data Access Layer base type
TELESCOPINTEGRAL		/ Telescope or mission name
ORIGIN	ISDC	/ Origin of FITS file
INSTRUME IBIS		/ Instrument name
DETNAM	ISGRI	/ Name of the detector layer
ISDCLEVL IMA		/ ISDC level of data processing
CREATOR	String	/ Program that created this FITS file
CONFIGUR	String	/ Software configuration
DATE	UTC_format	/ FITS file creation date
MJDREF	51544.0	/ Modified Julian Date of time origin
TIMESYS	TT	/ Time frame system
TIMEUNIT d		/ Time unit
TIMEREf	LOCAL	/ Time reference frame
REVOL	Integer	/ Revolution number
SWID	String	/ Science Window identifier
SW_TYPE	String	/ Type of the Science Window
SWBOUND	String	/ Reason for Science Window ending
OBTSTART OBT_format		/ OBT of the start of the Science Window
OBTEND	OBT_format	/ OBT of the end of the Science Window
TSTART	Real	/ Start time of the Science Window
TSTOP	Real	/ End time of the Science Window
TFIRST	Real	/ Time of the first data element
TLAST	Real	/ Time of the last data element
TELAPSE	Real	/ [s] Total elapsed time of the data
ONTIME	Real	/ [s] Sum of good time intervals
DEADC	Real	/ Dead-time correction factor
EXPOSURE	Real	/ [s] Effective exposure time
BSCALE	1	/ Real value=value*BSCALE + BZERO
BZERO	0	/ Offset applied to true pixel values
BUNIT	String	/ Unit for pixel values
CTYPE1	String	/ LONGPROJ where LONG can be RA, GLON, ELON and PROJ can be CAR, TAN or AIT
CRPIX1	Real	/ Pixel at reference point
CRVAL1	Real	/ LONG at the reference value
CUNIT1	deg	/ Physical units of axis 1
CTYPE2	String	/ LAT-PROJ where LAT can be DEC, GLAT, ELAT and PROJ can be CAR, TAN or AIT
CRPIX2	Real	/ Pixel at reference point
CRVAL2	Real	/ LAT at the reference value
CUNIT2	deg	/ Physical units of axis 2
CD1_1	Real	/ Element (1,1) of coordinate transf. matrix (default 1)
CD1_2	Real	/ Element (1,2) of coordinate transf. matrix (default 0)
CD2_1	Real	/ Element (2,1) of coordinate transf. matrix (default 0)
CD2_2	Real	/ Element (2,2) of coordinate transf. matrix (default 1)
LONGPOLE	180	/ Longitude in the native coord. system of the std system's N pole
LATPOLE	0	/ Latitude in the native coord. system of the std system's N pole
RADECSYS	FK5	/ Stellar reference frame
EQUINOX	2000.0	/ Coordinate system equinox
HDUCLASS	OGIP	/ Format conforms mostly to OGIP standards
HDUDOC	'ISDC-IBIS ICD'	/ Document in which the format is defined
HDUVERS	'1.1.0'	/ Version of format
HDUCLAS1	IMAGE	/ Dataset contains a sky image
CHANTYPE	PI	/ Type of detector channels
CHANMIN	Integer	/ Lowest channel of the energy range
CHANMAX	Integer	/ Highest channel of the energy range
E_MIN	Real	/ [keV] Lower energy limit
E_MEAN	Real	/ [keV] Mean energy
E_MAX	Real	/ [keV] Upper energy limit
IMATYPE	String	/ Type of image

Data Conventions: e.g. Timing

- On-board (clock) time: kept everywhere with full resolution ($1\mu\text{s}$), including clock resets. Synchronisation of instruments and spacecraft.
- MJD in terrestrial time (based on atomic clock, no leap second). Bijective translation to on-board time (includes on-board clock synchronisation, thermal effects, propagation time).
- Earth time in UTC

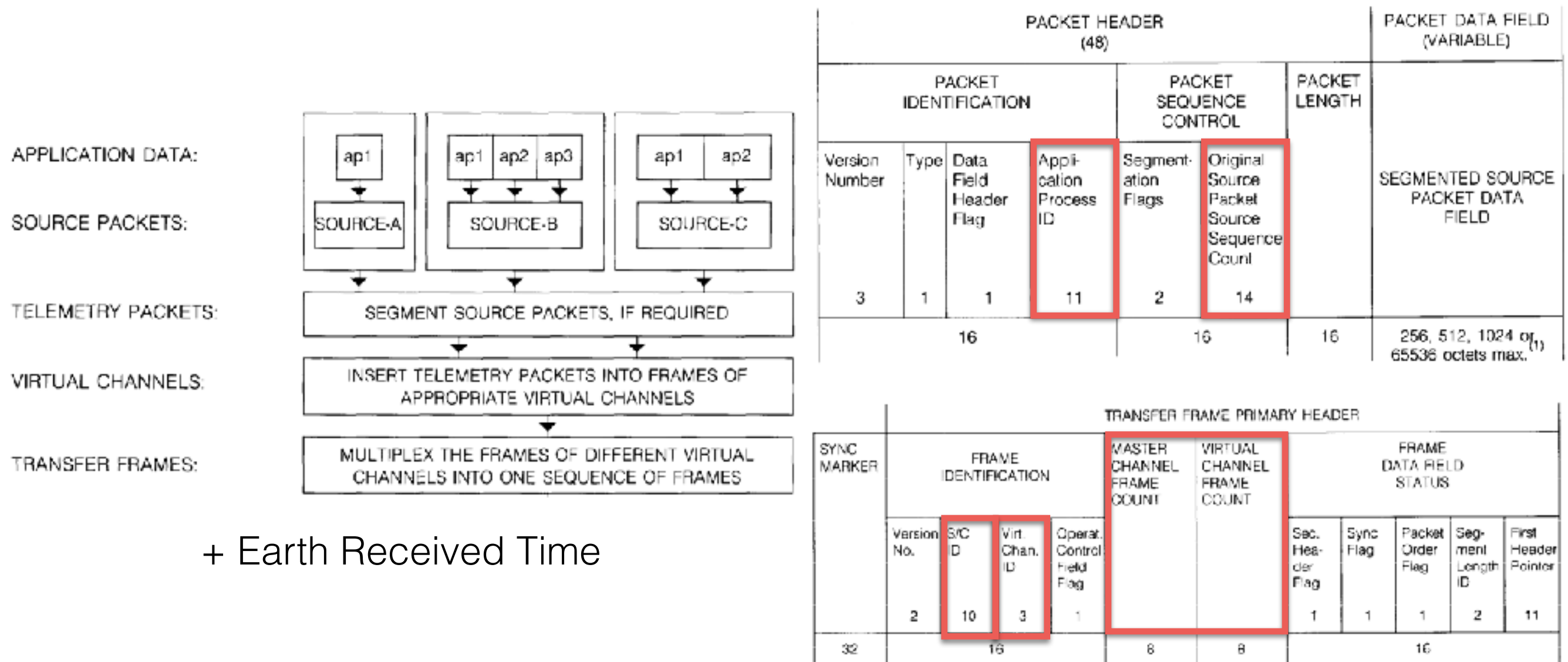


Data Acquisition

- Spacecraft (or Instrument) Telemetry
 - Packet Telemetry Standard (CCSDS 102.0-B-2 = PSS-04-106)
CCSDS=Consultative Committee for Space Data Systems
- Auxiliary data
 - Star tracker attitude file (planned/snapshot/historic)
 - Orbit file (planned/historic)
 - Time Correlation
 - Telecommand histories
 - Timeline (planned/historic)

Telemetry Frames and Packets

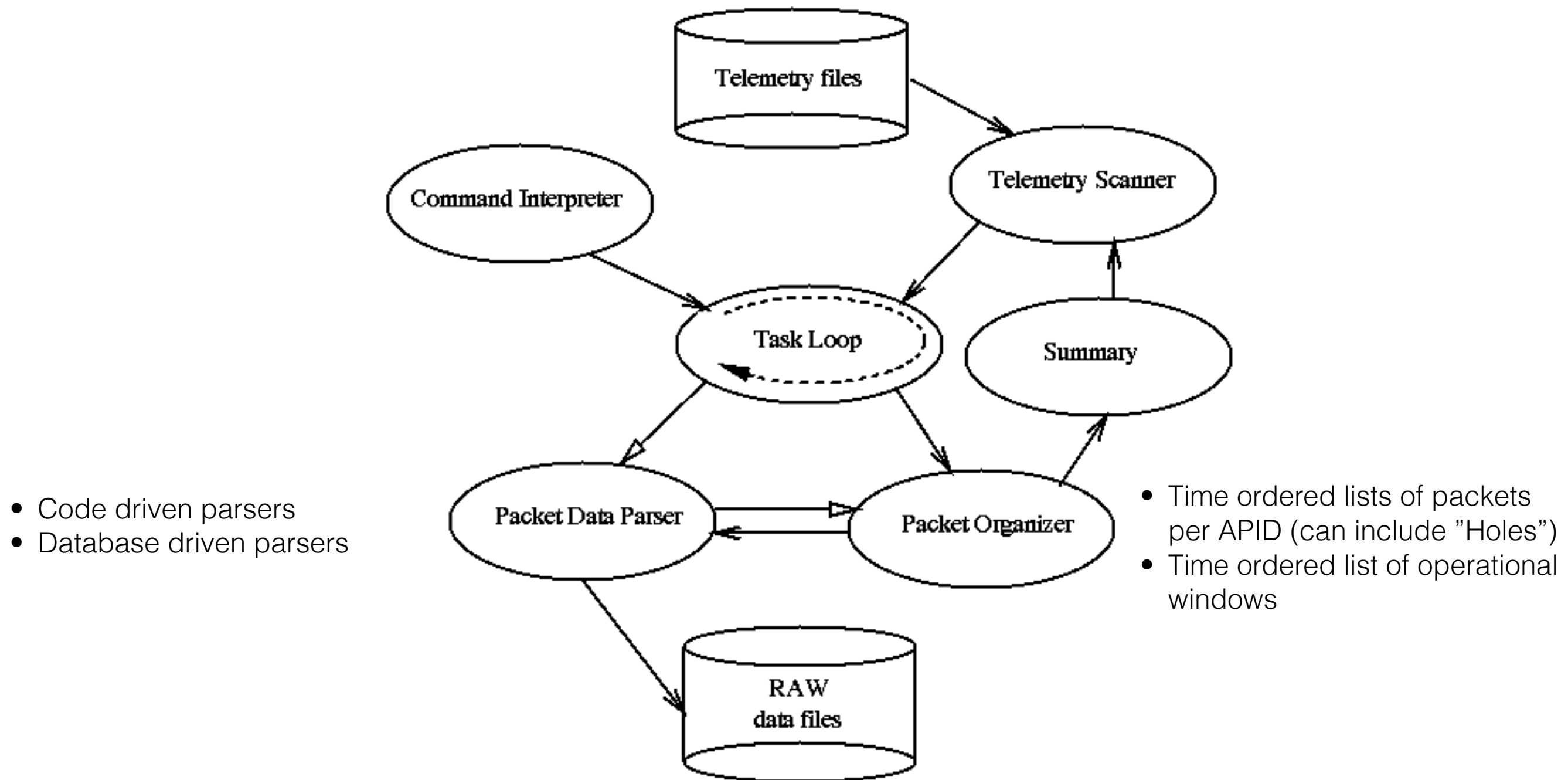
CCSDS 102.0-B-2



Need to take care of duplication/out-of-sequence/missing frames

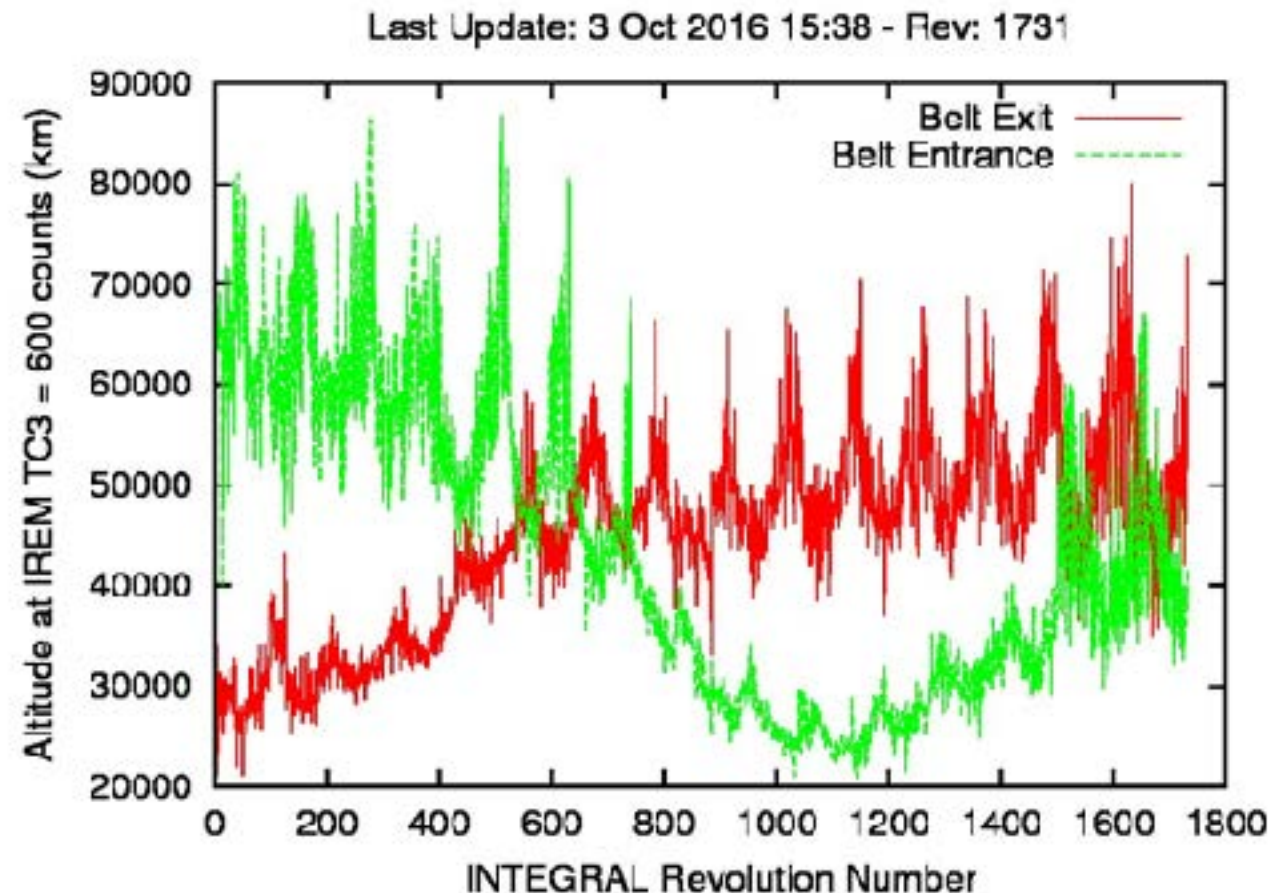
Telemetry Conversion

INTEGRAL: 263 different raw data structures



Data Checks

- Check as much as you can !
- Check data acquisition and consistency in real time
- Check instrument health (hk, although a Mission operation center responsibility)
- Check science data quality (not performed by mission operations), especially if related to operations



Calibration and Reduction

- Calibration changes with time and version (two axis)
- Calibration will be done many times and might need to be done by the end-user
- On-the-fly calibration has many advantages:
 - no need to store calibrated and reduced data
 - no need for reprocessing, always the best calibration
 - applying calibration is usually faster than reading dataand one drawback: the software need to be maintained
- If needed, consider storing only reduced data

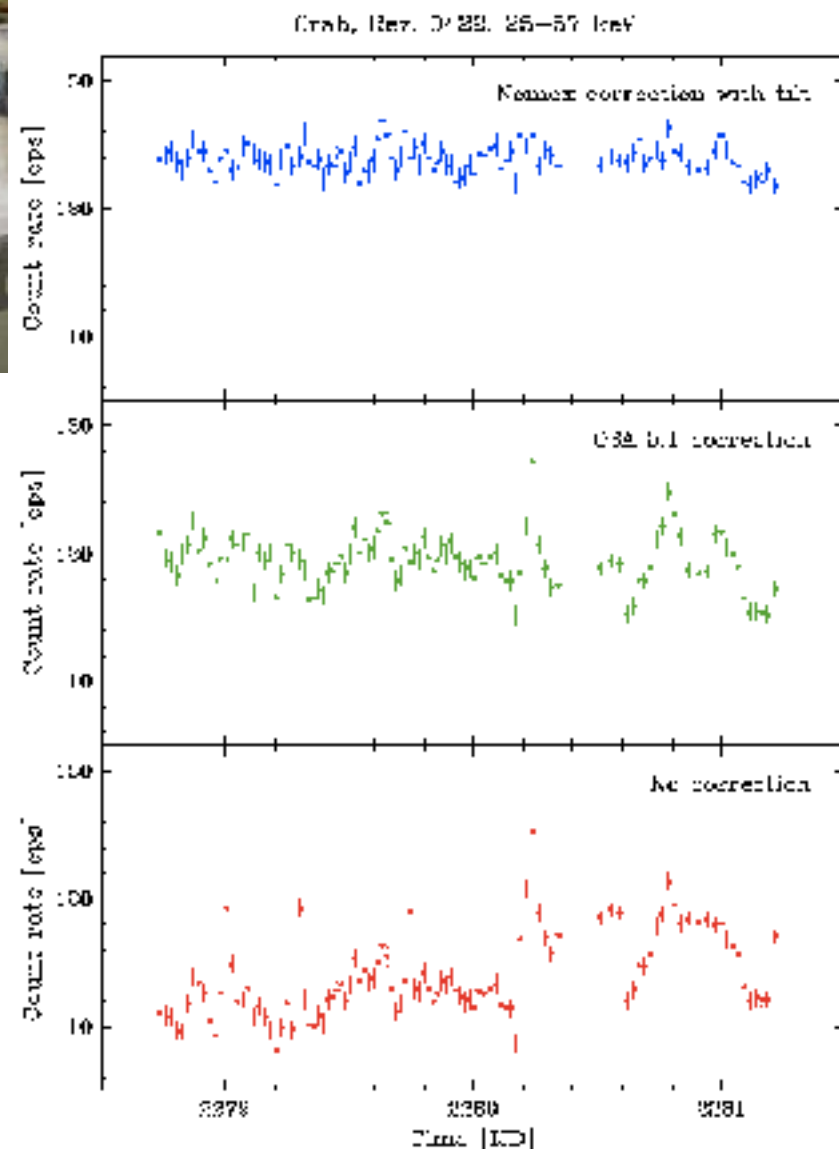
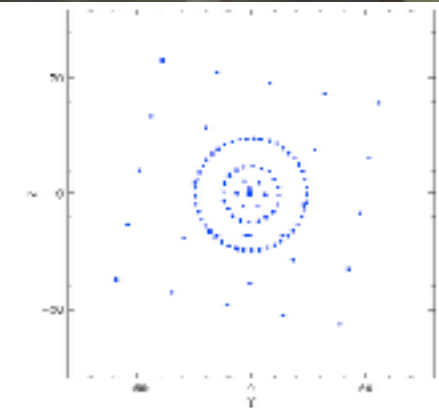
Scientific Analysis

- Quick-look:
 - search exceptional events on-line
 - verify that the data are good enough for the analysis to run
- Standard:
 - based on consolidated TM and historic auxiliary information
 - deliver the best (?) products to the observer
- Off-line:
 - performed by the scientist at home

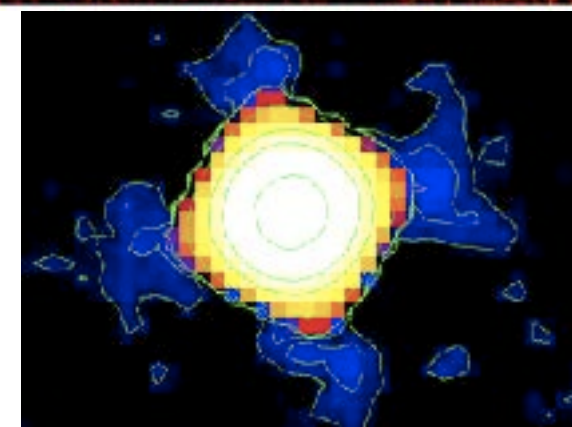
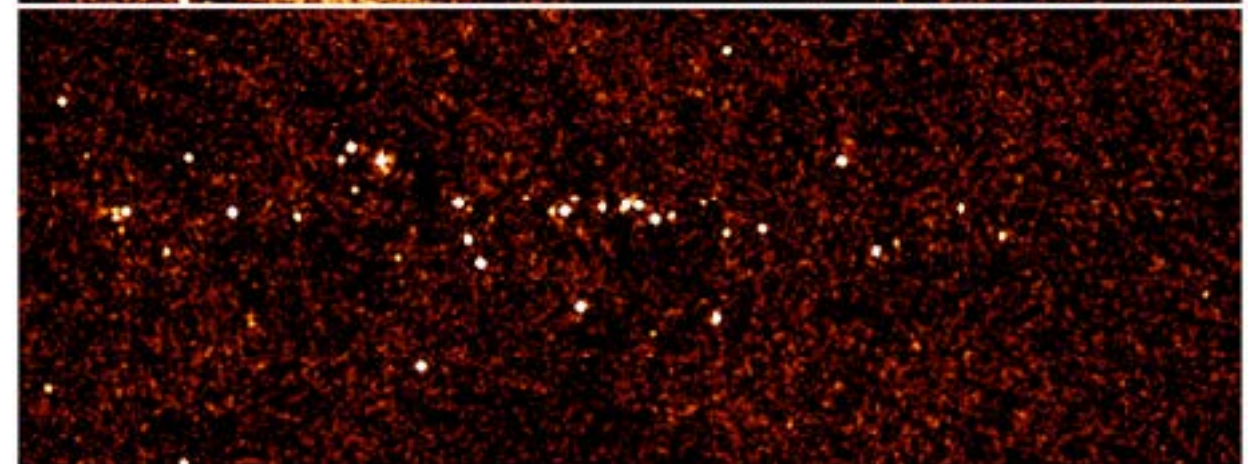
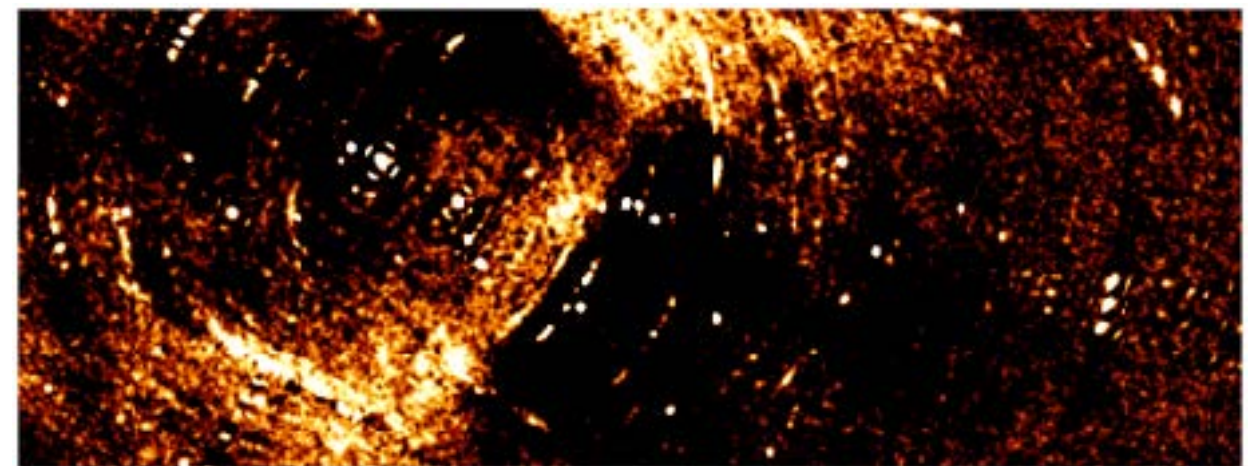
Hopefully based on exactly the same software

Calibration: an example

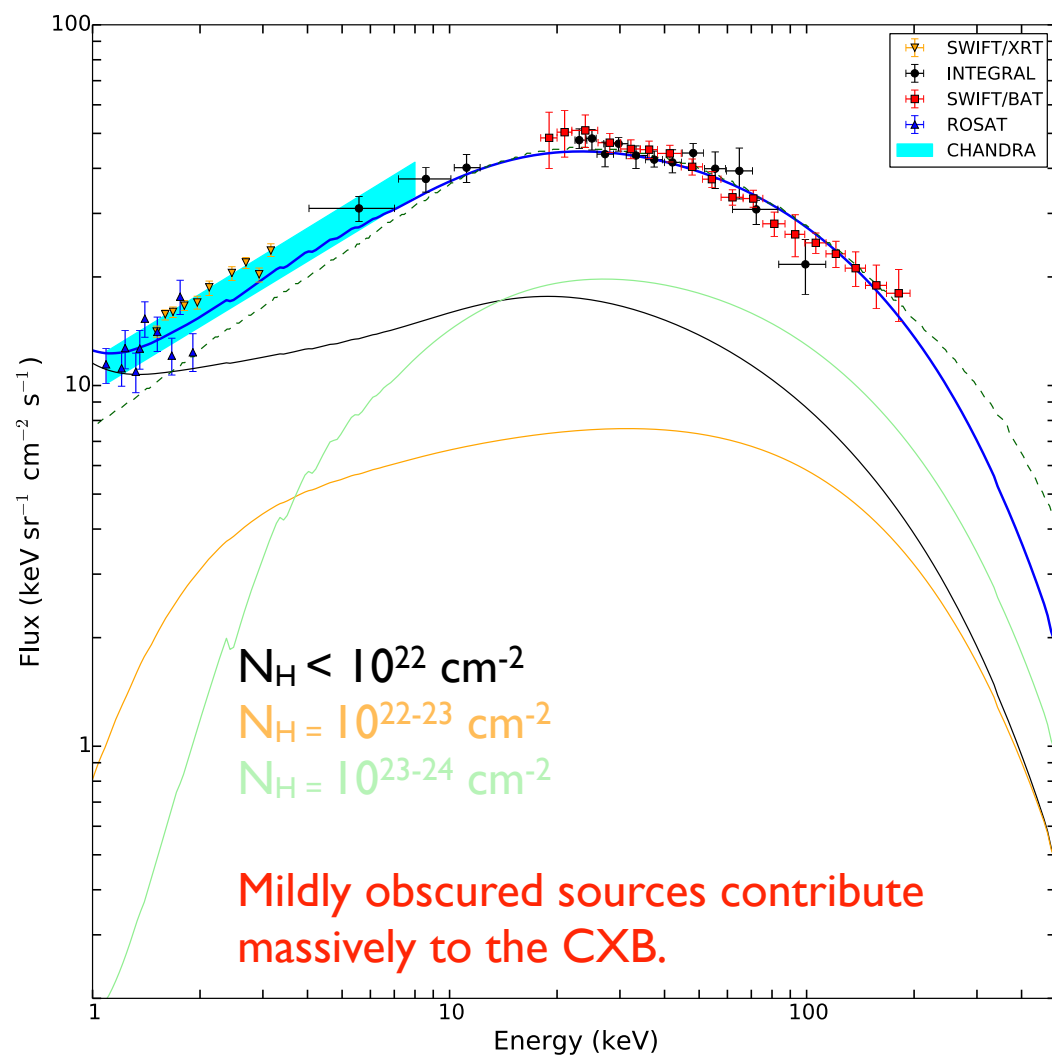
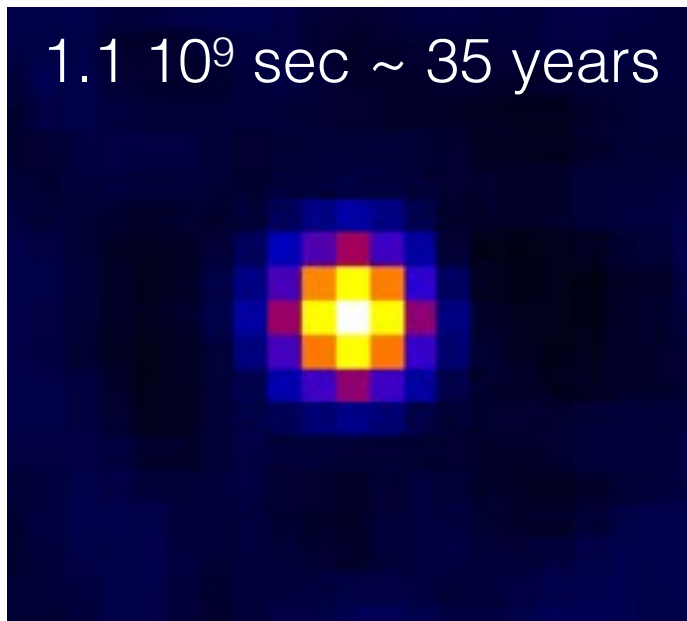
- Detector and mask alignment vs star tracker + thermal deformations
Current systematics: **14''**
- Nomex geometrical model. Current systematics on flux measurement: **1-2%**



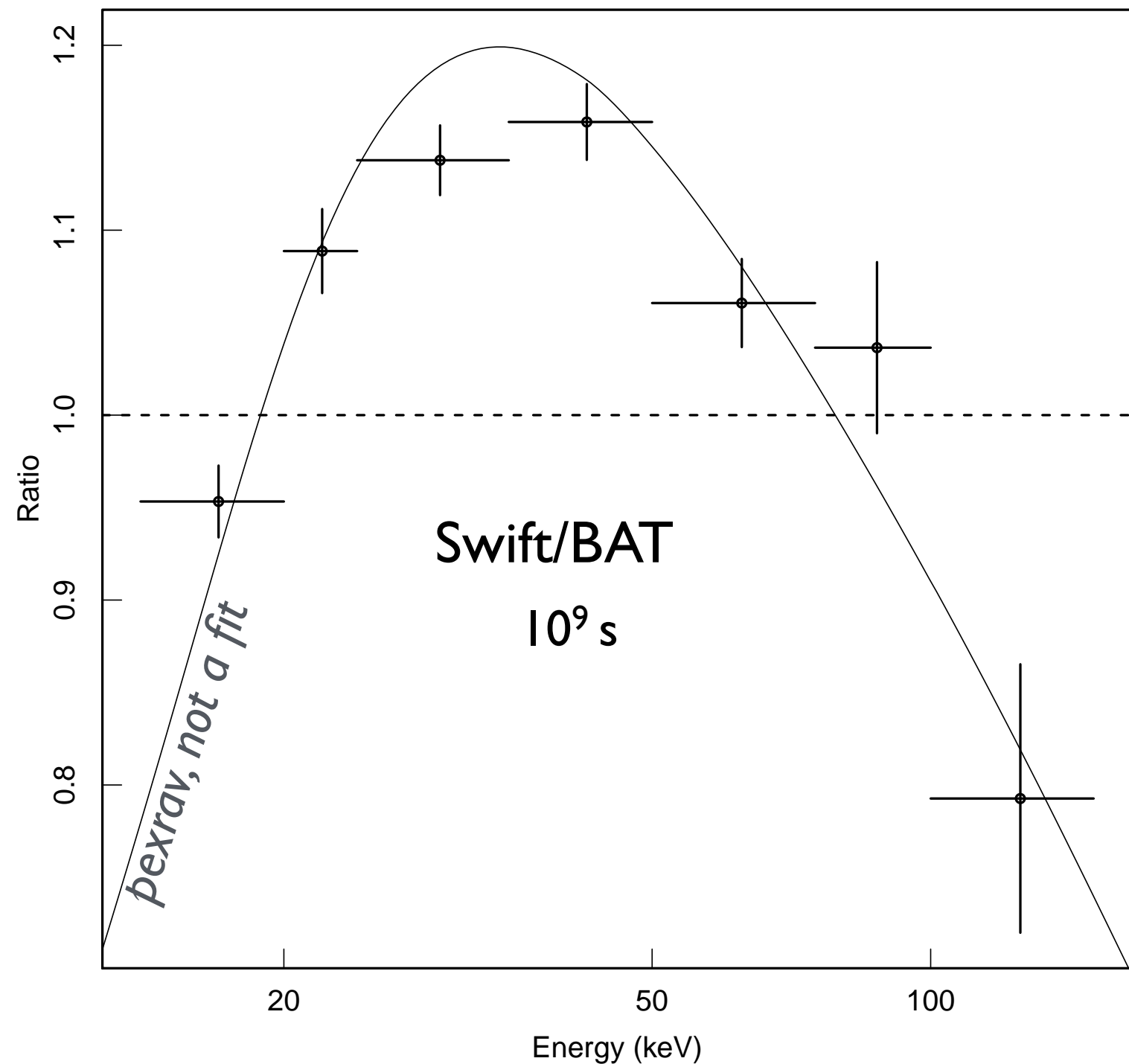
- Image defects related to insufficient instrument modeling. Systematic error on the PSF: **1%** limits usable exposure to 2Msec in the vicinity of bright sources



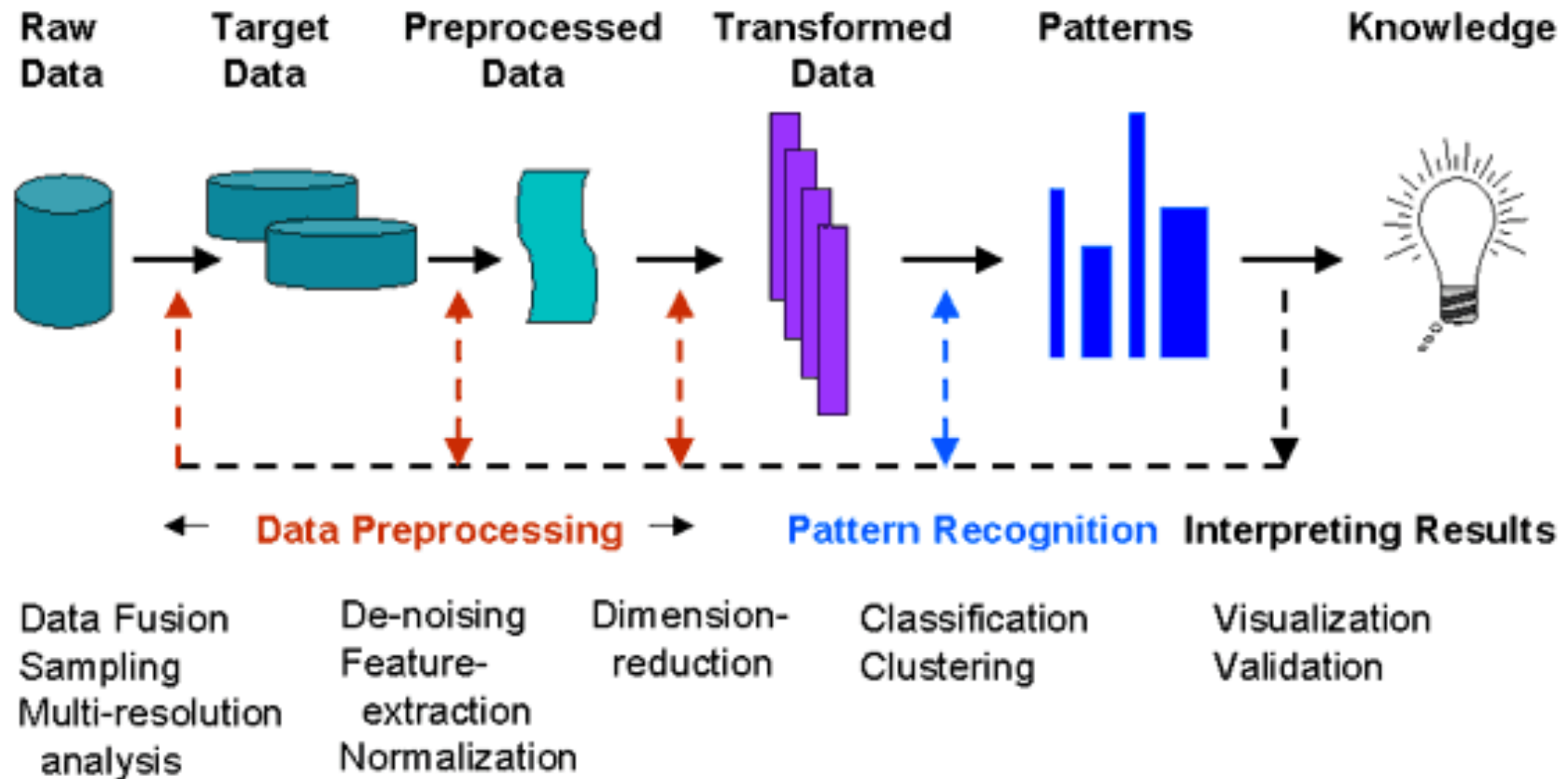
Amazing coded masks



Seyfert 2 : $10^{23-24} \text{ cm}^{-2}$ / $10^{22-23} \text{ cm}^{-2}$
(model & calibration independent)



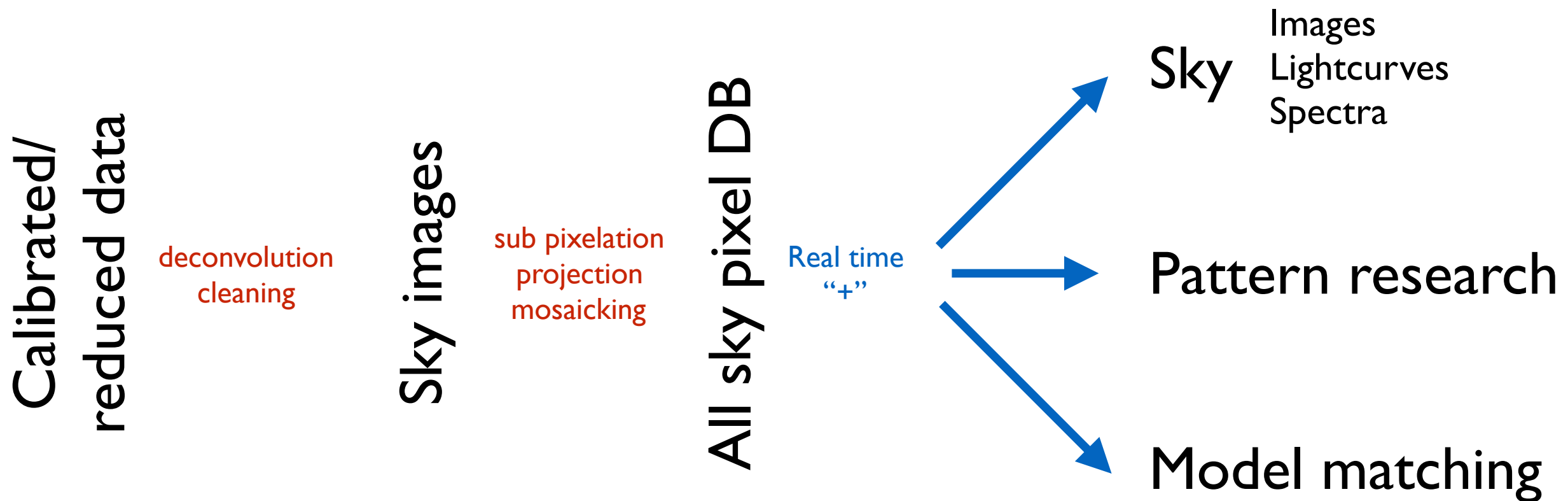
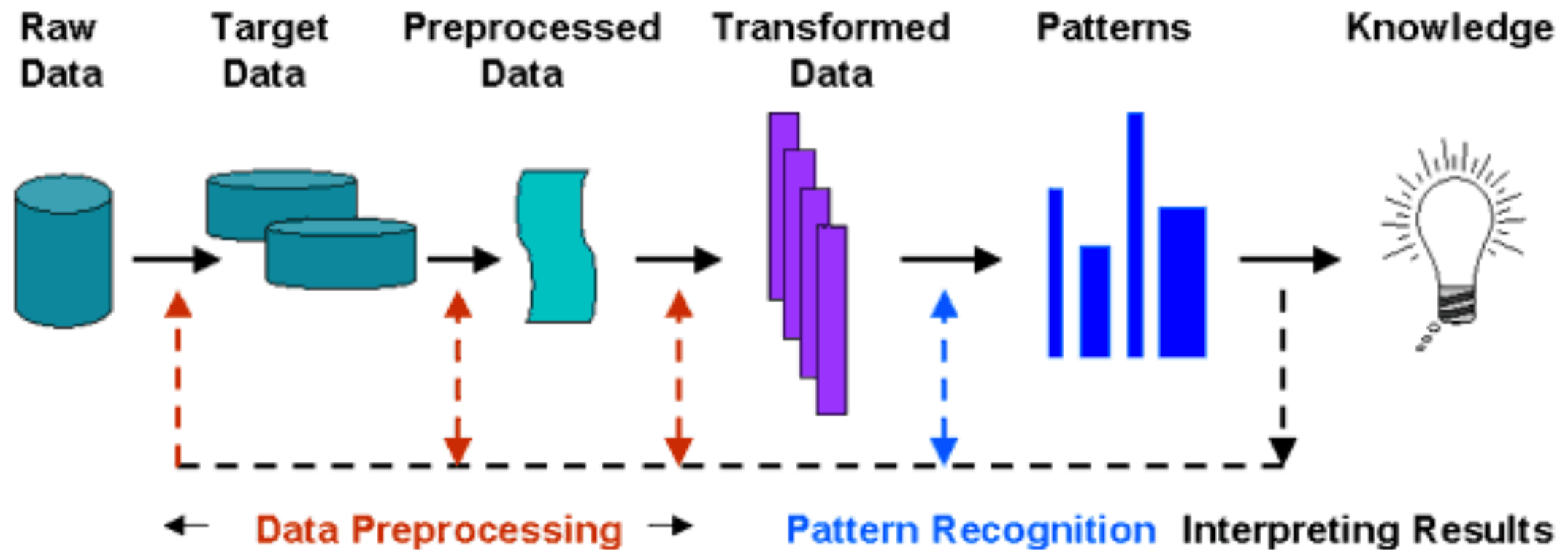
Data Mining



An iterative and interactive process

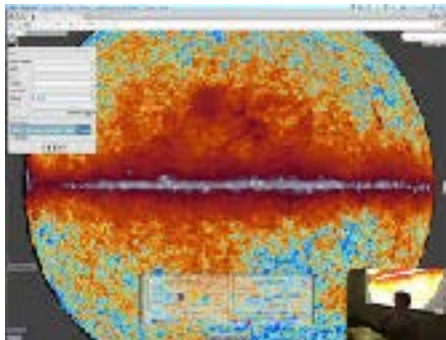
Driven by the needs of science

Data Mining

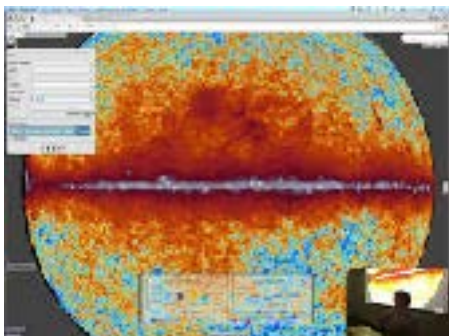


Redesigning Data Management

2020?



1985



Requires a merging of archive, pipeline & interpretation
This is a dynamic system, driven by science

Impact on Scientific Operations

Data mining can be used everywhere:

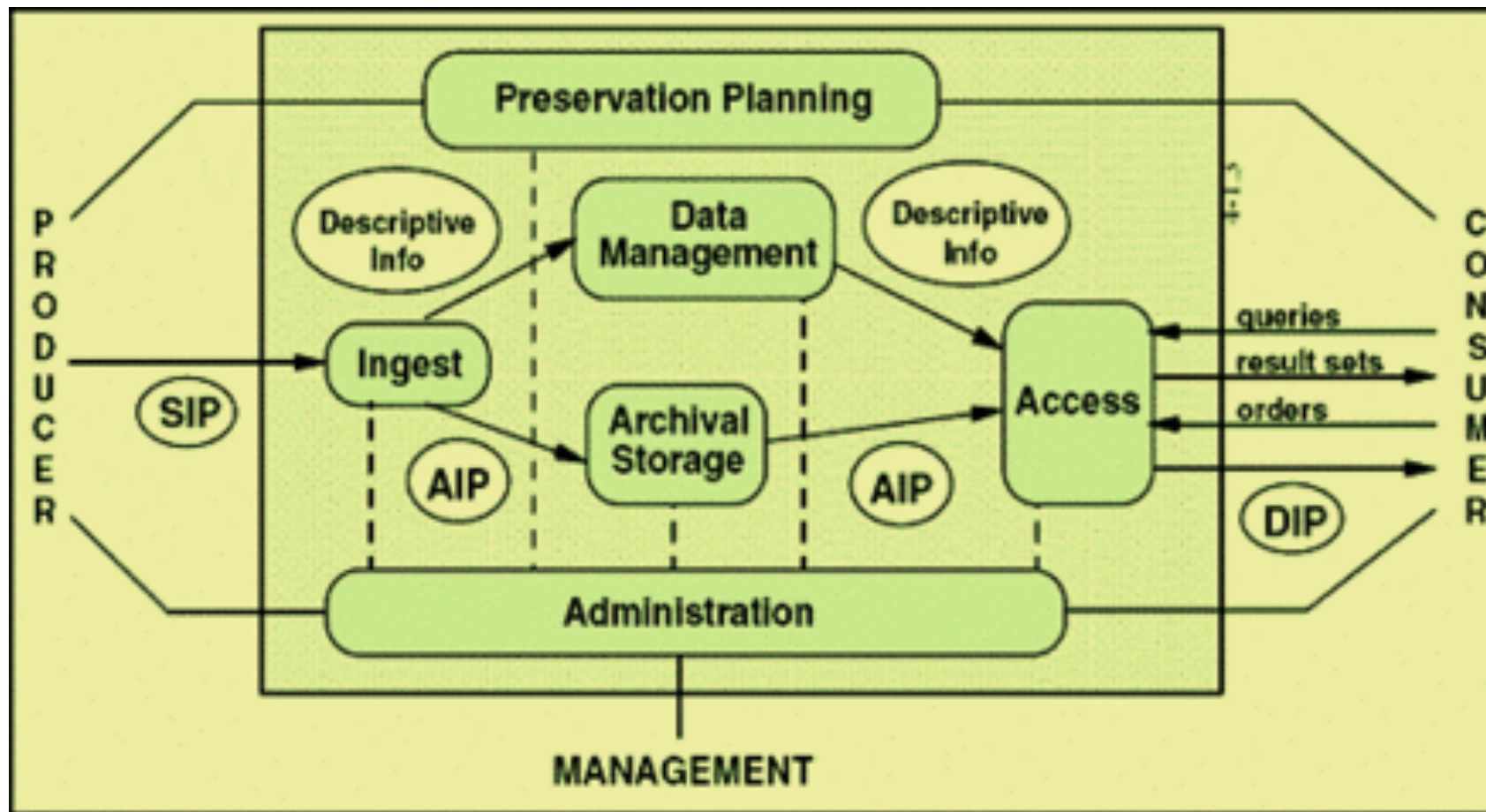
- **Product generation** (not “standard analysis” !)
- **Quick-look analysis** can be performed in real time by observers, instr. teams and the world

Distributed services can be offered/maintained by various partners and can be moved

More flexibility and potentiality does not mean more cost

Open Archival Information System

CCSDS 650.0-B-1 = ISO 14721:2012



- **Ingest**: products verification and metadata extraction
- **Archival Storage**: product storage and maintenance
- **Data Management**: metadata handling and storage
- **Access**: user interface and data retrieval
- **Administration**: manage daily operations (e.g. data rights)
- **Preservation Planning**: long term plans, migration, preservation

DEVELOPMENT MANAGEMENT

Software Engineering Standards

European Cooperation for Space Standardisation

ECSS-E-40 / PSS-05

ESA's Board for Software Standardisation and Control

mandatory for all software delivered to ESA

Software Life Cycle
Development Phases
Project Management

The standards seems heavy but can be tailored as a function of

- number of people required to develop, operate and maintain the software;
- number of potential users of the software;
- amount of software that has to be produced;
- criticality of the software, as measured by the consequences of its failure;
- complexity of the software, as measured by the number of interfaces or a similar metric;
- completeness and stability of the user requirements;
- risk values included with the user requirements.

Software is Part of a System

- **Software is frequently part of a larger system.** In this situation a number of activities will already have been performed at 'system level' before the life cycle for any software part of the system can start;
- It is a 'systems engineering' function to define the overall requirements for the system to be built. A **decomposition into subsystems** is performed with resulting subsystem specifications. Once the need for a software item has been established, its life cycle can begin.
- The responsibilities for the production and change control of the **User Requirement Document** should be agreed between 'system' and 'software' project management. The URD should be traceable to the system and/or subsystem documentation.

Software Development Phases

- 1. User Requirement phase**
- 2. Software Requirement phase**
- 3. Architectural Design phase**
- 4. Detailed Design Phase**
5. Transfer phase
6. Operation and maintenance phase

The first four phases end with formal reviews, the last two with test reports.

Software Development Phases

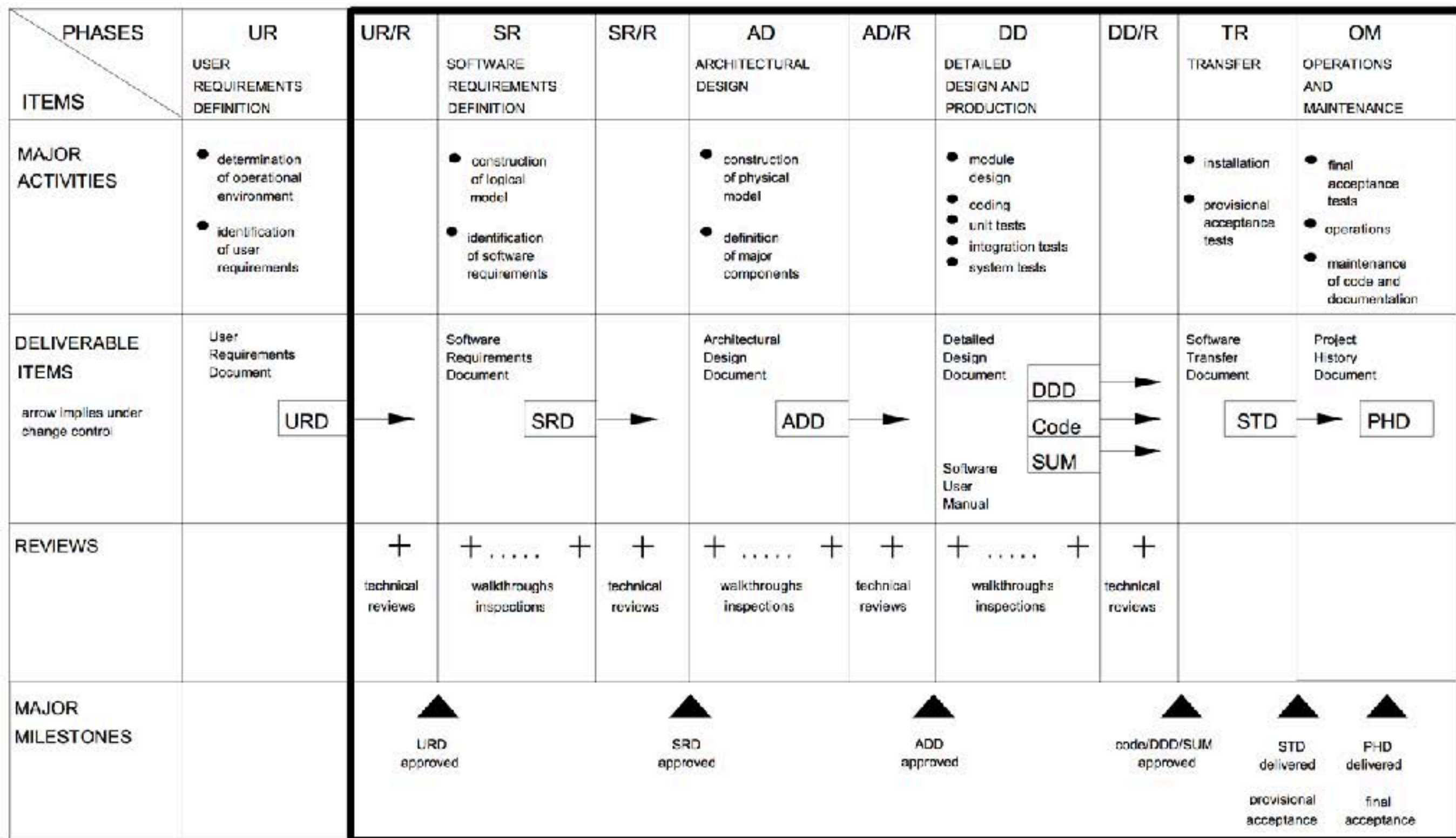
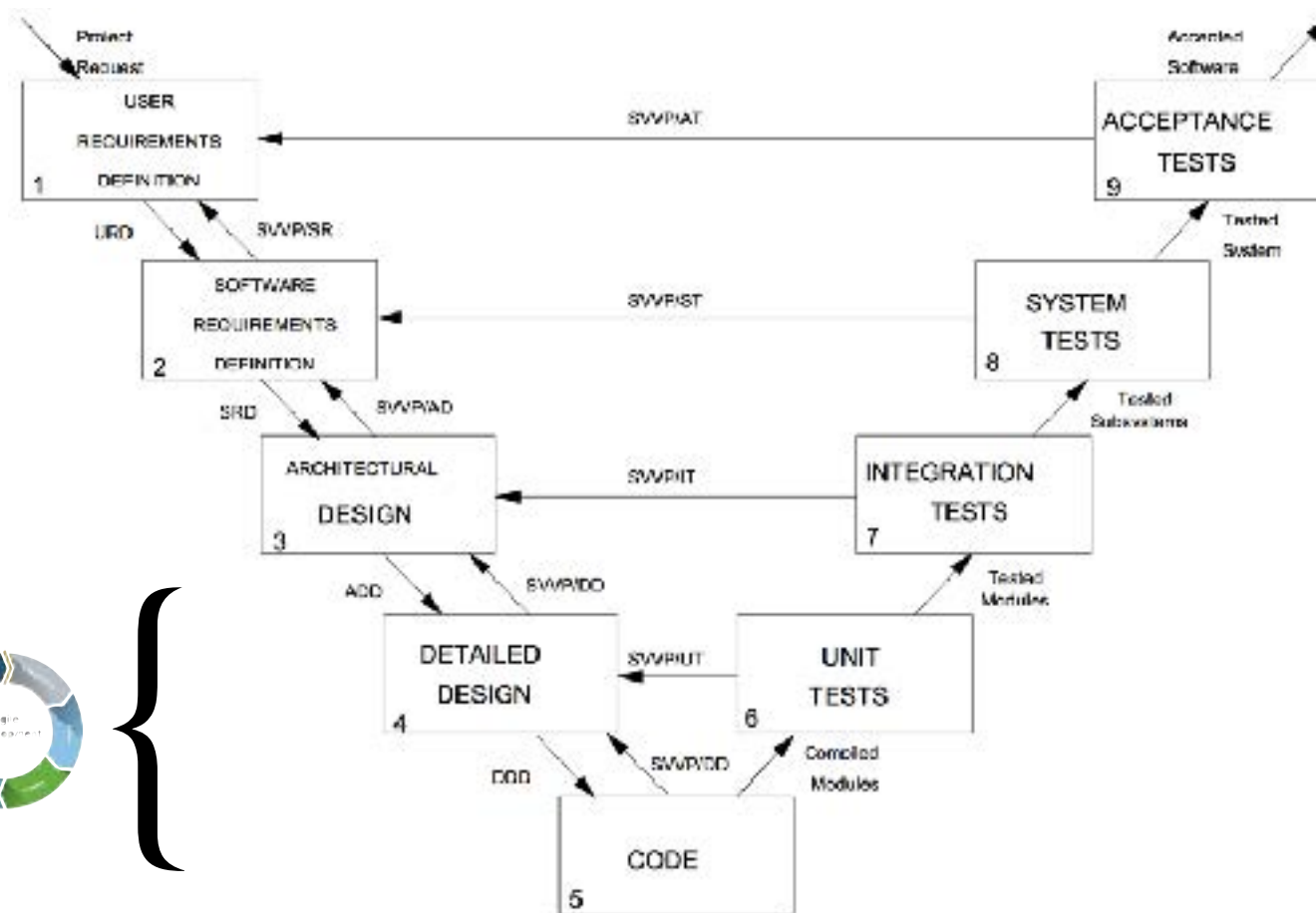
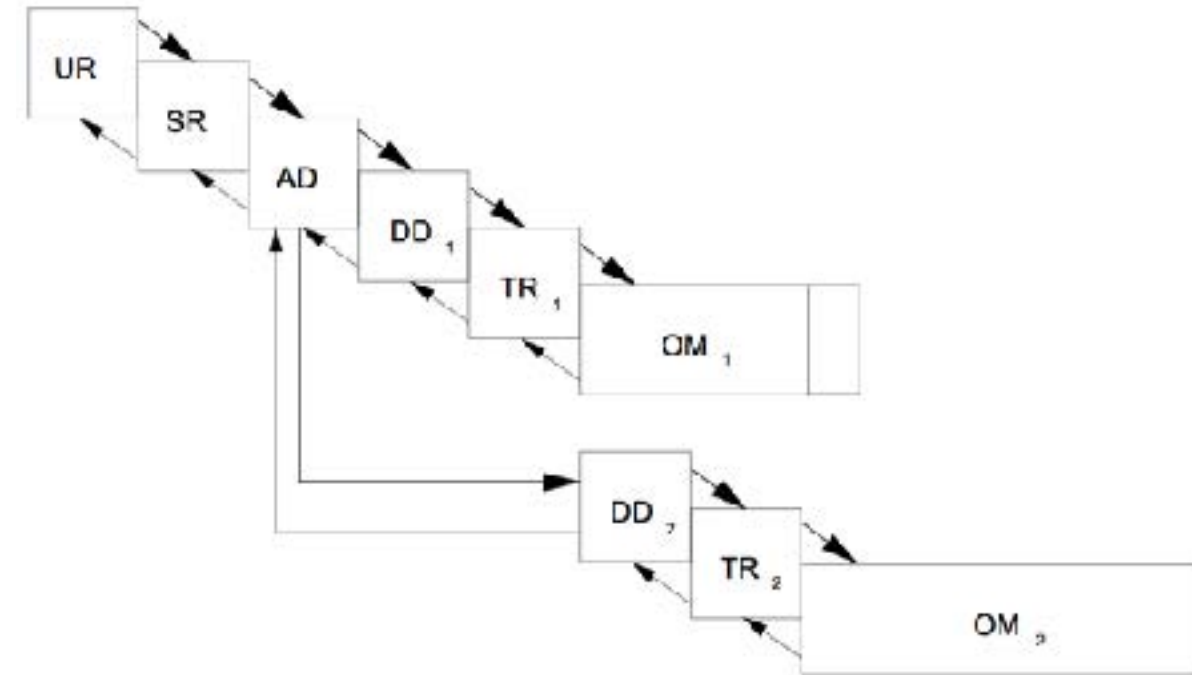


Figure 1.2: The Software Life Cycle Model

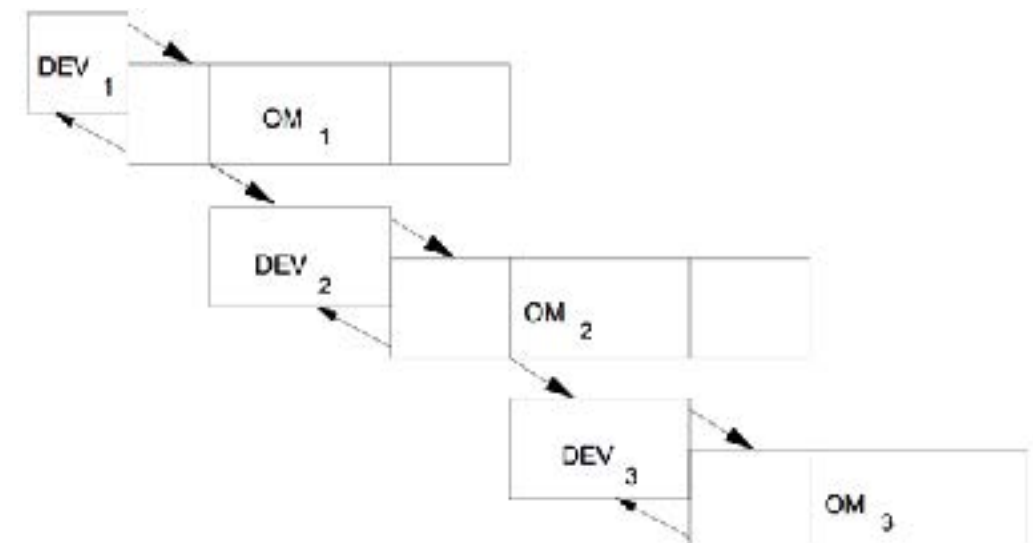
Software Life Cycle



Waterfall or V model

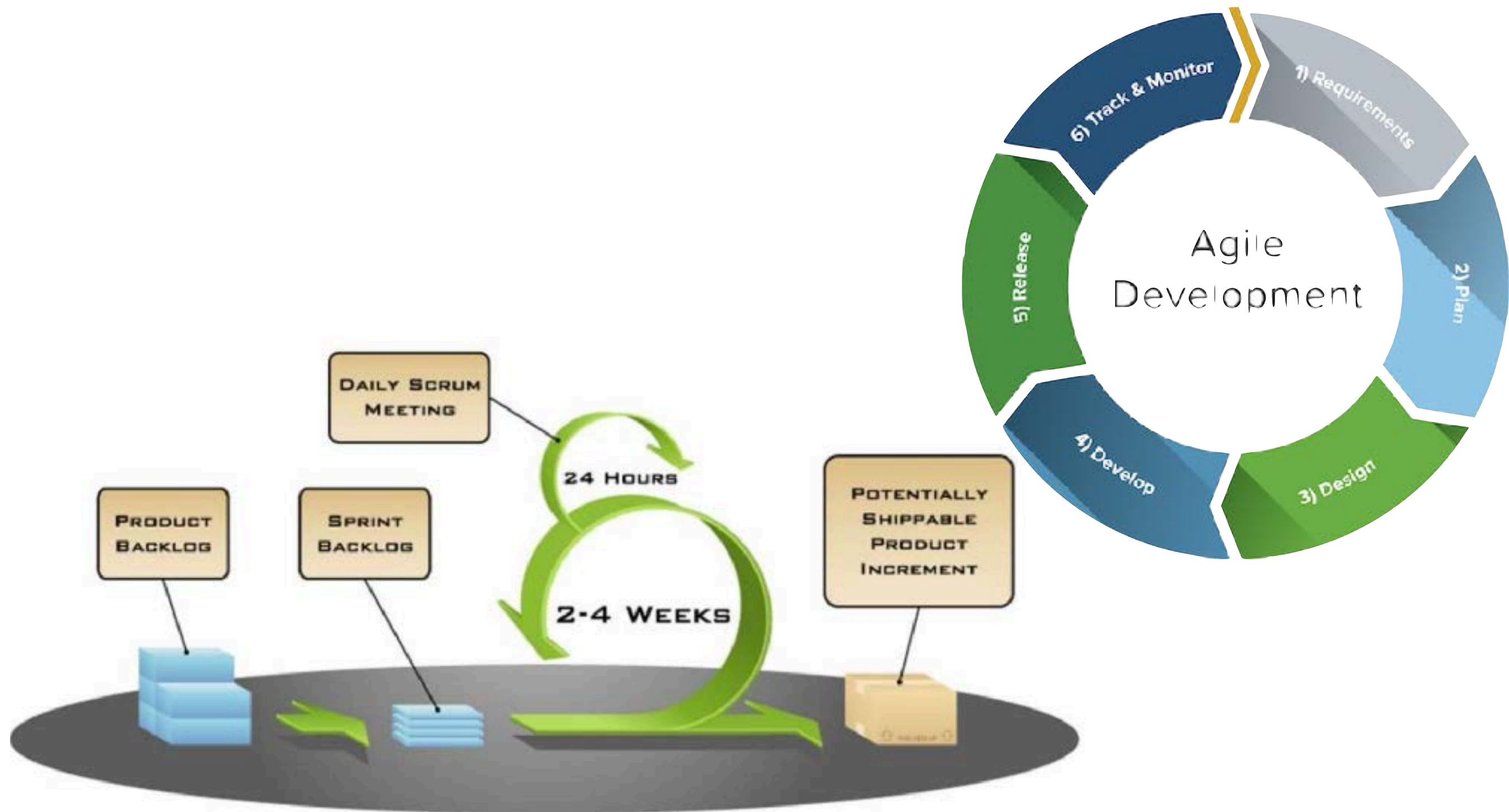


Incremental



Evolutionary or iterative

Software Life Cycle



Agile

when face-to-face interactions are easily established

User Requirement Phase

Problem definition phase:

- UR are the responsibility of the user
- UR should be verifiable
- High level but complete set of UR, keep only fundamentals
- Build a consensus among the users at requirement not implementation level
- Use cases are a way to collect user requirements
- Interfaces (ICD) are considered at user requirements level

Outputs:

- User Requirement Document
- Acceptance Test Plan
- Software Project Management Plan
- Configuration Management Plan
- Verification and Validation Plan
- Quality Assurance Plan

Software Requirement Phase

Problem analysis phase:

- SR are the responsibility of the developer
- SR should be verifiable and complete
- Functional, performance, interface, operational, resource, security, portability, safety requirements
- Build a consensus between users and developers
- Build a logical model (top-down decomposition)
- Interfaces (ICD) are considered at user requirements level

Outputs:

- Software Requirement Document
- System Test Plan
- Update of Software Project Management Plan (30% cost estimate)
- Update of Configuration Management Plan
- Update of Verification and Validation Plan
- Update of Quality Assurance Plan

Architectural Design Phase

Solution phase:

- AD is the responsibility of the developer
- AD should be verifiable and complete
- Build a physical model and control flow of the system
- Decomposition of the software into components (input, output, function) and data structures.
- Selection of languages, algorithms

Outputs:

- Architectural Design Document
- Integration Test Plan
- Update of Software Project Management Plan (10% cost estimate)
- Update of Configuration Management Plan
- Update of Verification and Validation Plan
- Update of Quality Assurance Plan

Detailed Design Phase

Implementation phase:

- DD is the responsibility of the software engineer
- DD phase is where Agile development is efficient
- Structured programming/pair programming
- Documentation to be produced concurrently
- Unit and integration testing

Outputs:

- Software
- Test data and procedures
- Code Documentation
- User Manual
- Acceptance Test Specification
- Update of Management Plans

Transfer & Operation and Maintenance Phases

Handover phase:

- TR is the responsibility of the software engineer
- Documentation to be produced concurrently
- Acceptance Tests

Outputs:

- Software Transfer Document (software installation)
- Acceptance test report

Practical use phase:

- Acceptance Tests

Outputs:

- Acceptance statement

Management Plans

Software Project Management:

- Project organisation
- Risk analysis
- Technical management
- Planning & budget
- Reporting

Software Configuration Management:

- Software item identification
- Version management (baseline, releases)
- Configuration management
- Change control

Software Verification & Validation:

- Reviews & audits
- Traceability
- Proof & Testing
- Change control

Software Quality Management:

- Management & communication
- Software documentation
- Reviews & audits
- Testing
- Reporting
- Code and media control
- Record collection, minutes
- Training
- Risk

End-to-End Tests

- Every possibility to participate to end-to-end tests should be used. They provides very good confidence that things are working. These tests are rarely complete.
- The schedule of end-to-end tests often vary (the data centre is not a priority at such times), so they are hard to plan
- Partial tests are also available:
with the MOC, using a spacecraft simulator
during payload calibration exercices
during LEOP and spacecraft commissioning

LEOP and Commissioning

- LEOP (Launch and early orbit phase) allows to finalise tests of spacecraft operation and routine data processing. Influence of radiation environment can be probed. Spacecraft performance need to be checked.
- Instrument commissioning mainly target to verify the proper functioning of the instruments. Start as early as possible. It is a very good way to detect and fix problems before the start of scientific operations.

(not so) Routine phase

- Specific instrument calibrations may need a lot of data or observation of sources not visible at launch. Calibration activities are never ending.
- The spacecraft orbit changes. Radiation and thermal environment as well. Misalignment can be an issue.
- Tests need to be repeated each time a new instrument mode is used, a parameter is modified, or a new on-board software is uploaded. This is heavy and should be minimised.
- Instrument and spacecraft may degrade, operations can be even more difficult close to the mission end. Keep expertise !

DATA IS THE LEGACY

DATA IS THE LEGACY

- **Data is the interface between the mission and the scientists**
- **Science is derived from the data**
- **Many science results are derived from the archive, not from individual observations and depend on the availability and usability of the data by the scientific community at large**
- **Scientific papers are still published with 30 years old data**
- **Questions evolve, data remains**

Be serious with the Data.... and use them !